

# Mobile Image Processing

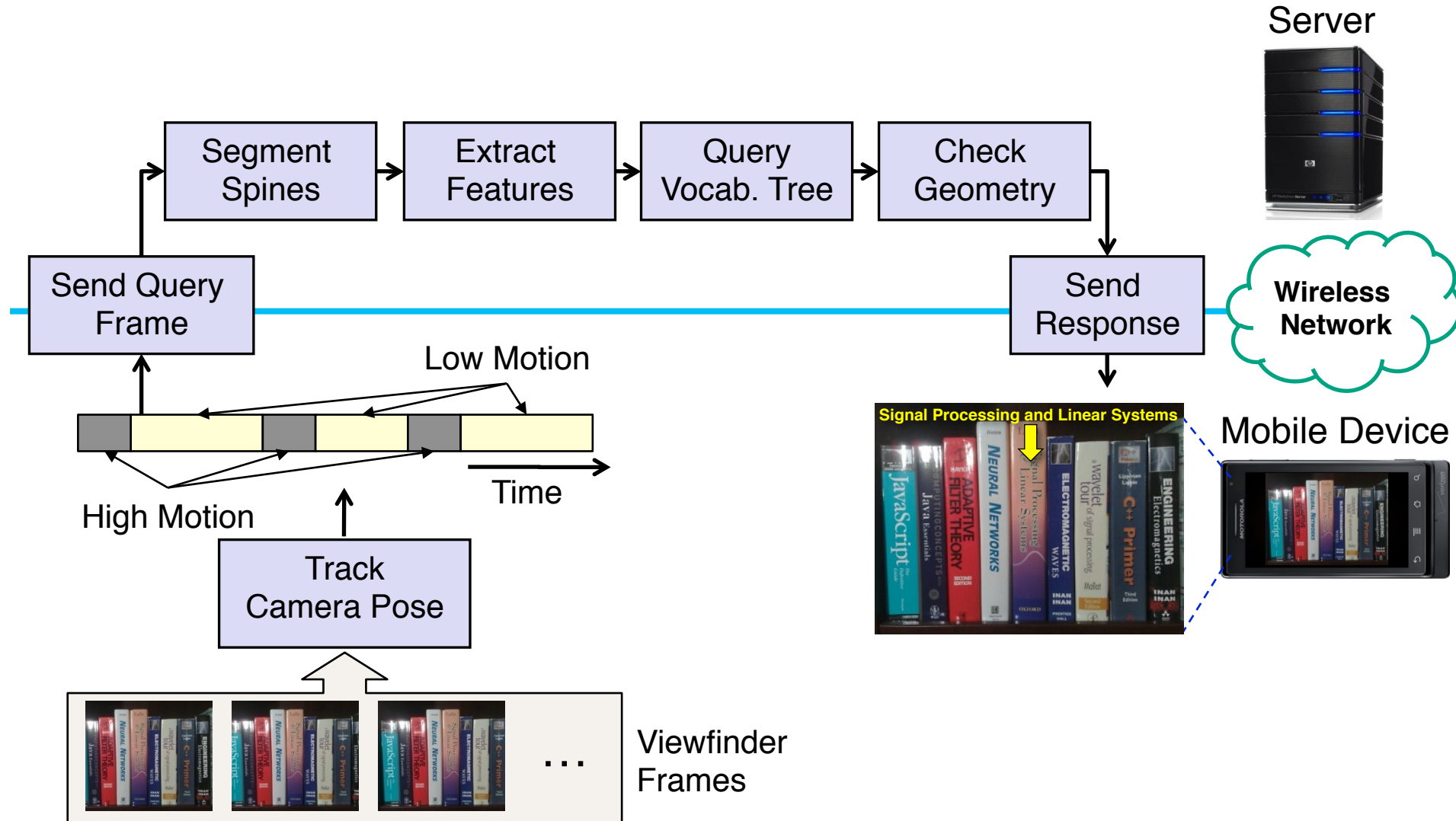
- Part 1: Introduction to mobile image processing on Android
- Part 2: Real-time augmentation of viewfinder frames
- Part 3: Utilizing optimized functions in the OpenCV library



# Mobile book spine recognition



# Mobile book spine recognition

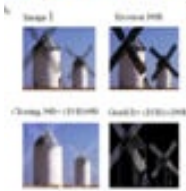


# Tracking local feature keypoints

???

# OpenCV: Open Source Computer Vision

General Image Processing Functions



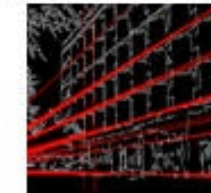
Segmentation



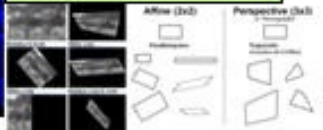
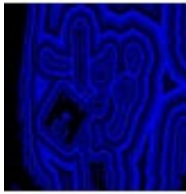
Geometric descriptors



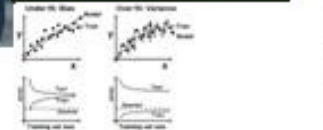
Features



Transforms



Machine Learning:  
• Detection,  
• Recognition



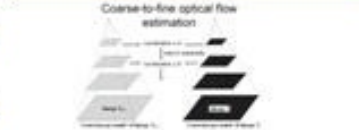
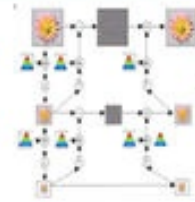
Tracking



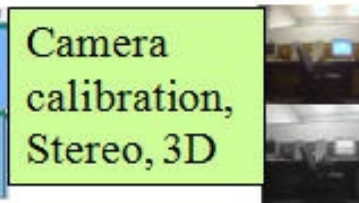
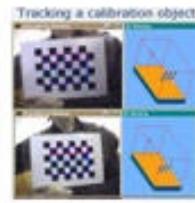
Matrix Math



Image Pyramids



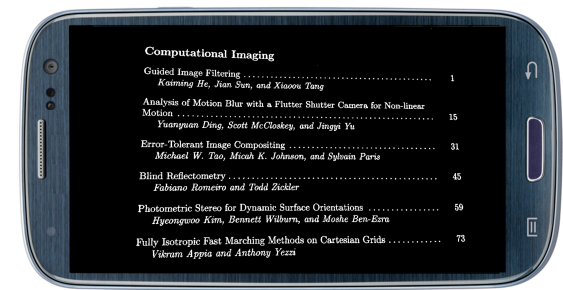
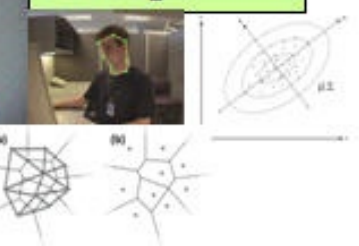
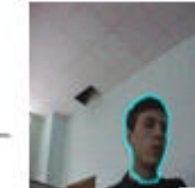
Camera calibration, Stereo, 3D



Utilities and Data Structures



Fitting



<http://docs.opencv.org>

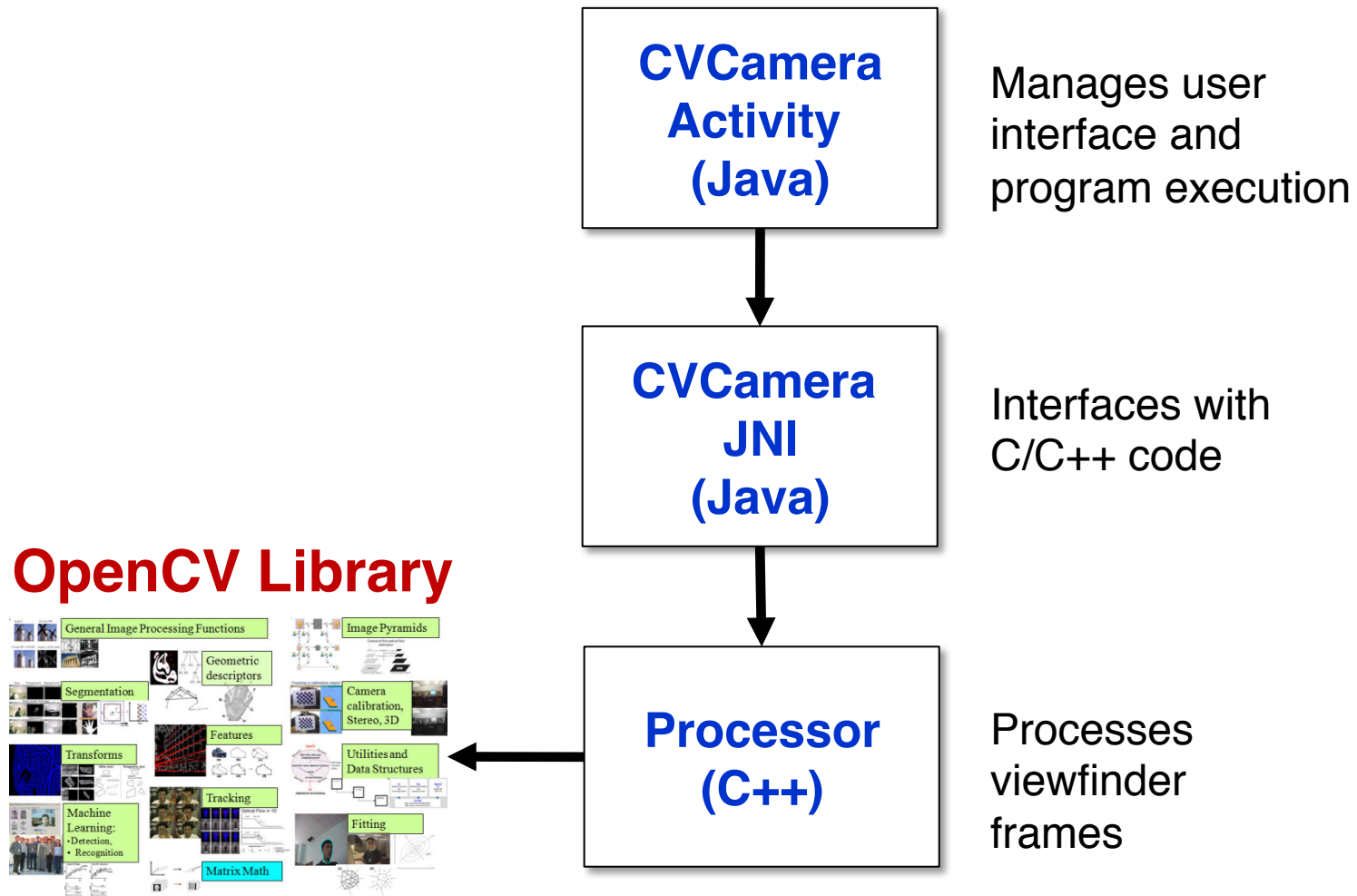
# OpenCV for Android

- Port of OpenCV to Android framework
  - Over 2K optimized algorithms written in C/C++
  - Compiled with STL-enabled Android NDK
  - Enables popular CV functions to be used on mobile images/videos
- Differences from regular Android programming
  - Requires writing C/C++ code
  - Requires writing Java Native Interface (JNI) wrappers
  - Requires using Android NDK in addition to Android SDK
- Our tutorial #2 helps to make the transition
  - How to set up OpenCV programming environment
  - How to write Android apps that call OpenCV functions
  - How to integrate NDK compilation into Eclipse IDE

# “CVCamera” project

- Goals of this project
  - Learn how to incorporate C/C++ code into an Android program
  - Learn how to utilize OpenCV library functions
  - Learn how to draw feature keypoints on viewfinder frames
- Step-by-step instructions available in Tutorial #2:
  - <http://ee368.stanford.edu/Android>

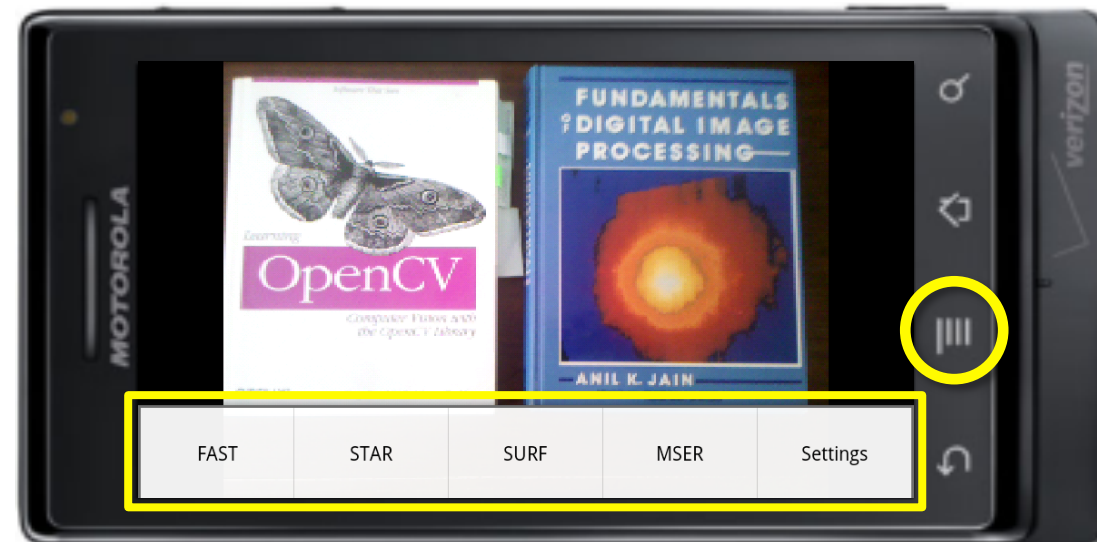
# “CVCamera” class hierarchy



# CVCamera class: menu options

```
public boolean onCreateOptionsMenu(Menu menu) {  
    menu.add("FAST");  
    menu.add("STAR");  
    menu.add("SURF");  
    menu.add("MSER");  
    menu.add("Settings");  
    return true;  
}
```

Java Code



# CVCamera class: calling feature extractors

```
public boolean onOptionsItemSelected(MenuItem item) {
    LinkedList<PoolCallback> defaultCallbackStack =
        new LinkedList<PoolCallback>();
    defaultCallbackStack.addFirst(myGLView.getDrawCallback());

    if (item.getTitle().equals("FAST")) {
        defaultCallbackStack.addFirst(new FastProcessor());
    }
    else if (item.getTitle().equals("STAR")) {
        defaultCallbackStack.addFirst(new STARProcessor());
    }
    else if (item.getTitle().equals("SURF")) {
        defaultCallbackStack.addFirst(new SURFProcessor());
    }
    else if (item.getTitle().equals("MSER")) {
        defaultCallbackStack.addFirst(new MSERProcessor());
    }

    myPreview.addCallbackStack(defaultCallbackStack);
    return true;
}
```

Java Code

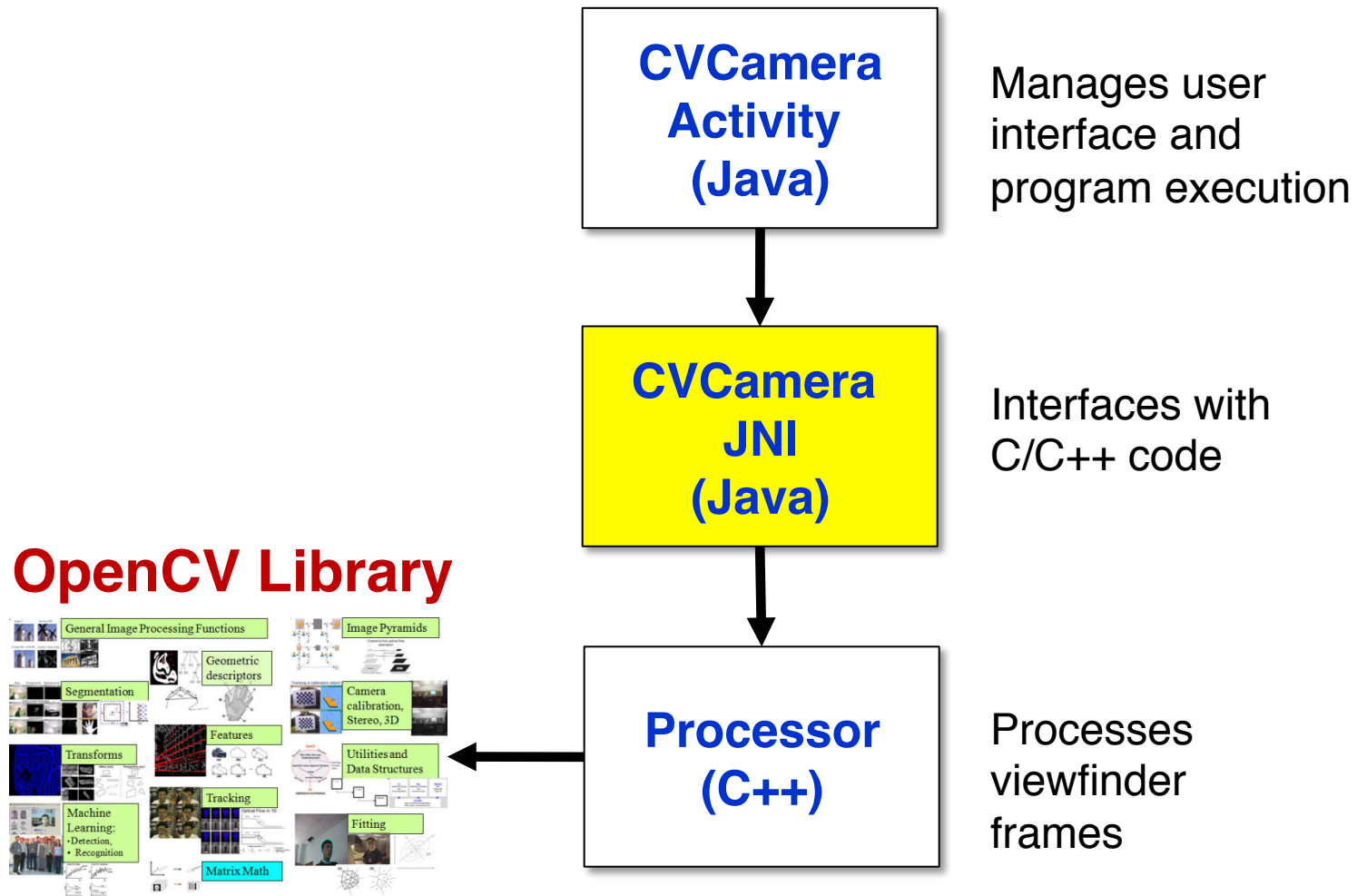
Populate a stack of  
callback functions

First callback function  
draws the frames

Other callback functions  
call feature extractors

???

# “CVCamera” class hierarchy



# JNI class: interface to C/C++ code

```
static {
    try {
        System.loadLibrary("android-opencv");
        System.loadLibrary("cvcamera");
    } catch (UnsatisfiedLinkError e) {
        throw e;
    }
}

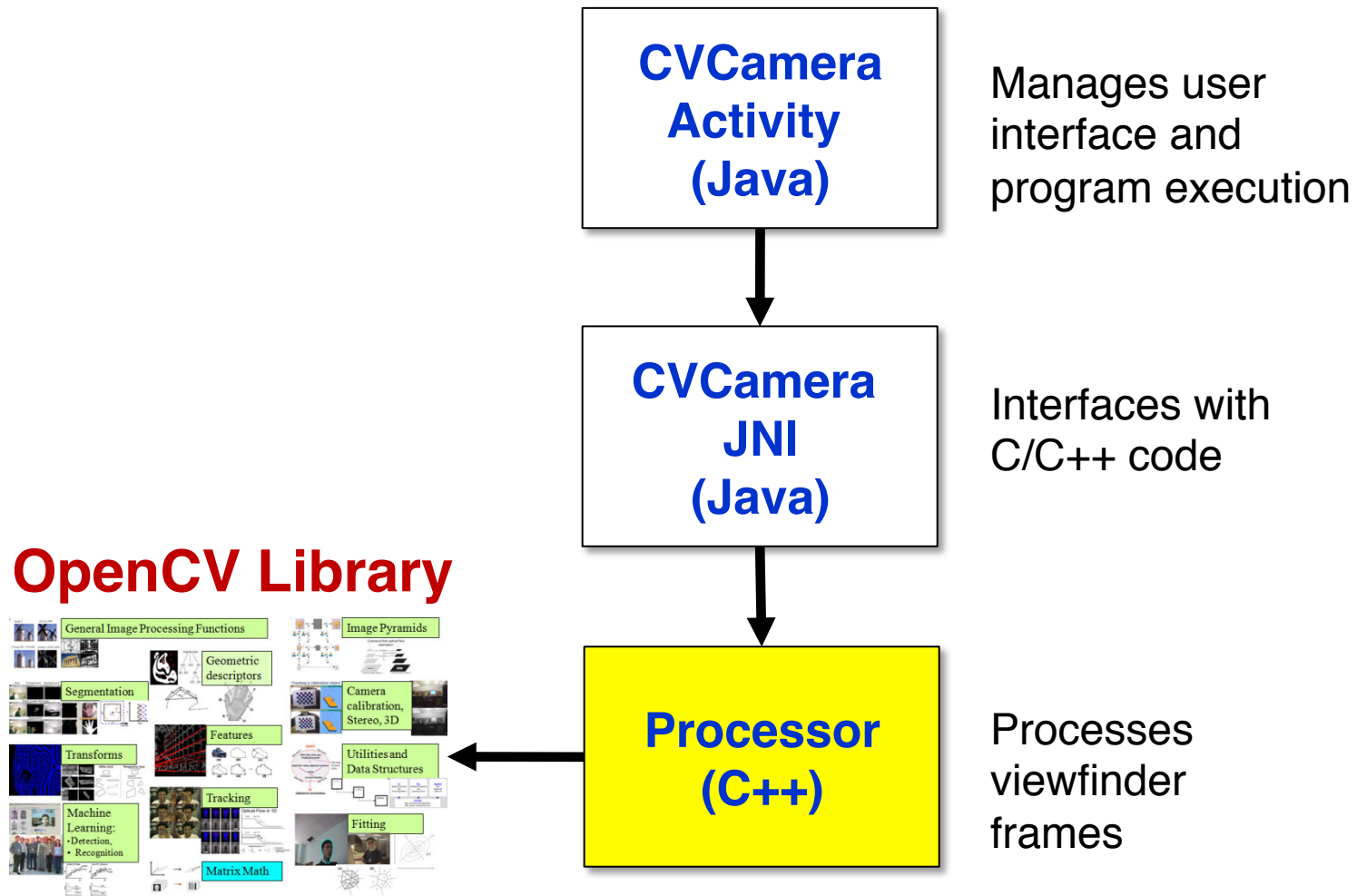
public final static native int DETECT_FAST_get();
public final static native int DETECT_STAR_get();
public final static native int DETECT_SURF_get();
public final static native int DETECT_MSER_get();
public final static native long new_Processor();
public final static native void delete_Processor(long jarg1);
```

Java Code

Load libraries built by the  
Android NDK

Function prototypes for  
interface to C/C++ side

# “CVCamera” class hierarchy



# Processor class: initialize feature detectors

```
class Processor {  
private:  
    cv::StarFeatureDetector my_stard;  
    cv::FastFeatureDetector my_fastd;  
    cv::SurfFeatureDetector my_surfd;  
    cv::MserFeatureDetector my_mserd;  
    std::vector<cv::KeyPoint> my_keypoints;  
  
public:  
    Processor():  
        my_stard(STAR detector parameters),  
        my_fastd(FAST detector parameters),  
        my_surfd(SURF detector parameters),  
        my_mserd(MSER detector parameters)  
        {}  
    void detectAndDrawFeatures  
        (int idx, image_pool* pool, int feature_type);  
};
```

C++ Code

Different feature extractors  
stored as members

Initialize extractors in the  
class instantiation list

# Processor class: detect and draw feature keypoints

```
// Detect feature keypoints
Mat grey_im = pool->getGrey(idx);
Mat color_im = pool->getImage(idx);
my_keypoints.clear();
my_mserd->detect(grey_im, my_keypoints);

// Draw feature keypoints
vector<KeyPoint>::const_iterator it;
for (it = my_keypoints.begin();
     it != my_keypoints.end(); ++it) {

    // Draw black circle
    Point2f pt = it->pt;
    circle(color_im, pt, it->size,
           cvScalar(0,0,0,0), 2);

    // Draw yellow circle
    pt.x += 1; pt.y += 1;
    circle(color_im, pt, it->size,
           cvScalar(255,255,0,0), 2);
} // iterator
```

C++ Code

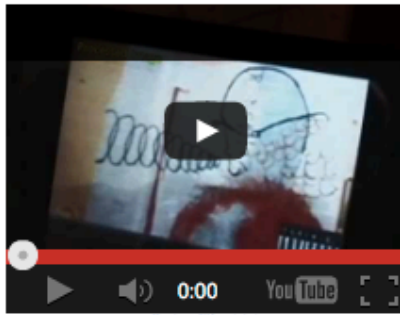


# Local feature keypoints extraction

???

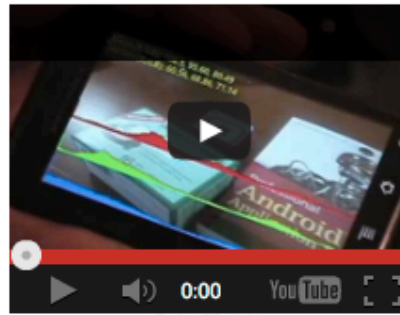
# Other examples on class website

Histogram Equalization



[Project Files \(zip\)](#)

Color Histograms



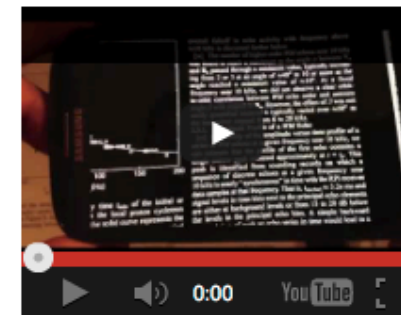
[Project Files \(zip\)](#)

Feature Tracking



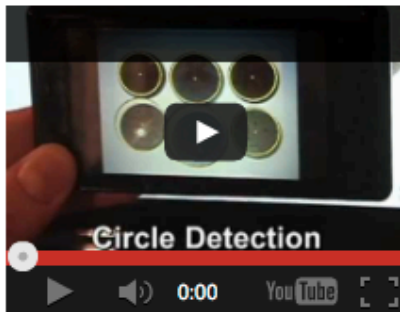
[Project Files \(zip\)](#)

Locally Adaptive Binarization



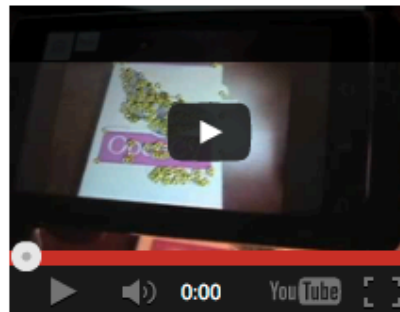
[Project Files \(zip\)](#)

Edges, Lines, and Circles



[Project Files \(zip\)](#)

Local Feature Keypoints



[Project Files \(zip\)](#)

Human Face Detection



[Project Files \(zip\)](#)

<http://ee368.stanford.edu/Android>

# Detecting edges, lines, and circles

# Detecting edges, lines, and circles

```
// Extract Canny edges
```

```
C++: Canny(  
    InputArray image, OutputArray edges, double threshold1, double threshold2  
);
```

```
// Extract lines using Hough transform
```

```
C++: HoughLines(  
    InputArray image, OutputArray lines, double rho, double theta, int thresh  
);
```

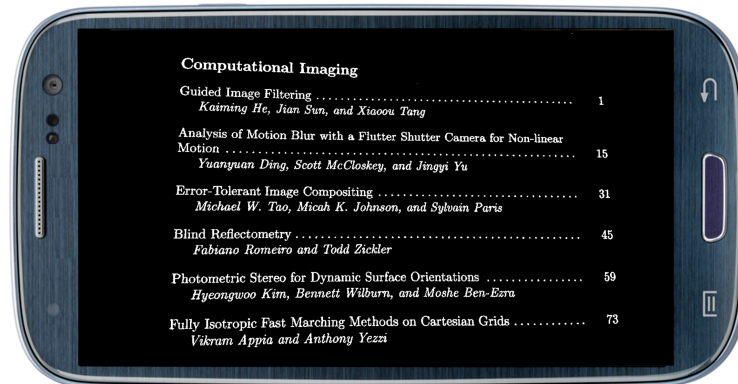
```
// Extract circles using Hough transform
```

```
C++: HoughCircles(  
    InputArray image, OutputArray circles, int method, double accumRatio, double minDist  
);
```

# Locally adaptive binarization

# Locally adaptive binarization

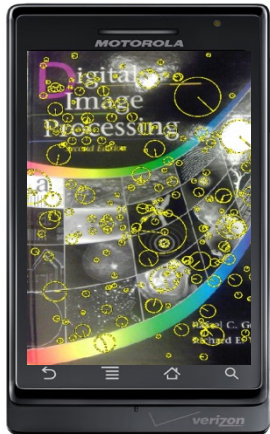
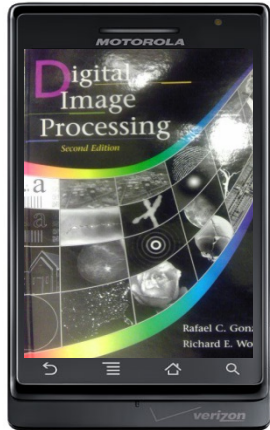
```
// Perform locally adaptive thresholding
C++: adaptiveThreshold(
    InputArray src, OutputArray dst, double maxValue, int adaptiveMethod,
    int thresholdType, int blockSize, double valOffset
);
```



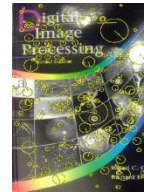
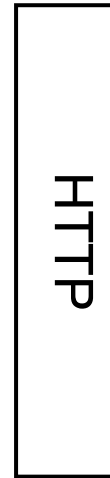
???

# Server-client communications

1. Client takes an input image

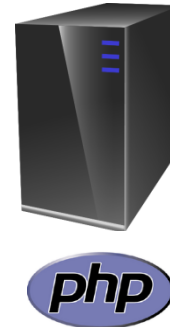


2. Send an image to server



5. Client receives the processed result

3. A PHP server invokes application



4. Server-side application processes the image

# Server-client communications

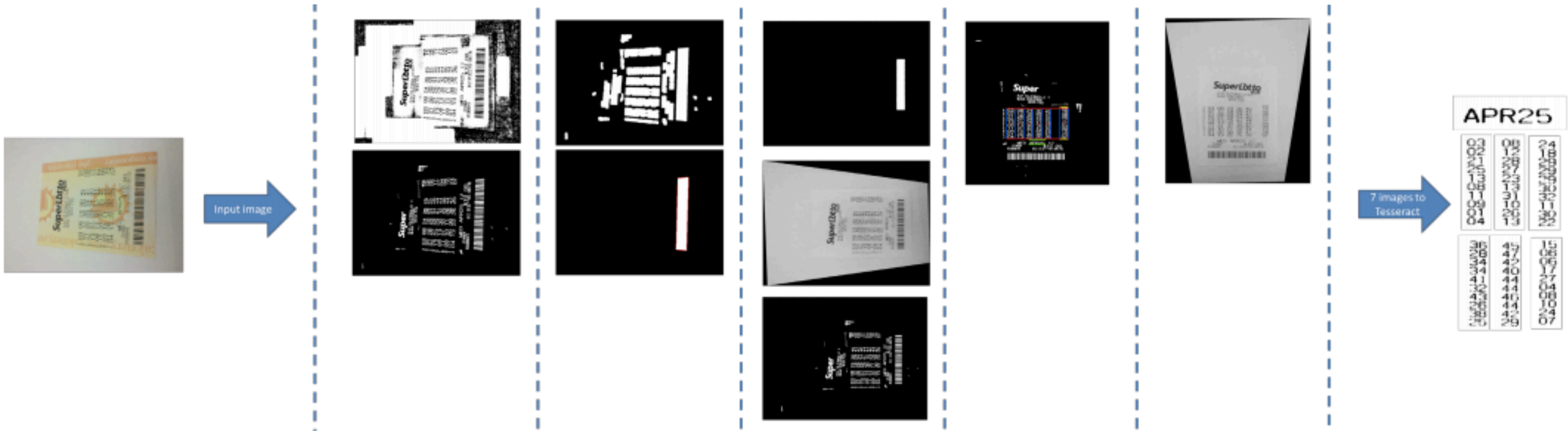
- Covers every aspect of server-client interactions
  - How to upload an image from the phone to a server
  - How to invoke applications on the server after the image is received
  - How to download the result onto the phone from the server
- Available as Tutorial #3 on class website:
  - <http://ee368.stanford.edu/Android>

# Class project: Previewing interior décor changes



M. Le, A. Zarraga, K. Zhu, Spring 2011  
[http://ee368.stanford.edu/Project\\_11](http://ee368.stanford.edu/Project_11)

# Class project: Mobile lottery ticket checker



T. Zou and A. Gupta, Spring 2012  
[http://ee368.stanford.edu/Project\\_12](http://ee368.stanford.edu/Project_12)

???