

# Population Dynamics

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# Outline

Population distribution

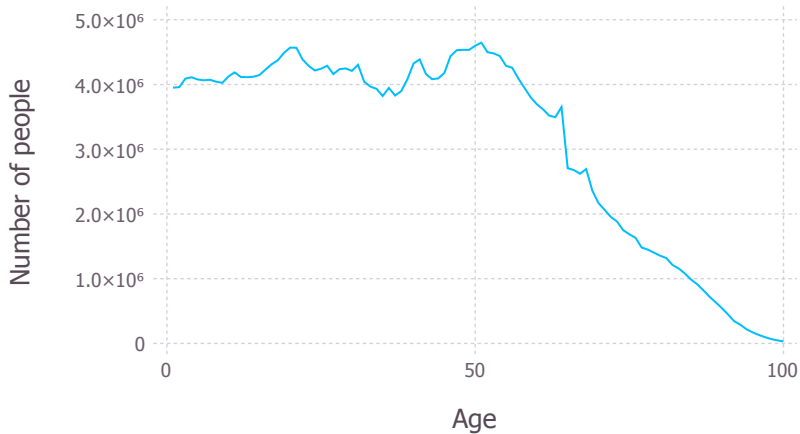
Dynamics

## Population distribution

- ▶  $x_t \in \mathbf{R}^{100}$  gives population distribution in year  $t = 1, \dots, T$
- ▶  $(x_t)_i$  is the number of people with age  $i - 1$  in year  $t$   
(say, on January 1)
- ▶ total population in year  $t$ :  $\mathbf{1}^T x_t$
- ▶ number of people age 70 or older in year  $t$ :  $(0_{70}, \mathbf{1}_{30})^T x_t$

# Population distribution of the U.S.

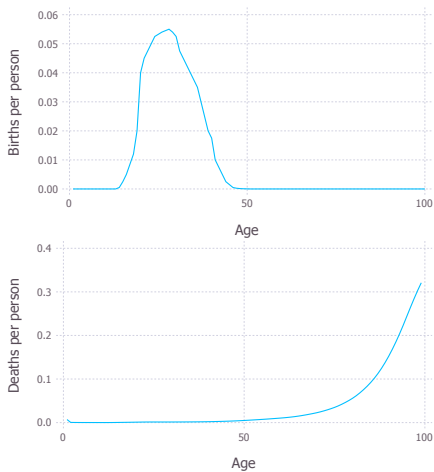
(from 2010 census)



## Birth and death rates

- ▶ birth rate  $b \in \mathbf{R}^{100}$ , death (or mortality) rate  $d \in \mathbf{R}^{100}$
- ▶  $b_i$  is the number of births per person with age  $i - 1$
- ▶  $d_i$  is the portion of those aged  $i - 1$  who will die this year (we'll take  $d_{100} = 1$ )
- ▶  $b$  and  $d$  can vary with time, but we'll assume they are constant

## Birth and death rates in the U.S.



# Outline

Population distribution

Dynamics

## Dynamics

- ▶ let's find next year's population distribution  $x_{t+1}$  (ignoring immigration; we'll add that later)
- ▶ number of 0-year-olds next year is total births this year:

$$(x_{t+1})_1 = b^T x_t$$

- ▶ number of  $i$ -year-olds next year is number of  $(i - 1)$ -year-olds this year, minus those who die:

$$(x_{t+1})_{i+1} = (1 - d_i)(x_t)_i, \quad i = 1, \dots, 99$$

- ▶  $x_{t+1} = Ax_t$ , where

$$A = \begin{bmatrix} b_1 & b_2 & \cdots & b_{99} & b_{100} \\ 1 - d_1 & & & \cdots & 0 \\ 0 & 1 - d_2 & & \cdots & 0 \\ \vdots & & \ddots & & \vdots \\ 0 & \cdots & & 1 - d_{99} & 0 \end{bmatrix}$$

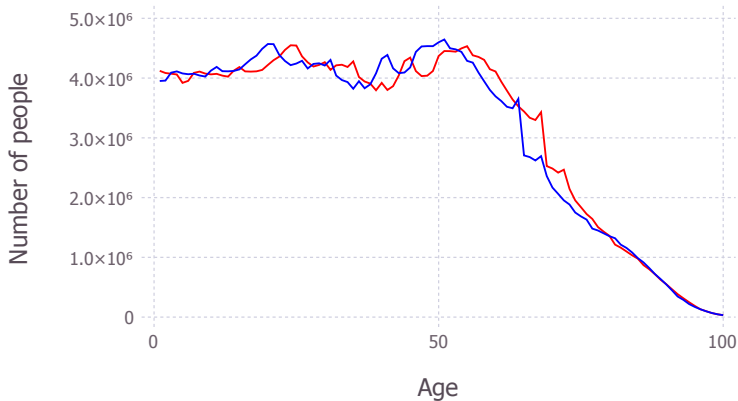


# Dynamics

- ▶ to predict distribution  $s$  years in the future:  $x_{t+s} = A^s x_t$
- ▶  $A^s$  propagates current population distribution  $s$  years forward
- ▶ to predict total population  $s$  years in future:  $\mathbf{1}^T x_{t+s} = \mathbf{1}^T A^s x_t$
- ▶ what do the entries of the row vector  $\mathbf{1}^T A^{10}$  mean?

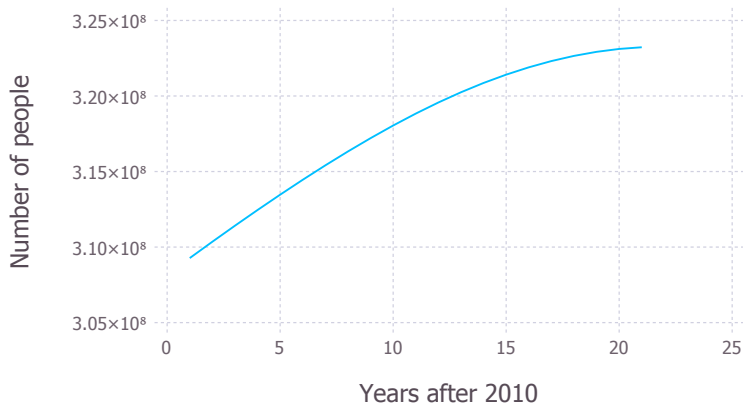
## Predicting future population distributions

predicting U.S. 2015 distribution from 2010 (ignoring immigration)



## Predicting population growth

predicted population growth (ignoring immigration)



## Initial population distributions

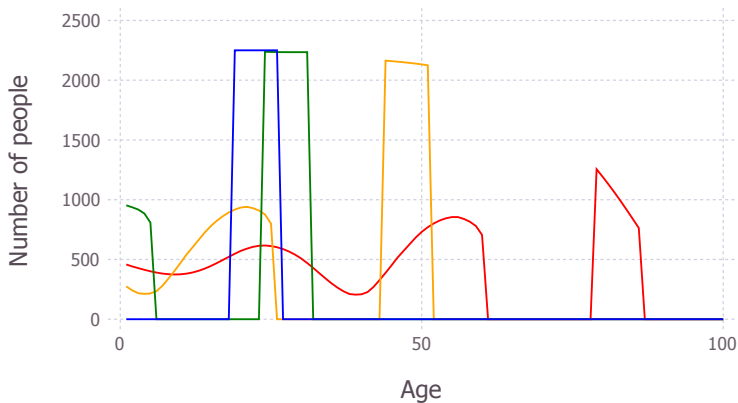
- ▶ what if we changed  $x_0$ ?
- ▶ instead of U.S. Census data, let's use a “college nation”

$$(x_0)_i = \begin{cases} 2200 & i = 19, 20, \dots, 27 \\ 0 & \text{otherwise} \end{cases}$$

(approximate population distribution of Stanford students)

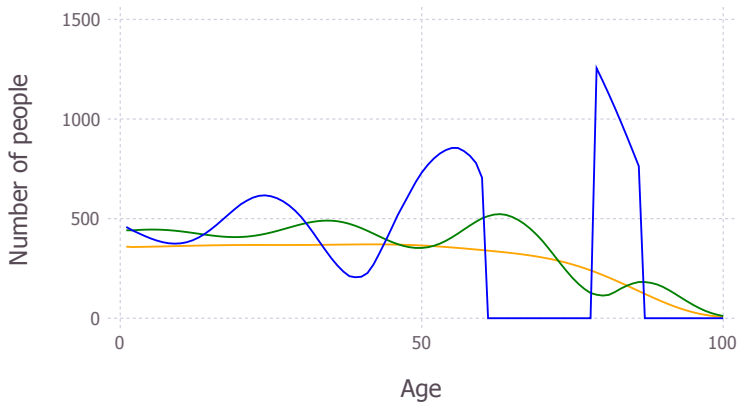
# Predicting future population distributions

predict  $s$  years into the future

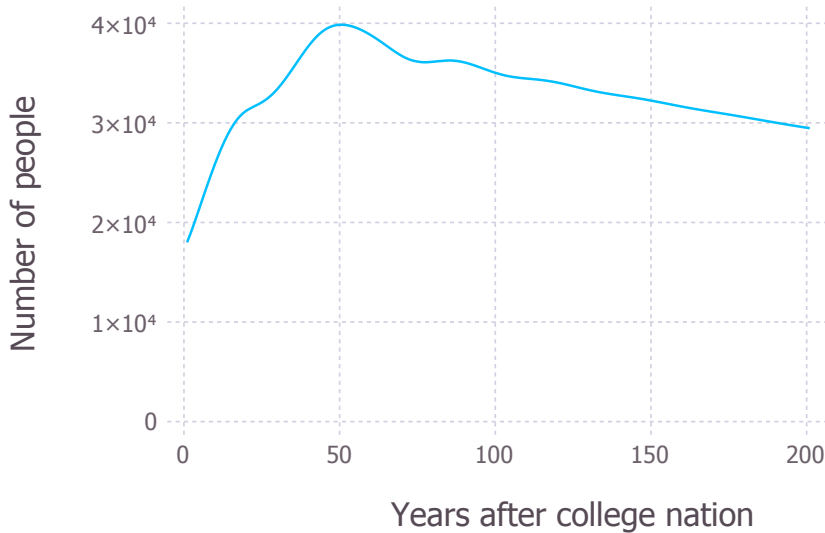


## Predicting future population distributions

predict a little farther into the future



## Population growth



# Immigration

- ▶  $u \in \mathbf{R}^{100}$  is immigration:  $u_i$  is the net immigration of  $(i - 1)$ -year-olds
- ▶ dynamics with immigration:  $x_{t+1} = Ax_t + u$
- ▶ to propagate distribution forward  $s$  years:

$$x_{t+1} = Ax_t + u$$

$$x_{t+2} = A(Ax_t + u) + u = A^2x_t + Au + u$$

$$\vdots$$

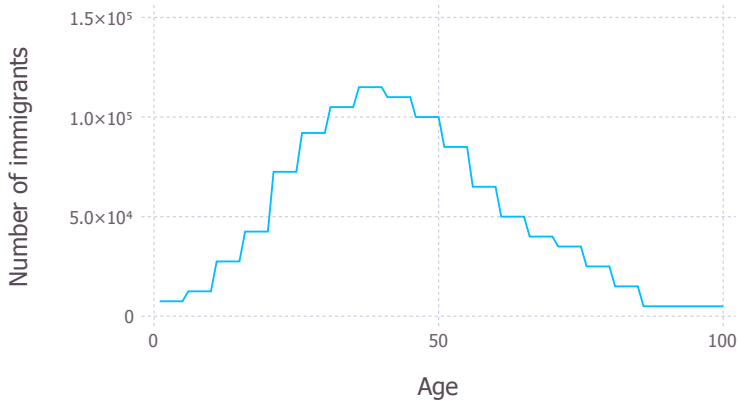
$$x_{t+s} = A^s x_t + A^{s-1}u + \cdots + Au + u$$

- ▶  $(A^{s-1} + \cdots + A + I)u$  is population distribution at  $t + s$  due to immigration over years  $t, \dots, s - 1$



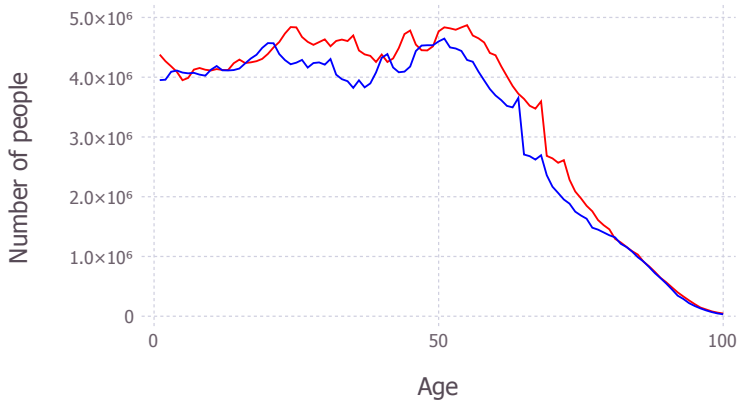
# Immigration into the U.S.

piecewise constant approximation



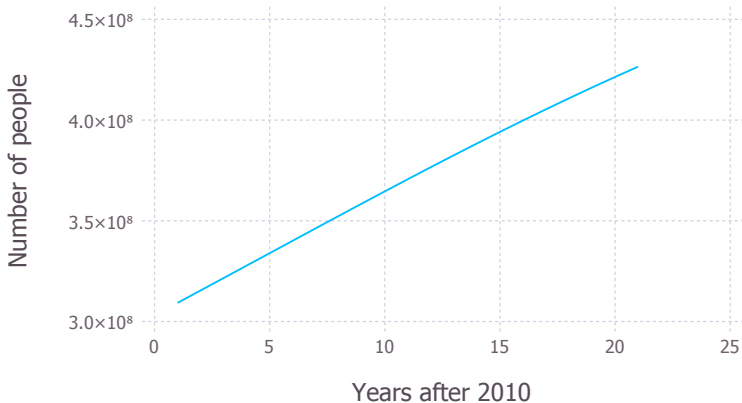
## Predicting future population distributions

predicting U.S. 2015 distribution from 2010



## Population growth with immigration

- ▶ we can plot  $\mathbf{1}^T x_t$  for  $t = 1, \dots, 1000$  with immigration



## Inferring immigration

- ▶ given  $x_1$ ,  $x_T$ ,  $b$ , and  $d$ , infer (constant) immigration vector  $u$
- ▶ we have  $x_T = A^{T-1}x_1 + A^{T-2}u + \dots + u$  and so

$$(A^{T-1} + \dots + A + I)u = x_T - A^{T-1}x_1$$

(what does righthand side mean?)

- ▶ so immigration is

$$u = (A^{T-2} + \dots + A + I)^{-1}(x_T - A^{T-1}x_1)$$