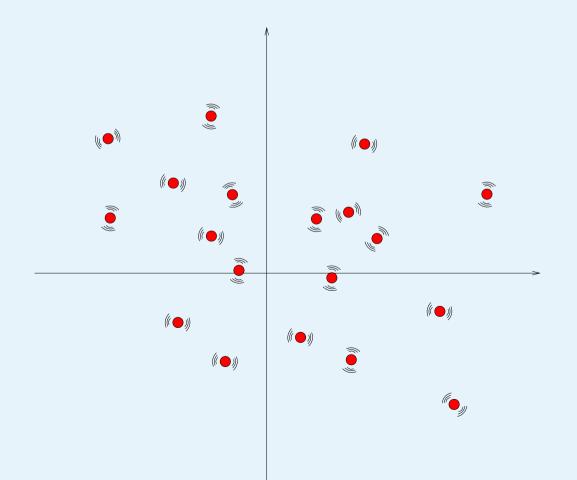
Stochastic Differential Equations





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Wiener Processes and Brownian Motions

Poisson Processes



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You get told:

Fix x_0

 $x \in \mathbb{R}^n$,



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Wiener Processes and Brownian Motions

You get told:

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Fix x_0 and a dynamical equation

$$\frac{dx}{dt} = f(x).$$



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Then you quote an Existence and Uniqueness theorem.



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Lo and behold, a trajectory!

 $x(t) = g(t, x_0)$



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The Chain rule.



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- Underlying it all is calculus, with
- The Leibniz Rule.
- The Chain rule.
- The Fundamental Theorem of Calculus.



Poisson Processes

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Wiener Processes and Brownian Motions

It's all very deterministic.



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Wiener Processes and Brownian Motions

It's all very deterministic. How do we put noise in?



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Wiener Processes and Brownian Motions It's all very deterministic. How do we put noise in?

Can we do something like:

$$dx = f(x)dt + Noise \tag{1}$$

And then follow the procedure from before?



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Make a careful definition of noise and its statistics.



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- Redo the basic notions of calculus now stochastically.



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The GRAND PRINCIPLE: non-deterministic trajectories generated by statistical differential equations should be governed by a deterministic differential equation on the *probability density* of states.



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$$\frac{\partial \rho}{\partial t} = F(x, t, \text{noise coefficients})$$
 (2)



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Wiener Processes and Brownian Motions We will approach the definition of noisy differential equations through two limiting procedures, one in space and one in time.



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 $N:\mathbb{N}\to\mathbb{N}$ given by

$$N_1(m) = N_1(m-1) +$$

with probability
$$\lambda$$

with probability $1 - \lambda$

with
$$N(0) = 0$$
.



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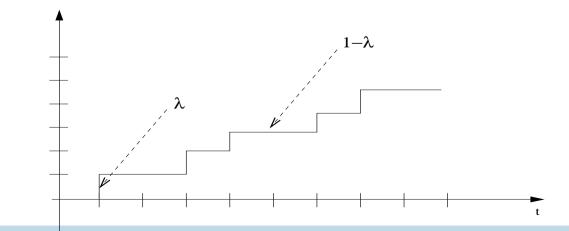
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with probability λ with probability $1 - \lambda$

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with N(0) = 0.

$$N_1(m) = N_1(m-1) + \begin{cases} 1\\ 0 \end{cases}$$

with probability λ with probability $1 - \lambda$

It's a "Pascal process" (I think) because:

$$\rho(m,n) = \binom{m}{n} \lambda^n (1-\lambda)^{m-n}$$



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Wiener Processes and **Brownian Motions**

Define for each k

$$N_k\left(\frac{m}{k}\right) = N_k\left(\frac{m-1}{k}\right) + \begin{cases} 1\\ 0 \end{cases}$$

with N(0) = 0.

with probability λ/k with probability $1 - \lambda/k$

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$$N_k\left(\frac{m}{k}\right) = N_k\left(\frac{m-1}{k}\right) + \begin{cases} 1\\ 0 \end{cases}$$

with N(0) = 0.

Definition 1
$$N_{\lambda} : \mathbb{R} \to \mathbb{N}$$

$$N_{\lambda} \stackrel{d}{=} \lim_{k \to \infty} N_k$$

with probability λ/k with probability $1 - \lambda/k$



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$$N_{\lambda}$$
 has a well-defined rate.

with probability λ/k with probability $1 - \lambda/k$



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 N_{λ} has a well-defined *rate*. That is,

$$\lim_{\Delta \to 0} \left[\frac{Prob[N_{\lambda}(t + \Delta) = N_{\lambda}(t) + 1]}{\Delta} \right]$$

is a constant function of time.

with probability λ/k with probability $1 - \lambda/k$



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$$N_{\lambda} \stackrel{d}{=} \lim_{k \to \infty} N_k$$

with probability λ/k

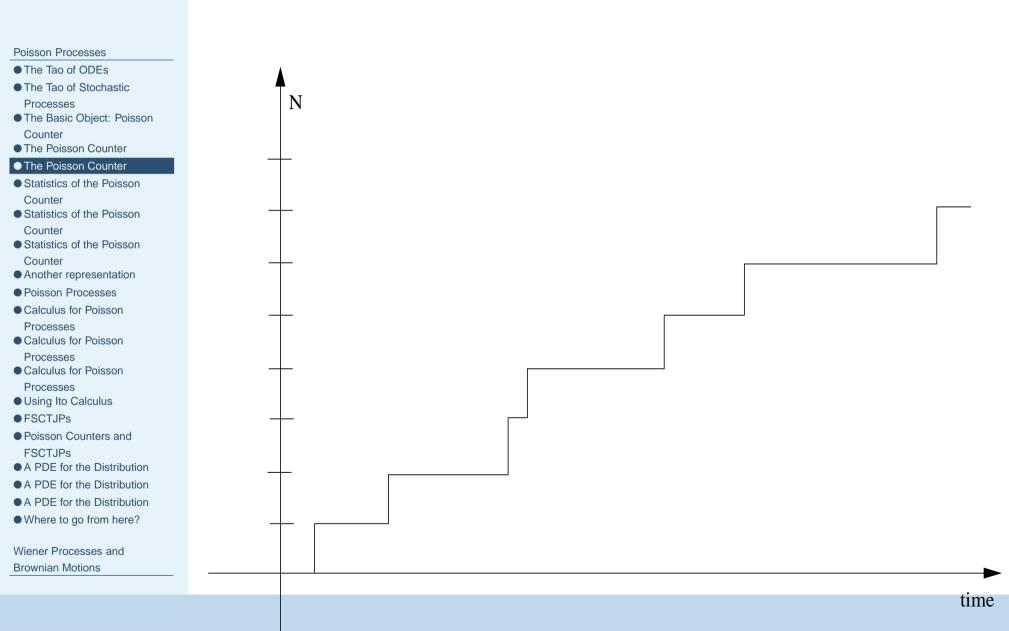
with probability $1 - \lambda/k$

In particular:

$$\lim_{\Delta \to 0} \left[\frac{Prob[N_{\lambda}(t + \Delta) = N_{\lambda}(t) + 1]}{\Delta} \right] = \lambda$$

This is why N_{λ} is called a *poisson counter with rate* λ .







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Wiener Processes and Brownian Motions

We can derive the statistics of this process. Let

$$P_i(t) = Prob[N_\lambda(t) = i].$$



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Wiener Processes and Brownian Motions We can derive the statistics of this process. Let

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What is
$$P_0(1)$$
?



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Wiener Processes and Brownian Motions We can derive the statistics of this process. Let

$$P_i(t) = Prob[N_\lambda(t) = i].$$

$$P_0(1) = \lim_{n \to \infty} \left(1 - \frac{\lambda}{n}\right)^n$$



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Wiener Processes and Brownian Motions We can derive the statistics of this process. Let

$$P_i(t) = Prob[N_\lambda(t) = i].$$

$$\lim_{n \to \infty} \left(1 + \frac{x}{n} \right)^n = e^x$$



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Wiener Processes and Brownian Motions We can derive the statistics of this process. Let

$$P_i(t) = Prob[N_\lambda(t) = i].$$

$$P_0(1) = \lim_{n \to \infty} \left(1 - \frac{\lambda}{n}\right)^n = e^{-\lambda}$$



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In general,

So

and

$$P_0(t) = e^{-\lambda t}$$

$$P_n(t) = \frac{(\lambda t)^n}{n!} e^{-\lambda t}.$$



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In general,

So

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$$P_0(t) = e^{-\lambda t}$$

$$P_n(t) = \frac{(\lambda t)^n}{n!} e^{-\lambda t}.$$

Of course,

$$\sum_{n} P_n(t) = e^{-\lambda t} \sum_{n} \frac{(\lambda t)^n}{n!} = e^{-\lambda t} e^{\lambda t} = 1$$



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Wiener Processes and Brownian Motions

$$E[N_{\lambda}](t) = \sum_{n} nP_{n}(t) = \lambda e^{-\lambda t} \sum_{n} \frac{(\lambda t)^{n}}{n!} = \lambda t$$



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Wiener Processes and Brownian Motions

$$E[N_{\lambda}](t) = \sum_{n} nP_{n}(t) = \lambda e^{-\lambda t} \sum_{n} \frac{(\lambda t)^{n}}{n!} = \lambda t$$

Moreover, we can calculate higher moments as well:

$$E[N_{\lambda}^{m}](t) = e^{-\lambda t} \sum_{n} n^{m} (\lambda t)^{n} / n!$$
(2)



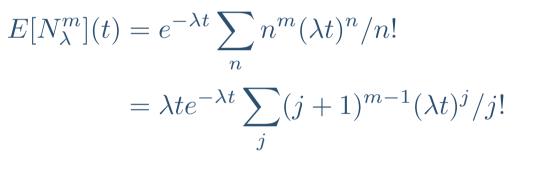
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Moreover, we can calculate higher moments as well:

E[

$$N_{\lambda}^{m}](t) = e^{-\lambda t} \sum_{n} n^{m} (\lambda t)^{n} / n!$$

$$= \lambda t e^{-\lambda t} \sum_{j} (j+1)^{m-1} (\lambda t)^{j} / j!$$

$$= \lambda t e^{-\lambda t} \sum_{i} \sum_{k} \binom{m-1}{k} j^{k} (\lambda t)^{k} / j!$$
(2)

k

j



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Wiener Processes and Brownian Motions

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Moreover, we can calculate higher moments as well:

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$$[N_{\lambda}^{m}](t) = e^{-\lambda t} \sum_{n} n^{m} (\lambda t)^{n} / n!$$

$$= \lambda t e^{-\lambda t} \sum_{j} (j+1)^{m-1} (\lambda t)^{j} / j!$$

$$= \lambda t e^{-\lambda t} \sum_{j} \sum_{k=0}^{m-1} {m-1 \choose k} j^{k} (\lambda t)^{k} / j!$$

$$= \lambda t \sum_{k=0}^{m-1} {m-1 \choose k} E[N_{\lambda}^{k}](t).$$
(2)



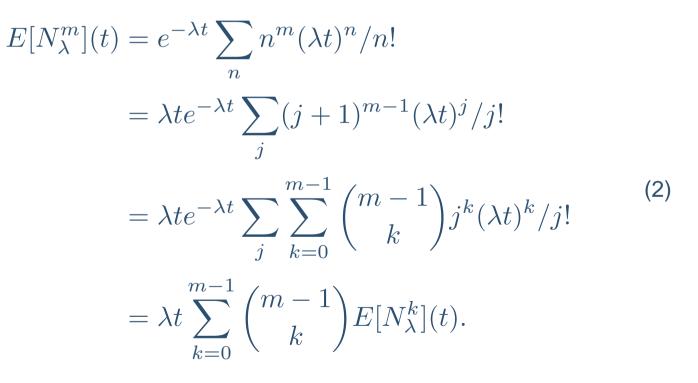
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Wiener Processes and Brownian Motions

 $E[N_{\lambda}](t) = \sum_{n} nP_{n}(t) = \lambda e^{-\lambda t} \sum_{n} \frac{(\lambda t)^{n}}{n!} = \lambda t$

Moreover, we can calculate higher moments as well:



This recursive calculation of moments is a hallmark of stochastic processes.



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Wiener Processes and Brownian Motions The mathematically inclined among you will be wondering: Is it OK to do what I did?



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Wiener Processes and Brownian Motions The mathematically inclined among you will be wondering: Is it OK to do what I did? Well, yes:

Theorem 1 Suppose $X_n : \mathbb{N}[1/n] \to \mathbb{N}$ is a sequence of time-invariant random variables such that

$$X = \lim_{n \to \infty} X_n : \mathbb{R} \to \mathbb{N}$$

exists and satisfies

$$\lim_{\tau \to 0} \left[\frac{Prob[X(t+\tau) = X(t) + 1]}{\tau} \right] = \lambda$$

$$\lim_{\tau \to 0} \left[\frac{Prob[X(t+\tau) = X(t)]}{\tau} \right] = 1 - \lambda.$$

Then $X \stackrel{d}{=} N_{\lambda}$.

and



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exists and satisfies

Then $X \stackrel{d}{=} N_{\lambda}$.

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$$\lim_{\tau \to 0} \left[\frac{Prob[X(t+\tau) = X(t)]}{\tau} \right] = 1 - \lambda$$

Hence, N_{λ} is "the" poisson limit process with rate λ .



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Wiener Processes and Brownian Motions

Another way to think about N_{λ} is as that process which satisfies:



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Wiener Processes and **Brownian Motions**

Another way to think about N_{λ} is as that process which satisfies:

$$\frac{dP_i(t)}{dt} = -\lambda P_i(t) + \lambda P_{i-1}(t).$$



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Wiener Processes and Brownian Motions

Another way to think about N_{λ} is as that process which satisfies:

$$\frac{dP_i(t)}{dt} = -\lambda P_i(t) + \lambda P_{i-1}(t).$$

That is, the transition matrix is:

$$\dot{\mathbf{P}}(t) = \begin{bmatrix} -\lambda & 0 & 0 & 0 & 0 & \cdots \\ \lambda & -\lambda & 0 & 0 & 0 & \cdots \\ 0 & \lambda & -\lambda & 0 & 0 & \cdots \\ \vdots & & & & \vdots \end{bmatrix} \mathbf{P}(t)$$

where $\mathbf{P}(t) = (P_1(t), P_2(t), ...)^T$.



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That is, the transition matrix is:

	$\left\lceil -\lambda \right\rceil$	0	0	0	0	••••	
$\dot{\mathbf{P}}(t) =$	λ	$-\lambda$	0	0	0	• • •	
	0	λ	$-\lambda$	0	0	• • •	
	÷					:	
	L						

where $\mathbf{P}(t) = (P_1(t), P_2(t), ...)^T$.

This transition-matrix representation points to how poisson counters like N_{λ} can be really useful in representing probabilistic processes.



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Wiener Processes and Brownian Motions

Let us write the equation

$$dx = f(x,t)dt + g(x,t)dN_{\lambda}.$$
(3)



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Wiener Processes and Brownian Motions

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This is a noisy (stochastic) analog of regular differential equations. But what does it mean?



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This is a noisy (stochastic) analog of regular differential equations. But what does it mean?

Definition 2 A trajectory x(t) is an *Ito solution* to the above equation if: When N_{λ} is constant on [a, b], x satisfies dx = f(x, t)dt

• When N_{λ} jumps at t_1 , x satisfies:

$$\lim_{t \to t_1^+} x(t) = g\left(\lim_{t \to t_1^-} x(t), t_1\right) + \lim_{t \to t_1^-} x(t)$$

- in a neighborhood of t_1
- \blacksquare x is continuous from the left.



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- in a neighborhood of t_1
- x is continuous from the left.

This does not define a single trajectory – instead, it defines a *set*, which possess a statistical distribution inherited from the distribution on the Poisson counters.



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Wiener Processes and Brownian Motions

So, given

$$dx = f(x,t)dt + \sum_{i} g_i(x,t)dN_i$$

what are the statistical properties of the solutions?



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Wiener Processes and Brownian Motions

So, given

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what are the statistical properties of the solutions?

In other words, what are E[x](t), higher moments, &c?



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In other words, what are E[x](t), higher moments, &c?

The basic principle: first use calculus to get

 $d(x^m) =$ something $\times dt +$ something $\times dN$



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Then take expectations:

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$$E[d(x^{m})] = dE[x^{m}] = E[f_{1}(x,t)]dt + E[g_{2}(x,t)]dE[N].$$

Using $E[N_{\lambda}](t) = \lambda t$, we get

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But this is a regular ODE!!



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Wiener Processes and Brownian Motions

In fact, if $\phi : \mathbb{R}^n \to \mathbb{R}$ is any (nice) function, then $\phi(x)$ is itself a poisson process; same method gives us satisfical info about $\phi(x)$.



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Regular calculus would tell us that

$$d(x^2) = 2xdx.$$



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$$dx = xdt + xdN$$
 to get $\frac{dx}{x} = dt + dN$.



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DO NOT FAIL TO UNDERSTAND THESE POINTS!!



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Wiener Processes and Brownian Motions However, it's (almost) trivial to see what the answer is.



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Recall, a trajectory x(t) is a solution if: When N_{λ} is constant on [a, b], x satisfies dx = f(x, t)dtWhen N_{λ} jumps at t_1 , x satisfies:

$$\lim_{t \to t_1^+} x(t) = g\left(\lim_{t \to t_1^-} x(t), t_1\right) + \lim_{t \to t_1^-} x(t)$$

in a neighborhood of t_1

• x is continuous from the left.



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On an interval where N_i doesn't change, standard calculus tells us:

$$d\phi = \left\langle \frac{d\phi}{dx}, f(x) \right\rangle dt.$$



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If N_i does change at t, then we have to add the discrete quantity:

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Hence, just from the definition of "solution":

$$d\phi(x,t) = \left\langle \frac{d\phi}{dx}, f(x) \right\rangle dt + \sum_{i=1}^{n} [\phi(x+g_i(x)) - \phi(x)] dN_i.$$



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This is the "Ito Rule"; it is a combination of modified Leibniz and Chain-rule for stochastic calculus.



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Wiener Processes and Brownian Motions

Example 1 Suppose

$$dx(t) = -kx(t)dt + dN_1(t) - dN_2(t)$$



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$$dx(t) = -kx(t)dt + dN_1(t) - dN_2(t)$$

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$$dx^{2} = -2kx^{2}(t)dt + [(x(t)+1)^{2} - x^{2}(t)]dN_{1} + [(x(t)-1)^{2} - x^{2}(t)]dN_{2}$$
(4)



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$$dx^{2} = -2kx^{2}(t)dt + [1 + 2x(t)]dN_{1} + [1 - 2x(t)]dN_{2}.$$
 (4)



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Wiener Processes and Brownian Motions

Example 1 Suppose

$$dx(t) = -kx(t)dt + dN_1(t) - dN_2(t)$$

Then

$$dE[x](t) = -kE[x](t)dt + \lambda_1 dt - \lambda_2 dt$$

So using variation of constants:

$$E[x](t) = \frac{E[x](0)}{k}((k - \lambda_1 + \lambda_2)e^{-kt} + \lambda_1 - \lambda_2).$$

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$$\frac{dE[x^2]}{dt} = -2kE[x^2] + 2(\lambda_1 - \lambda_2)E[x](t) + \lambda_1 + \lambda_2$$



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Again, recursive calculuation of moments.



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Again, recursive calculuation of moments. (You stick in from above and use Variation of Constants formula.)



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Wiener Processes and Brownian Motions

Suppose you're given a finite-state transition scheme:



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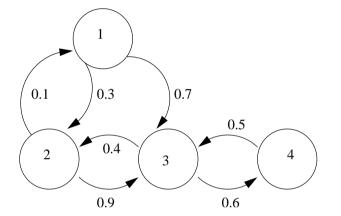
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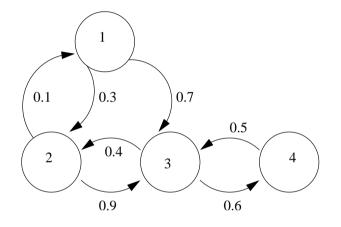
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Wiener Processes and Brownian Motions

Suppose you're given a finite-state transition scheme:



Definition 3 A state-transition equation

 $\dot{\mathbf{P}}(t) = A\mathbf{P}(t)$

is called a *finite-state continuous time jump process* (FSCTJP), when A is a stochastic matrix, i.e. columns sum to 0 and (off-diagonal) entries are non-negative.



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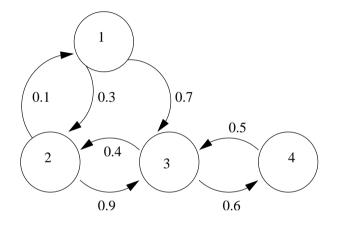
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Such systems have obvious potential for being useful representations of scientific phenonmena.

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Wiener Processes and Brownian Motions

Theorem 2 [Basis Theorem] Any FSCTJP is equivalent, in distribution, to

$$dx = \sum_{i=1}^{m} f_i(x) dN_i$$

for some (nice) functions f_i and poisson counters N_i with rates $\lambda_i > 0$.



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Example 2

$$\begin{bmatrix} \dot{p}_1(t) \\ \dot{p}_2(t) \\ \dot{p}_3(t) \end{bmatrix} = \begin{bmatrix} -3 & 0 & 8 \\ 3 & -2 & 0 \\ 0 & 2 & -8 \end{bmatrix} \begin{bmatrix} p_1(t) \\ p_2(t) \\ p_3(t) \end{bmatrix}$$

with
$$x(0) \in \{3, 7, 9\}.$$



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Then



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Then

$$dx = \frac{(x-9)(x-7)}{6} dN_3 + \frac{(x-3)(x-9)}{4} dN_2 + \frac{(3-x)(x-7)}{2} dN_8$$



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Wiener Processes and Brownian Motions Let ψ be any smooth function with $\psi = 0$ for large |x|. Then of course

$$d\psi = \left\langle \frac{d\phi}{dx}, f(x) \right\rangle dt + \sum_{i=1}^{n} [\psi(x + g_i(x)) - \psi(x)] dN_i.$$



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And

$$E[\psi(x)](t) = \int \psi(x)\rho(x,t)dx$$

just by definition.



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Now, differentiating w.r.t t and comparing gives:

$$\int \psi(x) \frac{d\rho(x,t)}{dt} = \int \left[\frac{d\psi}{dx} + \sum_{i} \lambda_i (\psi(x+g_i(x)) - \psi(x)) \right] \rho(x,t) dx$$



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Wiener Processes and Brownian Motions Let $h_i(x) = x + g_i(x)$. Assume that h_i is finite-to-one. Change variables $x \to z$ so that dz = |det(I + dg)|dx.



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$$\int \psi(x+g_i(x))\rho(x,t)dx = \int \psi(z)\rho(h_i^{-1}(z),t)|det(I+dg_i)|^{-1}dz.$$



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Hence

$$\int \psi(x) \frac{\partial \rho}{\partial t} dx = \int \left(-\psi \frac{\partial (f\rho)}{dx} - \sum_{i} \lambda_{i} \psi \rho \right) dx + \sum_{i} \lambda_{i} \int \psi(z) \rho(h_{i}^{-1}(z), t) |\det(I + dg)|^{-1} dz.$$
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Wiener Processes and Brownian Motions Let $h_i(x) = x + g_i(x)$. Assume that h_i is finite-to-one. Change variables $x \to z$ so that dz = |det(I + dg)|dx. Then by the chain rule:

$$\int \psi(x+g_i(x))\rho(x,t)dx = \int \psi(z)\rho(h_i^{-1}(z),t)|det(I+dg_i)|^{-1}dz.$$

Hence

$$\int \psi(x) \frac{\partial \rho}{\partial t} dx = \int \left(-\psi \frac{\partial (f\rho)}{dx} - \sum_{i} \lambda_{i} \psi \rho \right) dx + \sum_{i} \lambda_{i} \int \psi(z) \rho(h_{i}^{-1}(z), t) |\det(I + dg)|^{-1} dz.$$
(5)

This can be collected as $\int \psi(x)[\text{stuff}] = 0$.



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This can be collected as $\int \psi(x)[\text{stuff}] = 0$. But $\psi(x)$ was chosen arbitrarily!



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Wiener Processes and Brownian Motions

Hence, stuff = 0.



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Hence, stuff = 0.

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Wiener Processes and **Brownian Motions**

his yields
$$\frac{\partial \rho}{\partial t} = -\frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) |det(I + dg)|^{-1} - \frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t] + \frac{\partial}{\partial$$

 $\rho(x,t)$].



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• Where to go from here?

Wiener Processes and Brownian Motions Hence, stuff = 0.

This yields

$$\frac{\partial \rho}{\partial t} = -\frac{\partial}{\partial x}(f\rho) + \sum_{i} \lambda_{i} [\rho(h_{i}^{-1}(x), t) | det(I + dg)|^{-1} - \rho(x, t)].$$

This is a deterministic PDE for the distribution. We've achieved the Grand Principle.



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It's very hard to solve. But: things can be done (including solve for steady states).



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Wiener Processes and Brownian Motions

Various things can now be done:



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• Where to go from here?

Wiener Processes and Brownian Motions

Various things can now be done:

Construct non-constant-rate poisson counters, i.e. let $\lambda = \lambda(t)$. And then, generalize results.



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Wiener Processes and Brownian Motions Various things can now be done:

- Construct non-constant-rate poisson counters, i.e. let $\lambda = \lambda(t)$. And then, generalize results.
- Construct non-deterministic-rate poisson counters, i.e. given $\lambda(t)$ by distribution. And generalize results.



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- Construct non-constant-rate poisson counters, i.e. let $\lambda = \lambda(t)$. And then, generalize results.
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- Take away discretization in space, going from jump processes to continuous processes.



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Wiener Processes and Brownian Motions Various things can now be done:

- Construct non-constant-rate poisson counters, i.e. let $\lambda = \lambda(t)$. And then, generalize results.
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- Take away discretization in space, going from jump processes to continuous processes.

The first two can be done, and are interesting, but the third is really where it's at.



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How should we continu-ize in space, as a limit of poisson counters?



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How should we continu-ize in space, as a limit of poisson counters? Take a limit in which the rate $\lambda \rightarrow 0$.



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How should we continu-ize in space, as a limit of poisson counters? Take a limit in which the rate $\lambda \rightarrow 0$.

Let w_{λ} be given by $dw_{\lambda} = \frac{1}{\sqrt{\lambda}} (dN_{\lambda/2}^{+} - dN_{\lambda/2}^{-})$ where $N_{\lambda/2}^{+}, N_{\lambda/2}^{-}$ are independent poisson counters of rate $\lambda/2$, $w_{\lambda}(0) = 0$.



Poisson Processes

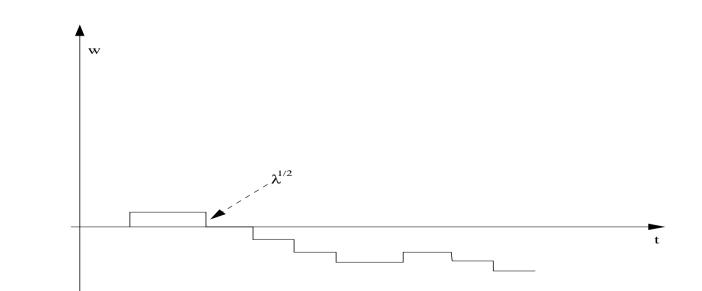
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 dw_{λ} is:

Spatial Continuization

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dw_{λ} is: **Zero-mean.**



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dw_λ is:

- Zero-mean.
- Memoryless.



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dw_{λ} is:

- Zero-mean.
- Memoryless.
- More continuous as $\lambda \to 0$.



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dw_{λ} is:

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- More continuous as $\lambda \rightarrow 0$. What are its statistics?



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dw_{λ} is:

- Zero-mean.
- Memoryless.
- More continuous as $\lambda \to 0$. What are its statistics? Ito's rule says:

$$dw_{\lambda}^{m} = \left(\left(w_{\lambda} + \frac{1}{\sqrt{\lambda}} \right)^{m} - w_{\lambda}^{m} \right) dN^{+} + \left(\left(w_{\lambda} - \frac{1}{\sqrt{\lambda}} \right)^{m} - w_{\lambda}^{m} \right) dN^{-}$$



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Thus (using the binomial expansion)



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Thus (using the binomial expansion)

$$\frac{d}{dt}E[w_{\lambda}^{m}] = \begin{cases} 0 & \text{if } m \text{ is odd} \\ \sum_{i=1}^{m/2-1} \frac{1}{\lambda^{i-1}} {m \choose 2i} E[w_{\lambda}^{m-2i}] & \text{if } m \text{ if even} \end{cases}$$



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Again, notice the recursive calculation of moments.



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Wiener Processes and Brownian Motions

Spatial Continuization

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dw is called a *Brownian motion* (if the limit exists, which it does).



Brownian Motion

Poisson Processes

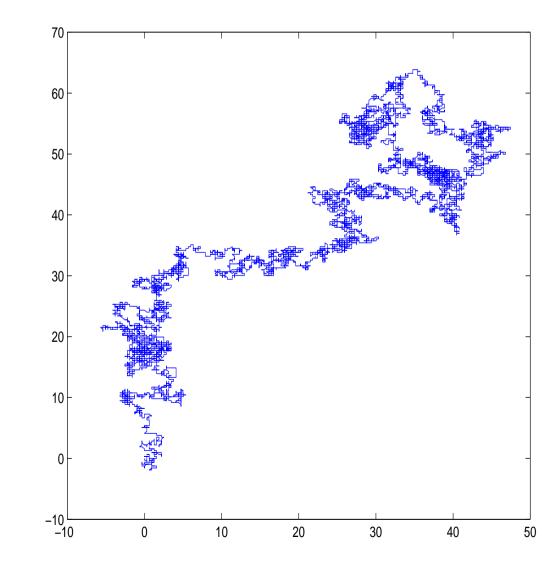
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$$\begin{bmatrix} dx \\ dy \end{bmatrix} = k \begin{bmatrix} dw_1 \\ dw_2 \end{bmatrix}$$

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- dw is self-similar. That is, given $a > 0, \exists b$, such that

$$w(at) \stackrel{d}{=} bw(t) \quad \forall t.$$

In fact $b = a^{1/2}$.



Definition 5 Let

Stochastic Differential Equations

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be interpreted using the limit procedure from above; that is, its solutions are limits of Ito solutions to

 $dx = f(x)dt + \sum_{i} g_i(x)dw_i$

$$dx_{\lambda} = f(x)dt + \sum_{i} \frac{g_{i}(x)}{\sqrt{\lambda}} (dN_{\lambda/2}^{+} - dN_{\lambda/2}^{-})$$



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Example 3 [Ornstein-Uhlenbeck Process]

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$$dx = vdt; dv = -\alpha(\gamma - v)dt + \sigma dw$$



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- γ is the long-term mean interest rate.



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- α is the "pressure to revert to the mean"
- σ is the financial volatility.



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Let ϕ be a function $\mathbb{R}^n \to \mathbb{R}$, and suppose x is governed by a Wiener process SDE as above. $\phi(x)$ is itself a Winer process, but what is its SDE?



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In other words, what is the Ito calculus for Wiener processes?



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It's easy to derive as a limiting version of Poisson version.



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This is a useful process, like dw_{λ} defined above.



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Let ϕ be a function $\mathbb{R}^n \to \mathbb{R}$, and suppose x is governed by a Wiener process SDE as above. $\phi(x)$ is itself a Winer process, but what is its SDE?

Let's start by introducing the process y_{λ} given by:

$$dy_{\lambda} = \frac{1}{\lambda} (dN_{\lambda/2}^{+} + dN_{\lambda/2}^{-}).$$

This is a useful process, like dw_{λ} defined above. Using Ito calculus, one finds $E[y_{\lambda}](t) = t + E[y_{\lambda}](0)$ and



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 $Var[y_{\lambda}](t) = E[(y_{\lambda}(t) - E[y_{\lambda}](t))^{2}] = t/\lambda.$



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$$Var[y_{\lambda}](t) = E[(y_{\lambda}(t) - E[y_{\lambda}](t))^{2}] = t/\lambda.$$

But thus:

$$y(t) \stackrel{d}{=} \lim_{\lambda \to \infty} y_{\lambda} = t,$$

a simple deterministic process!



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So let ϕ be a twice-differential function $\mathbb{R}^n \to \mathbb{R}$, and suppose x is governed by a Wiener process SDE as above.



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So let ϕ be a twice-differential function $\mathbb{R}^n \to \mathbb{R}$, and suppose x is governed by a Wiener process SDE as above.

Using the Ito Rule for ϕ on the process

$$dx_{\lambda} = f(x)dt + \sum_{i} \frac{g_i(x)}{\sqrt{\lambda}} (dN_{\lambda/2}^+ - dN_{\lambda/2}^-),$$

we get



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$$d\phi = \left\langle \frac{d\phi}{dx}, f(x) \right\rangle dt + \sum_{i} \left[\phi(x + \frac{g_i(x)}{\sqrt{\lambda}}) - \phi(x) \right] dN_{\lambda,i}^+ + \sum_{i} \left[\phi(x - \frac{g_i(x)}{\sqrt{\lambda}}) - \phi(x) \right] dN_{\lambda,i}^-$$
(6)



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Now, let's expand ϕ in a Taylor series in x, which gives us



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$$(7)$$



So let's stare at:

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This is just



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$$d\phi = \left\langle \frac{d\phi}{dx}, f(x) \right\rangle dt + \sum_{i} \left\langle \frac{d\phi}{dx}, g_{i}(x) \right\rangle dw_{\lambda} + \frac{1}{2} \sum_{i} \left\langle g_{i}(x), g_{i}(x) \frac{\partial^{2} \phi}{\partial x^{2}} \right\rangle dy_{\lambda} + O(\lambda^{-3/2})$$
(9)



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(9)

So now let's take the limit $\lambda \to \infty$, replacing dw_{λ} with dw, dy_{λ} with dt, and higher terms vanish.



This gives us:

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This is the Ito rule for SDEs.

It is the centerpiece of what's usually known as Ito calculus.



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It is the centerpiece of what's usually known as Ito calculus.

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Now, we have to look into taking expectations.



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```
But recall that E[dw] = 0.
```



Hence

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Hence

$$dE[\phi] = E\left[\left\langle \frac{d\phi}{dx}, f(x) \right\rangle\right] dt + \frac{1}{2} \sum_{i} E\left[\left\langle g_i(x), g_i(x) \frac{\partial^2 \phi}{\partial x^2} \right\rangle\right] dt,$$



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Hence

$$dE[\phi] = E\left[\left\langle \frac{d\phi}{dx}, f(x) \right\rangle\right] dt + \frac{1}{2} \sum_{i} E\left[\left\langle g_i(x), g_i(x) \frac{\partial^2 \phi}{\partial x^2} \right\rangle\right] dt,$$

a deterministic ODE, just like before.

Example 4 Suppose x is given by

dx = -xdt + xdw.

What is the second moment of this process?



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Example 4 Suppose x is given by

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Applying the rule above, we get

 $dE[x^{2}](t) = E[2x(-xdt + xdw)]dt + E[x^{2}]dt = E[-x^{2}dt + 2x^{2}dw] = -E[x^{2}dt + 2x^{2}$



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$$E[x^2](t) = e^{-t}E[x^2](0).$$



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The Langevin equation – simplest stochastic version of Newton's equations:



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$$\frac{d\vec{r}}{dt} = \vec{v}; \quad \frac{d\vec{v}}{dt} = -\zeta\vec{v} + Cdw$$

where ζ is the hydrodynamic friction and C is a constant to be determined.



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$$\zeta = 6\pi\eta a/m$$

where η is viscosity, a is particle radius, and m mass.



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$$E[v^2](t) = v_0^2 e^{-2\zeta t} + \frac{C}{2\zeta} (1 - e^{-2\zeta t}).$$

But stat. mech. tells us that in equilibrium

$$E[v^2] = \frac{3kT}{m}$$



Hence $C = 6kT\zeta/m$.

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Now, we can also use Ito rule to find Var[r](t) – the "mean square displacement":

$$E[(r(t) - E[r](t))^2] = \frac{E[v^2](0)}{\zeta} (1 - e^{-\zeta t})^2 + \frac{3kT}{m\zeta^2} (2\zeta t - 3 + 4e^{-\zeta t} - e^{-2\zeta t})$$



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At equilibrium this becomes

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But this is Einstein's result:

$$D = \frac{kT}{m\zeta} = \frac{kT}{6\pi\eta a}.$$

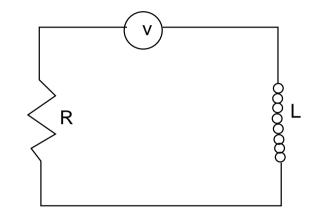


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Consider the resistor-inductor:





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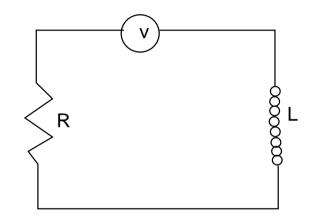
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Consider the resistor-inductor:



What is the expected energy at steady state?

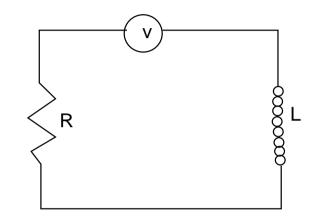


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What is the expected energy at steady state?

Well, energy in a circuit is $\frac{1}{2}Li^2$

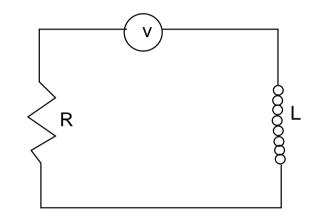


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The Nyquist-Johnson model of current flow is

$$Ldi = -Ridt + \sqrt{2kRT}dw$$



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Let's apply the Ito rule.



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$$di^{2}(t) = -\frac{2R}{L}i^{2}dt + 2\frac{\sqrt{2kRT}}{L}idw + \frac{2kRT}{L^{2}}dt$$



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So at steady state

$$E[i^2] = \frac{kT}{L}.$$

Thus



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Consider the system:

$$dx = (S - GG^T)xdt + \sqrt{\epsilon}Gdw$$

where $\boldsymbol{S}=-\boldsymbol{S}^T$ and

 $rank(G|SG|\dots|S^{n-1}G) = n.$



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The condition on rank means that each mode is correctly couple; *S* being antisymmetric means the system isn't losing energy; and dw is standard *n*-dim brownian motion. ϵ is the strength of the coupling.



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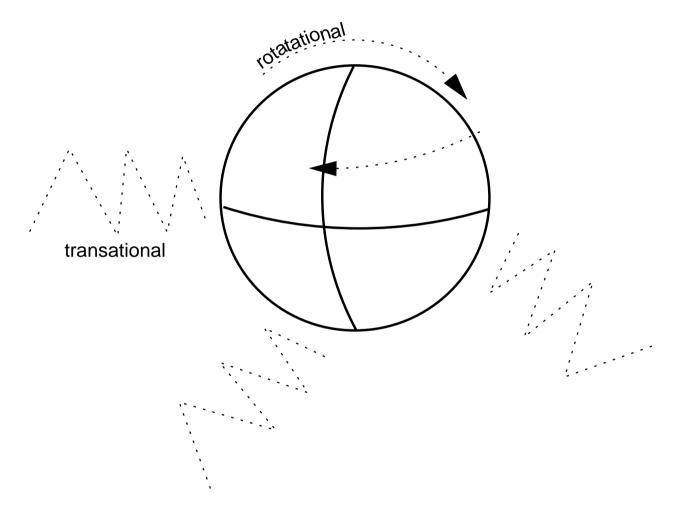
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$$dx = (S - \epsilon G G^T) x dt + \sqrt{\epsilon} G dw$$

where $S = -S^T$ and

$$rank(G|SG|\dots|S^{n-1}G) = n.$$

Theorem 3 [Equipartition Thm.] At thermal equilibrium, every mode possesses the same amount of energy.



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Let's write the Ito equation for $E[xx^T]$.



For the system

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dx = Axdt + Bdw



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the Ito equation for $\phi(x) = xx^T$ is

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 $d(xx^T) = [Axx^T + xx^T A^T]dt + \mathsf{stuff}dw + BB^T dt.$



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On taking expectations,

For the system

$$dE[xx^{T}] = AE[xx^{T}]dt + E[xx^{T}]A^{T}dt + BB^{T}dt.$$



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With $A = S - GG^{T}$ and $B = \sqrt{\epsilon}G$:
$$dE[\Sigma]$$

$$\frac{dE[\Sigma]}{dt} = (S - \epsilon GG^T)E[\Sigma] + E[\Sigma](S - \epsilon GG^T)^T + \epsilon GG^T.$$



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At equilibrium, using $S = -S^T$,



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With $A = S - GG^{T}$ and $B = \sqrt{\epsilon}G$:

 $\frac{dE[\Sigma]}{dt} = (S - \epsilon GG^T)E[\Sigma] + E[\Sigma](S - \epsilon GG^T)^T + \epsilon GG^T.$

At equilibrium, using $S = -S^T$,

 $(S - \epsilon G G^T) E[\Sigma_{\infty}] - E[\Sigma_{\infty}](S + \epsilon G G^T) = -\epsilon G G^T$



Let's stare at it:

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This is a simple linear algebraic equation!



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Hm, let's try $E[\Sigma_{\infty}] = I/2 \dots$

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This is a simple linear algebraic equation!

Hm, let's try $E[\Sigma_{\infty}] = I/2 \dots$

Lo and behold!

Let's stare at it:

$$\frac{1}{2}(S - \epsilon G G^T) - \frac{1}{2}(S + \epsilon G G^T) + \epsilon G G^T = 0$$



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Aside from uniqueness, this is it!



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Hm, let's try $E[\Sigma_{\infty}] = I/2 \dots$

Lo and behold!

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Aside from uniqueness, this is it!

We've shown that all modes get precisely I/2 fraction of total enegy;



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Hm, let's try $E[\Sigma_{\infty}] = I/2 \dots$

Lo and behold!

$$\frac{1}{2}(S - \epsilon G G^T) - \frac{1}{2}(S + \epsilon G G^T) + \epsilon G G^T = 0$$

Aside from uniqueness, this is it!

We've shown that all modes get precisely I/2 fraction of total enegy; Of course, usually there's kT factor.



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Recall the GRAND PRINCIPLE: non-deterministic trajectories generated by statistical differential equations should be governed by a deterministic PDE on the probability density of states.



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$dx = f(x)dt + \sum_{i} g_i(x)dw_i$



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Now, let's let $\rho(x,t)$ be the PDF of x at time t.



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ASSUME: twice differentiable.



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Do the test-function trick: ϕ smooth and with $\phi(x) = 0$ for large |x|.



So, if

A Distributional PDE

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$$dx = f(x)dt + \sum_{i} g_i(x)dw_i,$$

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$$\frac{d}{dt}E[\phi] = \int \left(\left\langle \frac{d\phi}{dx}, f(x) \right\rangle + \frac{1}{2} \sum_{i} \left\langle g_i(x) \frac{d^2\phi}{dx^2}, g_i(x) \right\rangle \right) \rho(x, t) dx$$



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- p. 46/50



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Example 5 Suppose dx = dw.



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$$\frac{\partial \rho}{\partial t} = \frac{1}{2} \frac{\partial^2}{\partial x^2} \rho(x, t).$$



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This is the diffusion equation!



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This is the diffusion equation! It is just as we should expect, since dw is Brownian motion.



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This is the diffusion equation! It is just as we should expect, since dw is Brownian motion. Evidently,

$$\rho(x,t) = \frac{1}{\sqrt{2\pi t}} \int e^{-(x-z)^2/2t} \rho(z,0) dz$$

where $\rho(x,0)$ is the initial distribution — if it is twice differentiable.



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Example 6 Suppose dx = -xdt + dw, i.e there's a drift term.



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In this case,

$$\frac{\partial \rho(x,t)}{\partial t} = \frac{\partial (x\rho)}{\partial x} + \frac{1}{2} \frac{\partial^2 \rho}{\partial x^2}.$$



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This has the solution

$$\rho(x,t) = \int \frac{1}{\sqrt{2\pi s(t)}} e^{-(x-e^{-t}z)^2/2s(t)} \rho(z,0) dz$$



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$$\rho(x,t) = \int \frac{1}{\sqrt{2\pi s(t)}} e^{-(x-e^{-t}z)^2/2s(t)} \rho(z,0) dz$$

where
$$s(t) = \frac{1}{2}(1 - e^{-2t})$$
.



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We want prob. $x \in [-\pi, \pi]$ for t < 1.



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$$\frac{\partial \rho}{\partial t} = \frac{\partial}{\partial x}(x\rho) + \frac{1}{2}\frac{\partial^2 \rho}{\partial x^2}; \rho(-\pi, t) = \rho(\pi, t) = 0.$$



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But this is solvable (using trig fns) to get

$$\rho(x,t) = \sum_{n} p_n(t) \cos(nx)$$

where $\dot{p}_n = (1 - n^2 - 1/n)p_n$.



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Suppose we have the process

$$dx = -xdt + dw; x(0) = 0.$$

We want prob. $x \in [-\pi, \pi]$ for t < 1. *Modify* the process dx so that the original equation holds but has dx = 0 outside of $[-\pi, \pi]$. FP says

$$\frac{\partial \rho}{\partial t} = \frac{\partial}{\partial x}(x\rho) + \frac{1}{2}\frac{\partial^2 \rho}{\partial x^2}; \rho(-\pi, t) = \rho(\pi, t) = 0.$$

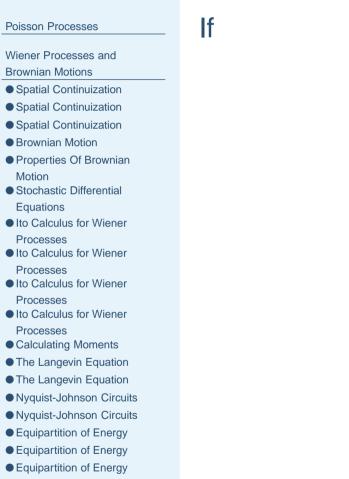
But this is solvable (using trig fns) to get

$$\rho(x,t) = \sum_{n} p_n(t) \cos(nx)$$

where $\dot{p}_n = (1 - n^2 - 1/n)p_n$. NOTICE: prob = $p_0(t) = e^{-t}$.



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so expectations are more complicated. $\Im w$ and dw are the same.



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