

Stochastic Subgradient Method

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Noisy unbiased subgradient

- random vector $\tilde{g} \in \mathbf{R}^n$ is a **noisy unbiased subgradient** for $f : \mathbf{R}^n \rightarrow \mathbf{R}$ at x if for all z

$$f(z) \geq f(x) + (\mathbf{E} \tilde{g})^T (z - x)$$

i.e., $g = \mathbf{E} \tilde{g} \in \partial f(x)$

- same as $\tilde{g} = g + v$, where $g \in \partial f(x)$, $\mathbf{E} v = 0$
- v can represent error in computing g , measurement noise, Monte Carlo sampling error, etc.

- if x is also random, \tilde{g} is a noisy unbiased subgradient of f at x if

$$\forall z \quad f(z) \geq f(x) + \mathbf{E}(\tilde{g}|x)^T (z - x)$$

holds almost surely

- same as $\mathbf{E}(\tilde{g}|x) \in \partial f(x)$ (a.s.)

Stochastic subgradient method

stochastic subgradient method is the subgradient method, using noisy unbiased subgradients

$$x^{(k+1)} = x^{(k)} - \alpha_k \tilde{g}^{(k)}$$

- $x^{(k)}$ is k th iterate
- $\tilde{g}^{(k)}$ is any noisy unbiased subgradient of (convex) f at $x^{(k)}$, *i.e.*,

$$\mathbf{E}(\tilde{g}^{(k)} | x^{(k)}) = g^{(k)} \in \partial f(x^{(k)})$$

- $\alpha_k > 0$ is the k th step size
- define $f_{\text{best}}^{(k)} = \min\{f(x^{(1)}), \dots, f(x^{(k)})\}$

Assumptions

- $f^* = \inf_x f(x) > -\infty$, with $f(x^*) = f^*$
- $\mathbf{E} \|g^{(k)}\|_2^2 \leq G^2$ for all k
- $\mathbf{E} \|x^{(1)} - x^*\|_2^2 \leq R^2$ (can take = here)
- step sizes are square-summable but not summable

$$\alpha_k \geq 0, \quad \sum_{k=1}^{\infty} \alpha_k^2 = \|\alpha\|_2^2 < \infty, \quad \sum_{k=1}^{\infty} \alpha_k = \infty$$

these assumptions are stronger than needed, just to simplify proofs

Convergence results

- convergence in expectation:

$$\lim_{k \rightarrow \infty} \mathbf{E} f_{\text{best}}^{(k)} = f^*$$

- convergence in probability: for any $\epsilon > 0$,

$$\lim_{k \rightarrow \infty} \mathbf{Prob}(f_{\text{best}}^{(k)} \geq f^* + \epsilon) = 0$$

- almost sure convergence:

$$\lim_{k \rightarrow \infty} f_{\text{best}}^{(k)} = f^*$$

a.s. (we won't show this)

Convergence proof

key quantity: *expected Euclidean distance squared to the optimal set*

$$\begin{aligned}\mathbf{E} \left(\|x^{(k+1)} - x^\star\|_2^2 \mid x^{(k)} \right) &= \mathbf{E} \left(\|x^{(k)} - \alpha_k \tilde{g}^{(k)} - x^\star\|_2^2 \mid x^{(k)} \right) \\ &= \|x^{(k)} - x^\star\|_2^2 - 2\alpha_k \mathbf{E} \left(\tilde{g}^{(k)T} (x^{(k)} - x^\star) \mid x^{(k)} \right) + \alpha_k^2 \mathbf{E} \left(\|\tilde{g}^{(k)}\|_2^2 \mid x^{(k)} \right) \\ &= \|x^{(k)} - x^\star\|_2^2 - 2\alpha_k \mathbf{E}(\tilde{g}^{(k)} \mid x^{(k)})^T (x^{(k)} - x^\star) + \alpha_k^2 \mathbf{E} \left(\|\tilde{g}^{(k)}\|_2^2 \mid x^{(k)} \right) \\ &\leq \|x^{(k)} - x^\star\|_2^2 - 2\alpha_k (f(x^{(k)}) - f^\star) + \alpha_k^2 \mathbf{E} \left(\|\tilde{g}^{(k)}\|_2^2 \mid x^{(k)} \right)\end{aligned}$$

using $\mathbf{E}(\tilde{g}^{(k)} \mid x^{(k)}) \in \partial f(x^{(k)})$

now take expectation:

$$\mathbf{E} \|x^{(k+1)} - x^*\|_2^2 \leq \mathbf{E} \|x^{(k)} - x^*\|_2^2 - 2\alpha_k(\mathbf{E} f(x^{(k)}) - f^*) + \alpha_k^2 \mathbf{E} \|\tilde{g}^{(k)}\|_2^2$$

apply recursively, and use $\mathbf{E} \|\tilde{g}^{(k)}\|_2^2 \leq G^2$ to get

$$\mathbf{E} \|x^{(k+1)} - x^*\|_2^2 \leq \mathbf{E} \|x^{(1)} - x^*\|_2^2 - 2 \sum_{i=1}^k \alpha_i (\mathbf{E} f(x^{(i)}) - f^*) + G^2 \sum_{i=1}^k \alpha_i^2$$

and so

$$\min_{i=1, \dots, k} (\mathbf{E} f(x^{(i)}) - f^*) \leq \frac{R^2 + G^2 \|\alpha\|_2^2}{2 \sum_{i=1}^k \alpha_i}$$

- we conclude $\min_{i=1,\dots,k} \mathbf{E} f(x^{(i)}) \rightarrow f^*$
- Jensen's inequality and concavity of minimum yields

$$\mathbf{E} f_{\text{best}}^{(k)} = \mathbf{E} \min_{i=1,\dots,k} f(x^{(i)}) \leq \min_{i=1,\dots,k} \mathbf{E} f(x^{(i)})$$

so $\mathbf{E} f_{\text{best}}^{(k)} \rightarrow f^*$ (convergence in expectation)

- Markov's inequality: for $\epsilon > 0$

$$\mathbf{Prob}(f_{\text{best}}^{(k)} - f^* \geq \epsilon) \leq \frac{\mathbf{E}(f_{\text{best}}^{(k)} - f^*)}{\epsilon}$$

righthand side goes to zero, so we get convergence in probability

Example

piecewise linear minimization

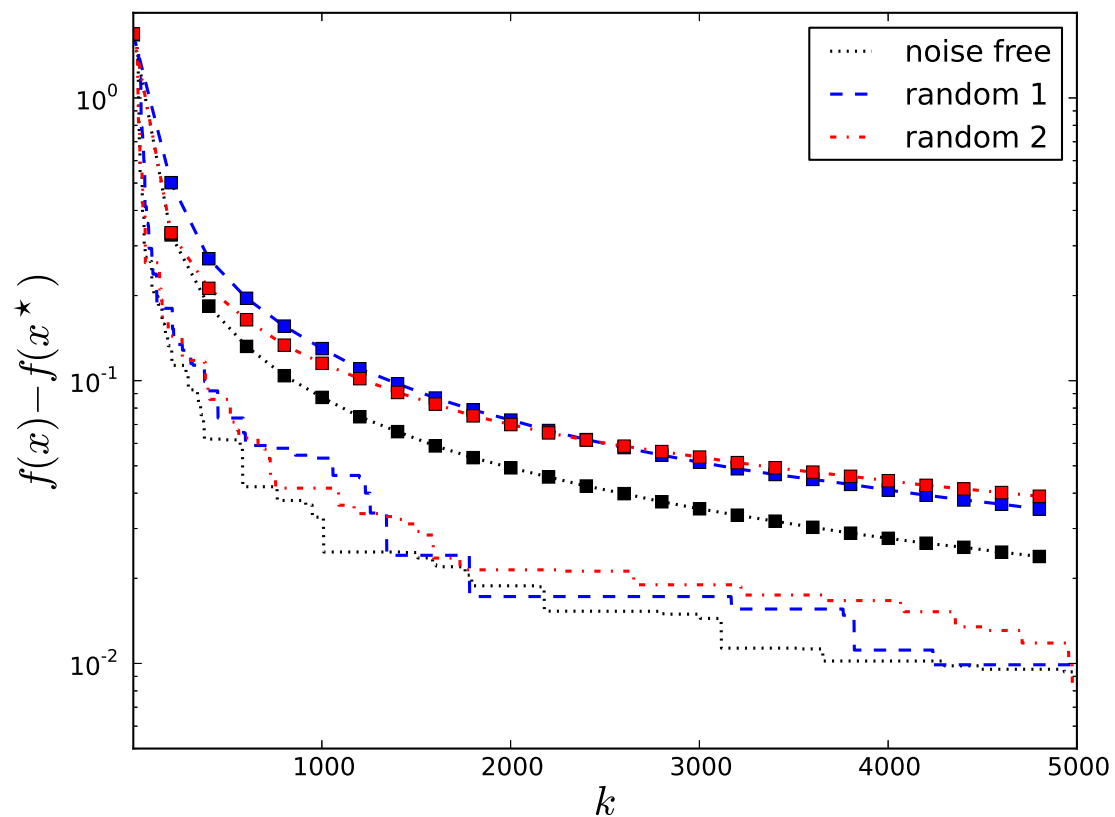
$$\text{minimize } f(x) = \max_{i=1, \dots, m} (a_i^T x + b_i)$$

we use stochastic subgradient algorithm with noisy subgradient

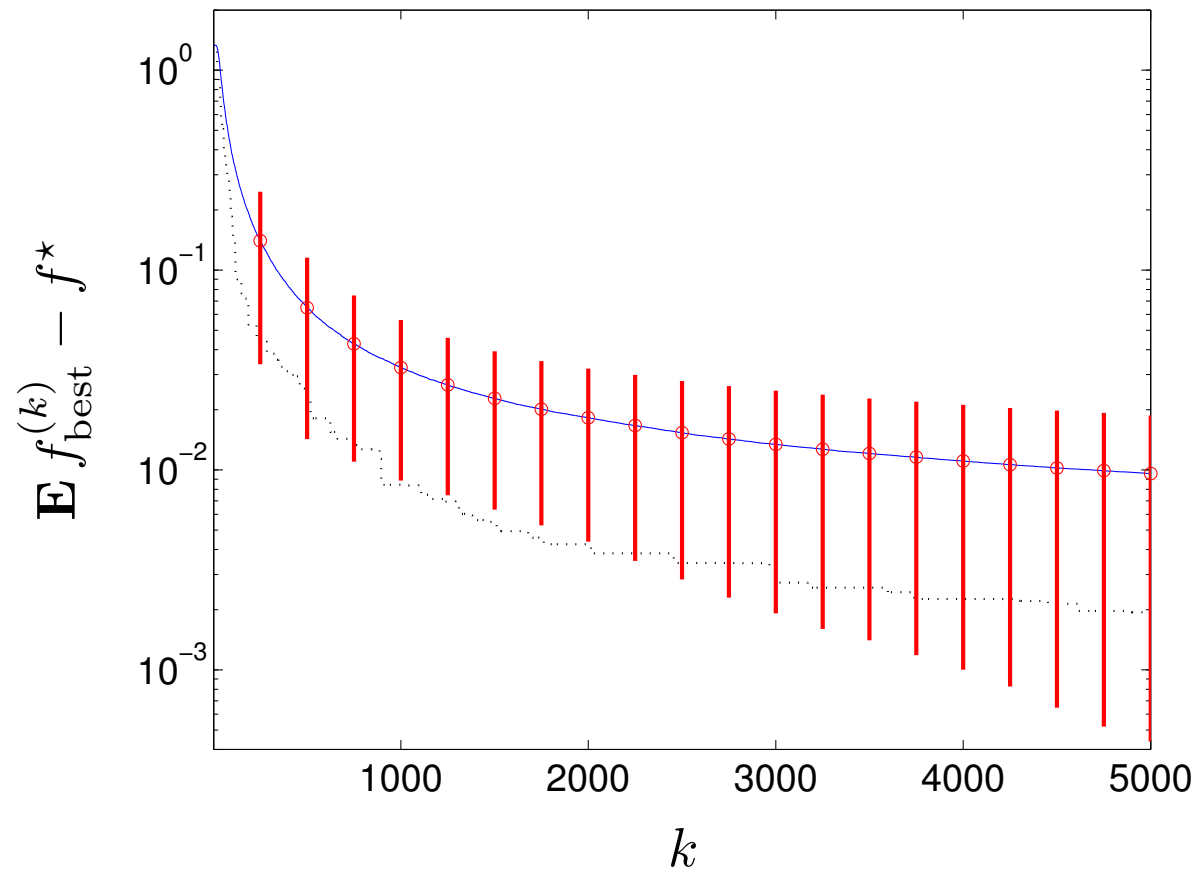
$$\tilde{g}^{(k)} = g^{(k)} + v^{(k)}, \quad g^{(k)} \in \partial f(x^{(k)})$$

$v^{(k)}$ independent zero mean random variables

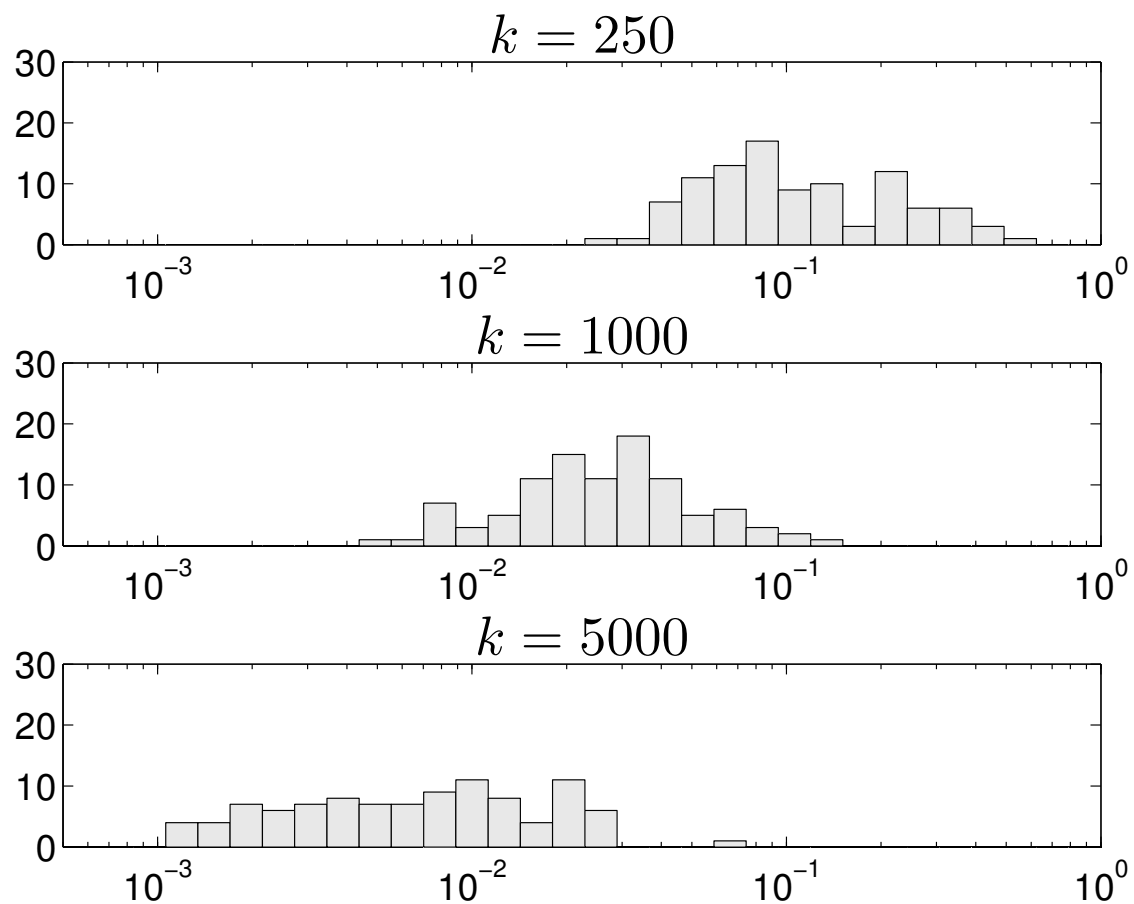
problem instance: $n = 20$ variables, $m = 100$ terms, $f^* \approx 1.1$, $\alpha_k = 1/k$
 $v^{(k)}$ are IID $\mathcal{N}(0, 0.5I)$ (25% noise since $\|g\| \approx 4.5$)



average and one std. dev. for $f_{\text{best}}^{(k)} - f^*$ over 100 realizations



empirical distributions of $f_{\text{best}}^{(k)} - f^*$ at $k = 250$, $k = 1000$, and $k = 5000$



Stochastic programming

$$\begin{array}{ll} \text{minimize} & \mathbf{E} f_0(x, \omega) \\ \text{subject to} & \mathbf{E} f_i(x, \omega) \leq 0, \quad i = 1, \dots, m \end{array}$$

if $f_i(x, \omega)$ is convex in x for each ω , problem is convex

‘certainty-equivalent’ problem

$$\begin{array}{ll} \text{minimize} & f_0(x, \mathbf{E} \omega) \\ \text{subject to} & f_i(x, \mathbf{E} \omega) \leq 0, \quad i = 1, \dots, m \end{array}$$

(if $f_i(x, \omega)$ is convex in ω , gives a lower bound on optimal value of stochastic problem)

Variations

- in place of $\mathbf{E} f_i(x, \omega) \leq 0$ (constraint holds in expectation) can use
 - $\mathbf{E} f_i(x, \omega)_+ \leq \epsilon$ (LHS is expected violation)
 - $\mathbf{E} (\max_i f_i(x, \omega)_+) \leq \epsilon$ (LHS is expected worst violation)
- unfortunately, *chance constraint* $\mathbf{Prob}(f_i(x, \omega) \leq 0) \geq \eta$ is convex only in a few special cases

Expected value of convex function

suppose $F(x, w)$ is convex in x for each w and $G(x, w) \in \partial_x F(x, w)$

- $f(x) = \mathbf{E} F(x, w) = \int F(x, w)p(w) dw$ is convex
- a subgradient of f at x is

$$g = \mathbf{E} G(x, w) = \int G(x, w)p(w) dw \in \partial f(x)$$

- a noisy unbiased subgradient of f at x is

$$\tilde{g} = \frac{1}{M} \sum_{i=1}^M G(x, w_i)$$

where w_1, \dots, w_M are M independent samples (Monte Carlo)

Example: Expected value of piecewise linear function

$$\text{minimize } f(x) = \mathbf{E} \max_{i=1,\dots,m} (a_i^T x + b_i)$$

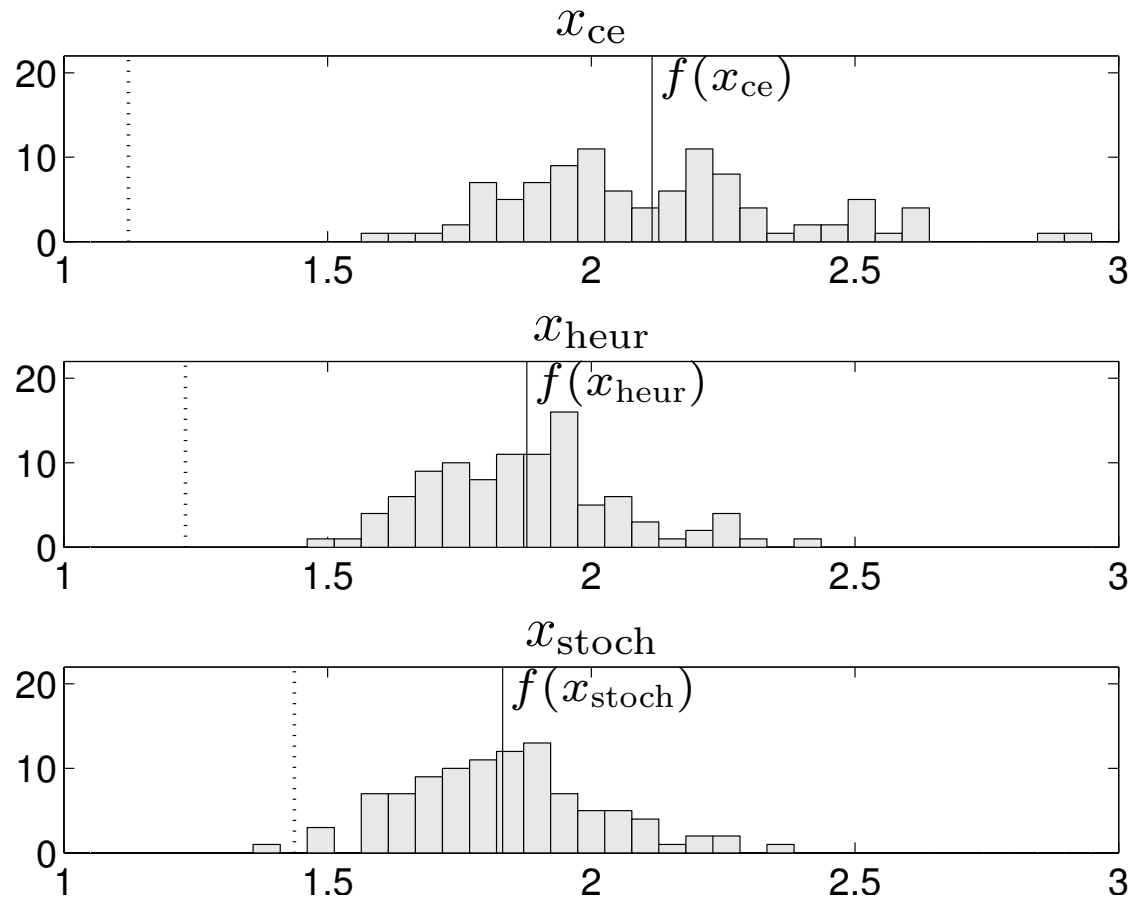
where a_i and b_i are random

evaluate noisy subgradient using Monte Carlo method with M samples,
and run stochastic subgradient method

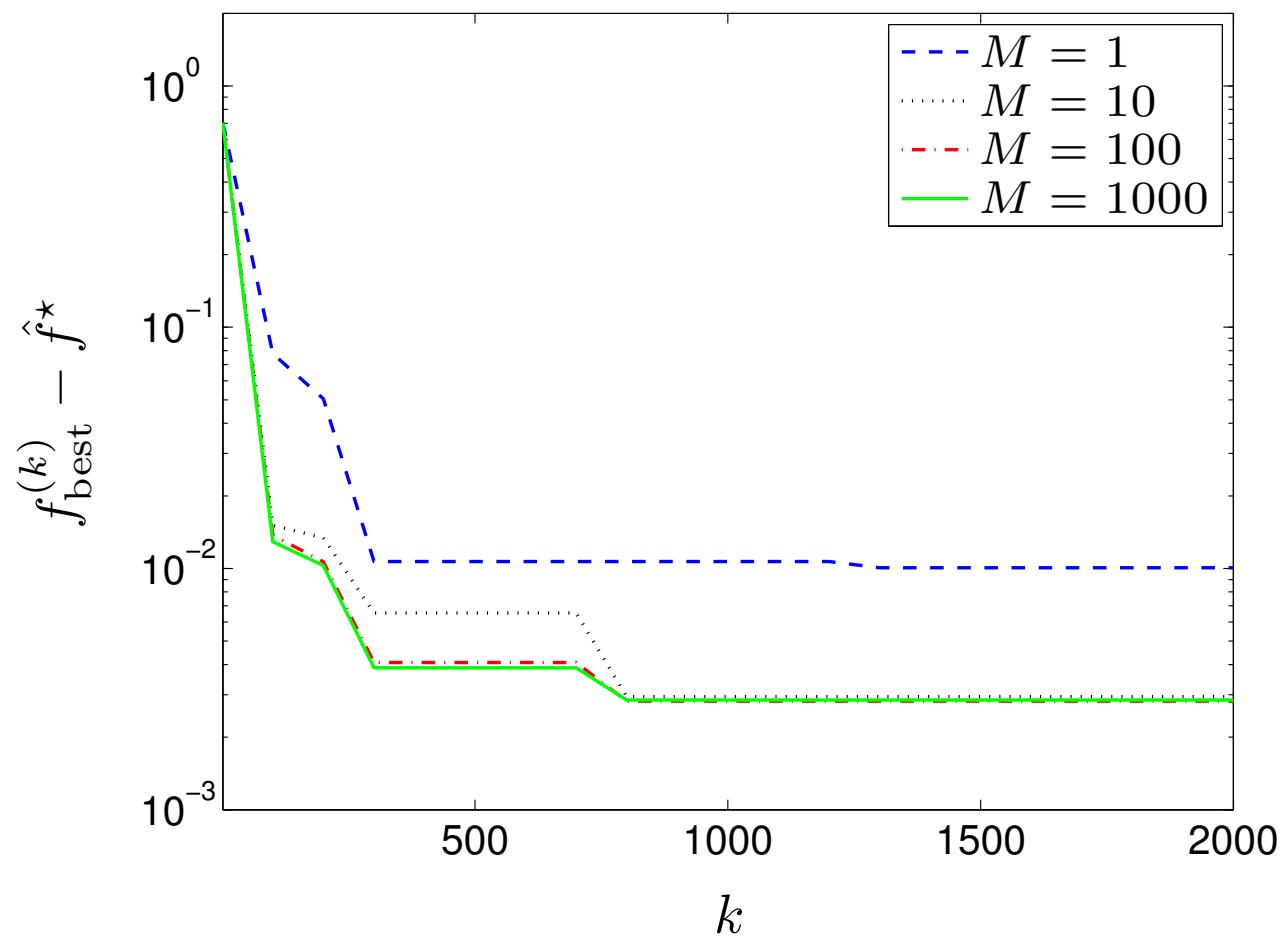
compare to:

- certainty equivalent: minimize $f_{\text{ce}}(x) = \max_{i=1,\dots,m} (\mathbf{E} a_i^T x + \mathbf{E} b_i)$
- heuristic: minimize $f_{\text{heur}}(x) = \max_{i=1,\dots,m} (\mathbf{E} a_i^T x + \mathbf{E} b_i + \lambda \|x\|_2)$

problem instance: $n = 20$, $m = 100$, $a_i \sim \mathcal{N}(\bar{a}_i, 5I)$, $b \sim \mathcal{N}(\bar{b}, 5I)$,
 $\|a_i\|_2 \approx 5$, $\|b\|_2 \approx 10$, x_{stoch} computed using $M = 100$



$f^* \approx 1.34$ estimated by running the method with $M = 1000$ for long time



On-line learning and adaptive signal processing

- $(x, y) \in \mathbf{R}^n \times \mathbf{R}$ have some joint distribution
- find weight vector $w \in \mathbf{R}^n$ for which $w^T x$ is a good estimator of y
- choose w to minimize expected value of a convex *loss function* l

$$J(w) = \mathbf{E} l(w^T x - y)$$

- $l(u) = u^2$: mean-square error
- $l(u) = |u|$: mean-absolute error

- at each step (*e.g.*, time sample), we are given a sample $(x^{(k)}, y^{(k)})$ from the distribution

noisy unbiased subgradient of J at $w^{(k)}$, based on sample $x^{(k+1)}, y^{(k+1)}$:

$$g^{(k)} = l'(w^{(k)T} x^{(k+1)} - y^{(k+1)}) x^{(k+1)}$$

where l' is the derivative (or a subgradient) of l

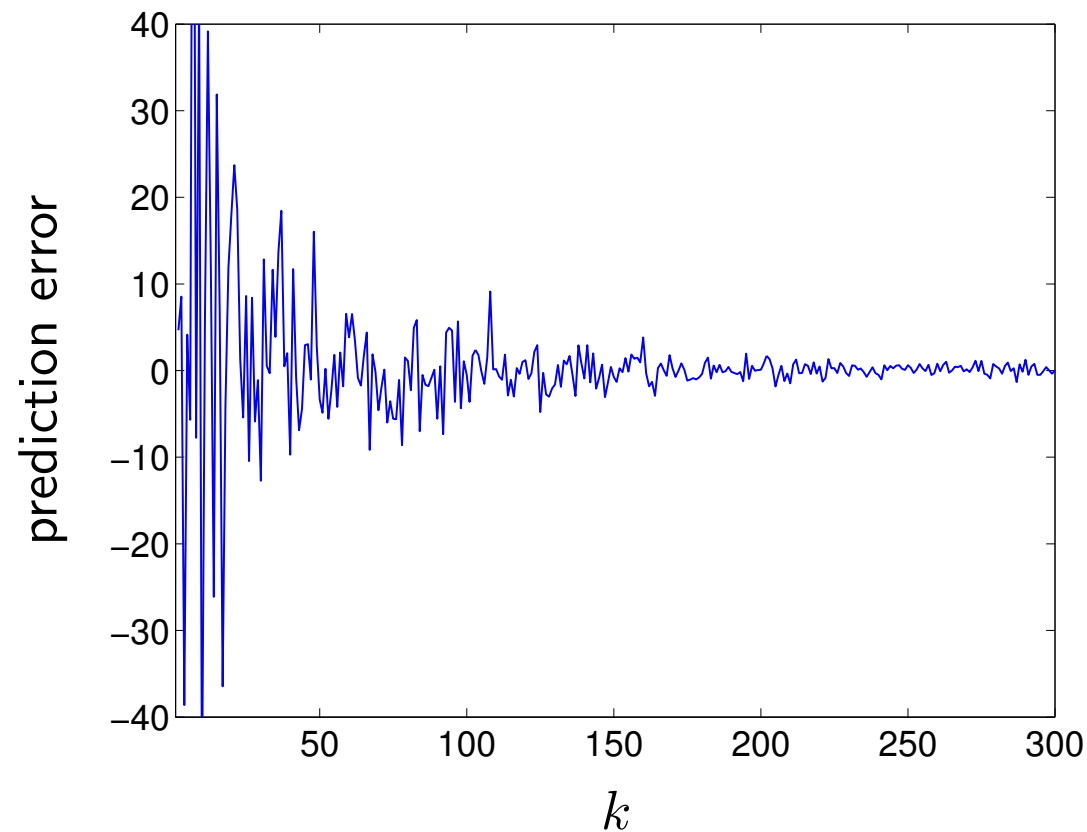
on-line algorithm:

$$w^{(k+1)} = w^{(k)} - \alpha_k l'(w^{(k)T} x^{(k+1)} - y^{(k+1)}) x^{(k+1)}.$$

- for $l(u) = u^2$, gives the LMS (least mean-square) algorithm
- for $l(u) = |u|$, gives the *sign* algorithm
- $w^{(k)T} x^{(k+1)} - y^{(k+1)}$ is the prediction error

Example: Mean-absolute error minimization

problem instance: $n = 10$, $(x, y) \sim \mathcal{N}(0, \Sigma)$, Σ random with $\mathbf{E}(y^2) \approx 12$,
 $\alpha_k = 1/k$



empirical distribution of prediction error for w^* (over 1000 samples)

