

Reconstruction of compressive light field data

Yuxin Hu, Minda Deng

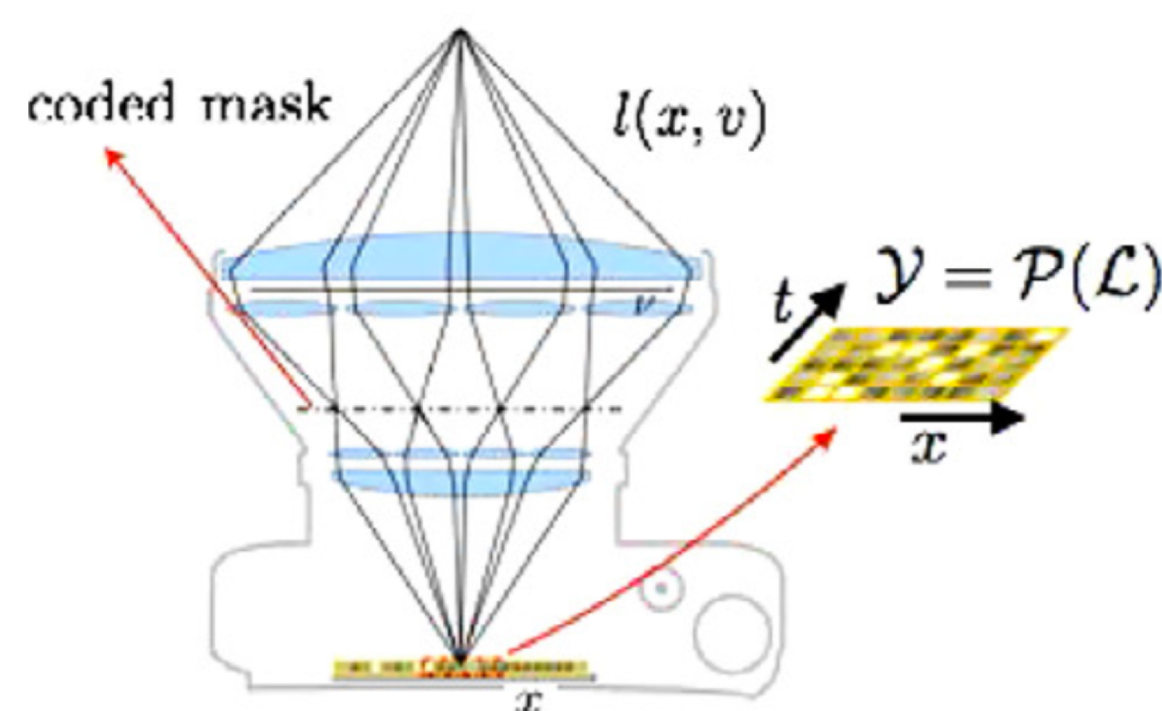
{yuxinh, mindad}@stanford.edu

Stanford University, Stanford, CA 94305, USA

Introduction & Motivation

- Light field photography records both spatial and angular (4D) information, allowing for new applications
 - Depth estimation, Occlusion removal, etc.
- However, intrinsic tradeoff between spatial and angular resolution
- Different physical design: combining different views (angular) while adding 5th dimension (time frame) [1]
 - Spatial resolution reserved
 - Needs to be reconstructed
- Compressive sensing for image reconstruction

$$\underset{\{x\}}{\text{minimize}} \frac{1}{2} \|b - Ax\|_2^2 + \lambda \Gamma(x)$$



Related Work

- Super resolution algorithm: linear optimization, not work for compressive light field data [2]
- 4D light field dictionary: learning phase computationally slow and expensive [3]
- Compressive light field photography reconstruction using low rank and sparse priors [1]
- Different priors/constraints including: total variation, locally/globally low-rank [4], L1-DCT.

References

- [1] Kamal et al., Computer Vision and Image Understanding, 2016
- [2] Bishop et al., Proceedings of the ICCP, IEEE, 2009
- [3] Marwah et al., ACM Trans. Graph, 2013
- [4] Jain et al., ACM symposium on Theory of computing. ACM, 2013.

New Technique

Our low-rank + sparse formulation:

$$\min_{L, S} \|A(L + S) - b\|_2^2 + \lambda_1 P_1(L) + \lambda_2 P_2(S)$$

Update rule using ADMM

while stop criterion false **do**

$$L^{k+1} = \underset{L}{\text{argmin}} \|A(L + S^k) - b\|_2^2 + \rho/2 \|L - Z_1^k + U_1^k\|_2^2$$

$$S^{k+1} = \underset{S}{\text{argmin}} \|A(L^k + S) - b\|_2^2 + \rho/2 \|\Psi(S) - Z_2^k + U_2^k\|_2^2$$

$$Z_1 = \text{prox}_{\frac{\lambda_1}{\rho} P_1}(L^{K+1} + U_1^{K+1})$$

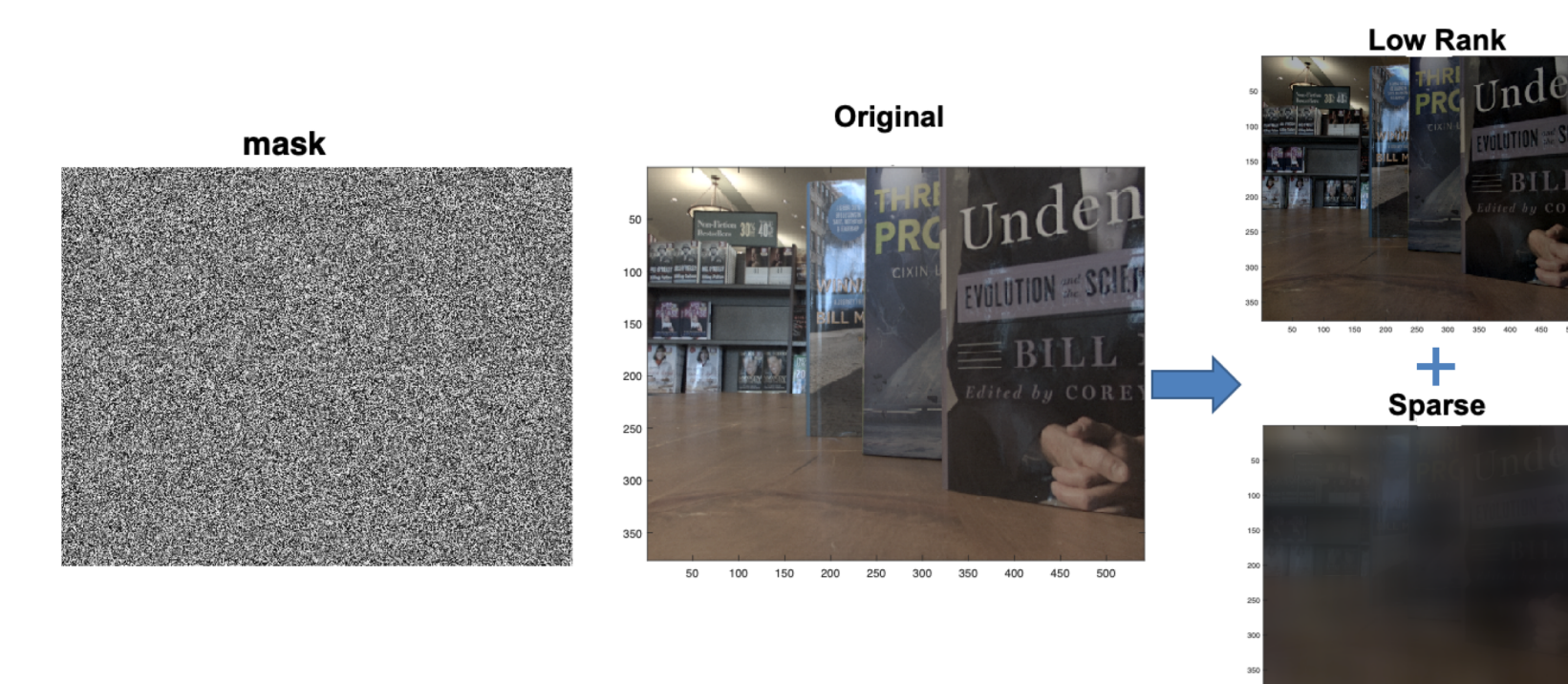
$$Z_2 = \text{prox}_{\frac{\lambda_2}{\rho} P_2}(\Psi(S^{K+1}) + U_2^{K+1})$$

$$U_1^{k+1} = U_1^k + L^{k+1} - Z_1^{k+1}$$

$$U_2^{k+1} = U_2^k + \Psi(S^{k+1}) - Z_2^{k+1}$$

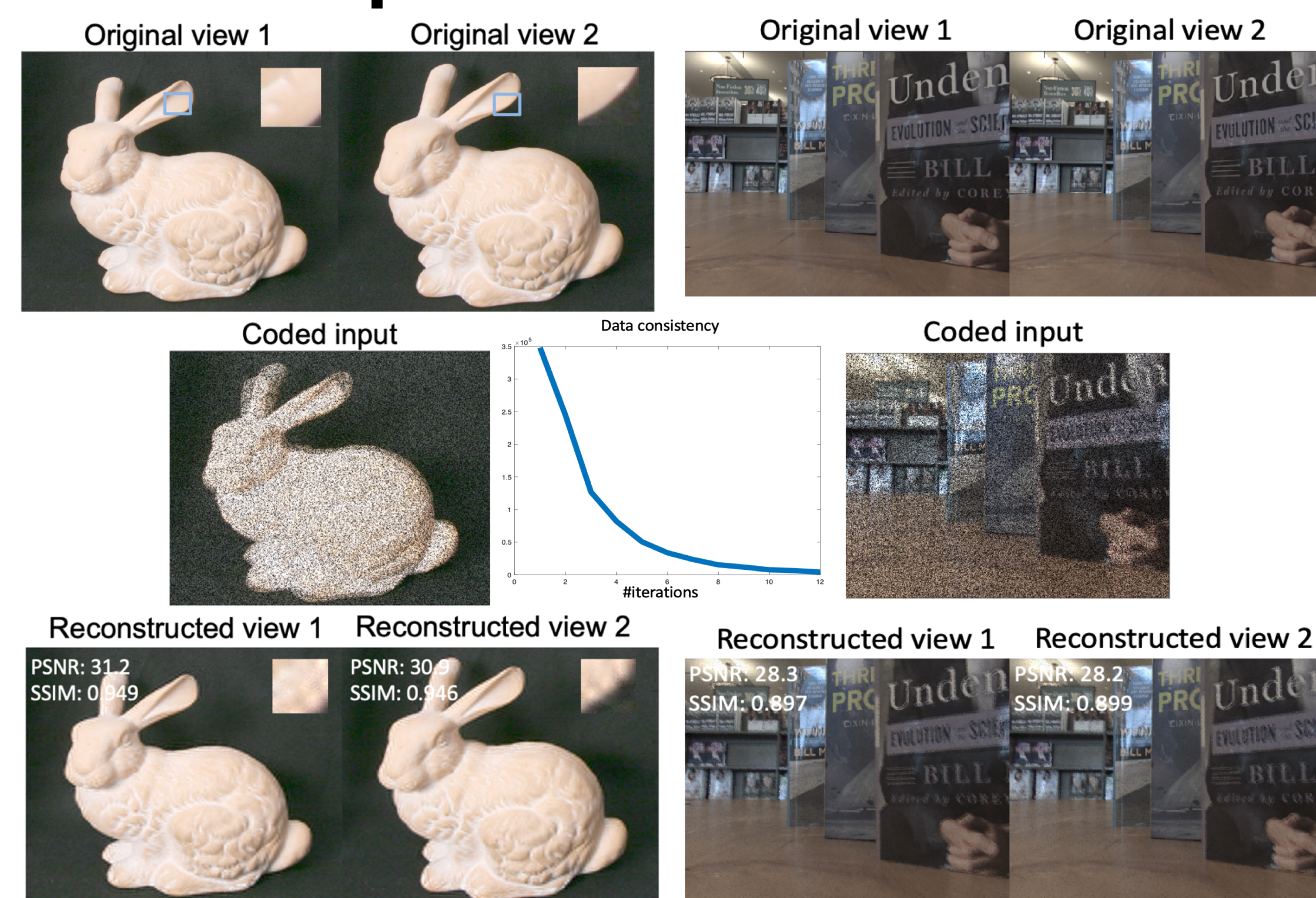
return L, S

	Explanations
A	mask operator at all V views and all T frames
L/S	low rank/sparse component (V views in total)
b	acquired view-combined image (T frames in total)
λ_1, λ_2	regularization parameters
P_1	prior on low rank term (locally low-rank, globally low-rank)
P_2, Ψ	prior on sparse term (l1-wavelet, l1-fft, l1-dct, l2, TV)



*Code available at <https://drive.google.com/open?id=1XDZsROvJaLwXzfpkCJR6GRPxOVA9FVYf>

Experimental Results



*Data from <http://graphics.stanford.edu/data/LF/lfs.html>

Summary

- Able to recover multiple views from compressive light field data.
- Formulated the recovery as a two-component model (low rank + sparse) and implemented corresponding ADMM algorithm to solve it.
- Still exploring different models, different combinations of priors and parameter space.