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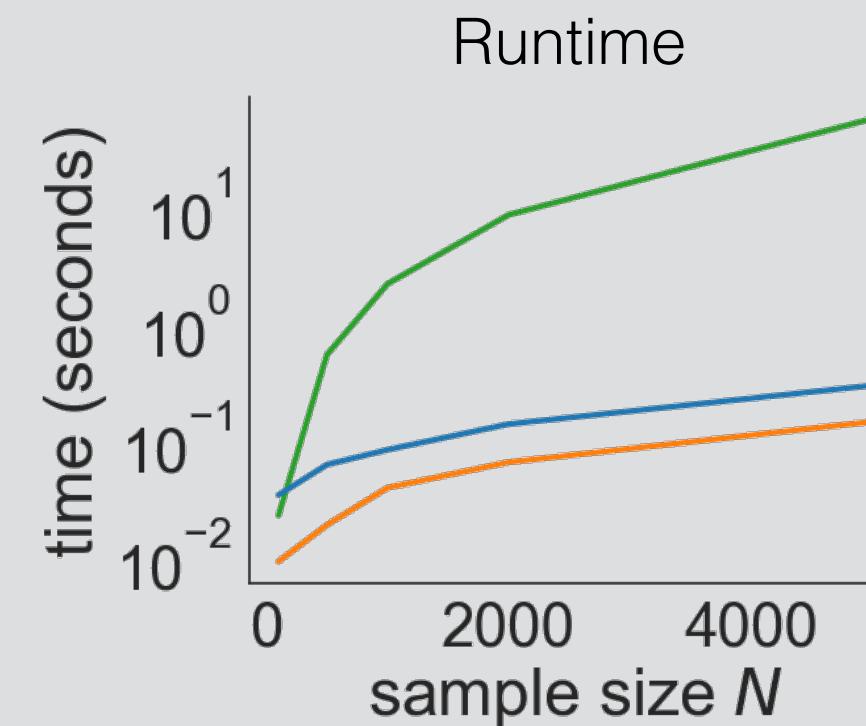
Microsoft Research New England

Summary

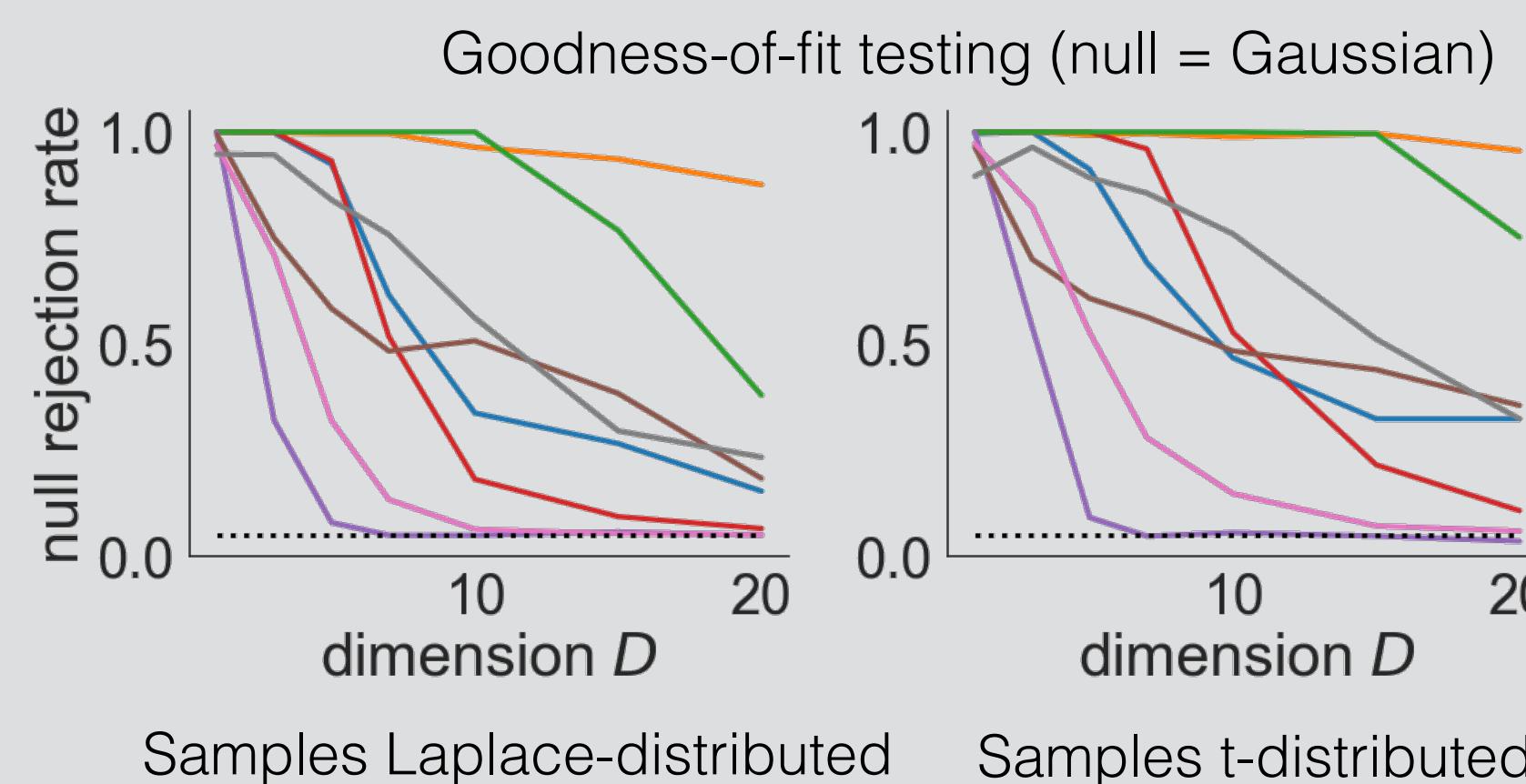
- Computable Stein discrepancies** used for...
 - sampler selection
 - posterior inference
 - goodness-of-fit testing
- But** computation scales **quadratically** with sample size
- We introduce **random feature Stein discrepancies**, which...
 - retain excellent theoretical properties of existing Stein discrepancies
 - are computable in **linear time**



faster...



more powerful...



All the Details

I. Defining the (random) feature Stein discrepancy

$$g_{\Phi,r} \triangleq \left\{ g : \mathbb{R}^D \rightarrow \mathbb{R} \mid g_d(x) = \int \Phi(x, z) \overline{f_d(z)} dz \text{ with } \sum_{d=1}^D \|f_d\|_{L_s}^2 \leq 1 \text{ for } s = \frac{r}{r-1} \right\}.$$

$$\text{Feature Stein discrepancy: } \Phi\text{SD}_{\Phi,r}^2(\mu, P) \triangleq \sup_{g \in G_{\Phi,r}} |\mu(\mathcal{T}g)|^2 = \sum_{d=1}^D \|\mu(\mathcal{T}_d \Phi)\|_{L_s}^2$$

Random feature Stein discrepancy: for $Z_1, \dots, Z_M \stackrel{\text{i.i.d.}}{\sim} \nu$,

$$\text{R}\Phi\text{SD}_{\Phi,r,\nu,M}^2(\mu, P) \triangleq \sum_{d=1}^D \left(M^{-1} \sum_{m=1}^M \nu(Z_m)^{-1} |\mu(\mathcal{T}_d \Phi)(Z_m)|^r \right)^{2/r}$$

II. Assumed form for feature function

Assumption: The base kernel has the form $k(x, y) = A_n(x)\Psi(x - y)A_n(y)$ for $A_n(x) \triangleq A(x - m_n)$ and $m_n \triangleq \mathbb{E}_{X \sim Q_n}[X]$

Assumption: $\Phi(x, z) = A_n(x)F(x - z)$

III. Detecting convergence and non-convergence

Proposition. If the tilted Wasserstein distance

$$\mathcal{W}_{A_n}(Q_n, P) \triangleq \sup_{h \in \mathcal{H}} |Q_n(A_n h) - P(A_n h)| \quad (\mathcal{H} \triangleq \{h : \|\nabla h(x)\|_2 \leq 1, \forall x \in \mathbb{R}^D\})$$

converges to zero, then $\Phi\text{SD}_{\Phi,r}(Q_n, P) \rightarrow 0$ and $\text{R}\Phi\text{SD}_{\Phi,r,\nu_n,M_n}(Q_n, P) \xrightarrow{P} 0$ for any choices of $r \in [1, 2]$, ν_n , and $M_n \geq 1$.

Proposition (KSD-ΦSD inequality). If $k(x, y) = \int \mathcal{F}(\Phi(x, \cdot))(\omega) \overline{\mathcal{F}(\Phi(y, \cdot))(\omega)} \rho(\omega) d\omega$, $r \in [1, 2]$, and $\rho \in L^t$ for $t = r/(2-r)$, then

$$\text{KSD}_k^2(Q_n, P) \leq \|\rho\|_{L_t} \Phi\text{SD}_{\Phi,r}^2(Q_n, P).$$

IV. Constructing convergence-determining RΦSDs

(C, γ) second moments: We say (Φ, r, ν) yields (C, γ) second moments for P and Q_n if $\mathbb{E}[Y_{n,d}^2] \leq C\mathbb{E}[Y_{n,d}]^{2-\gamma}$ for $Y_{n,d} \triangleq |(Q_n \mathcal{T}_d \Phi)(Z)|^r / \nu(Z)$ and $Z \sim \nu$.

Proposition. Suppose (Φ, r, ν) yields (C, γ) second moments for P and Q_n . If the reference KSD_k(Q_n, P) = $\Omega(n^{-1/2})$ then a sample size $M = \Omega(n^{\gamma r/2})$ suffices to have, with high probability,

$$2\|\rho\|_{L_r}^{1/2} \text{R}\Phi\text{SD}_{\Phi,r,\nu,M}(Q_n, P) \geq \text{KSD}_k(Q_n, P).$$

Theorem. Under regularity conditions, there exists a smoothness parameter $\bar{\lambda} \in (1/2, 1]$ and a constant $b \in [0, 1]$ such that the following holds. For any $\xi \in (0, 1-b)$, $c > 0$, and $\alpha > 2(1-\bar{\lambda})$, if $\nu(z) \geq c\Psi(z - m_N)^{\xi r}$, then there exists a constant $C_\alpha > 0$ such that (Φ, r, ν) yields $(C_\alpha, \gamma_\alpha)$ second moments for P and Q_n , where $\gamma_\alpha \triangleq \alpha + (2-\alpha)\xi/(2-b-\xi)$.

Tilted hyperbolic secant kernel:

$$\Psi(x) = \Psi_a^{\text{sech}}(x) \triangleq \prod_{d=1}^D \text{sech}(\sqrt{\frac{\pi}{2}} a x_d) \quad \text{and} \quad A(x) = \prod_{d=1}^D e^{c\sqrt{1+x_d^2}}$$

L^r tilted hyperbolic secant RΦSD:

$$F = \Psi_{2a}^{\text{sech}}, \quad r = 2, \quad \text{and} \quad \nu(z) \propto \Psi_{4a\xi}^{\text{sech}}(z - m_n)$$

Inverse multiquadric kernel: $\Psi_{c,\beta}^{\text{IMQ}}(x) \triangleq (c^2 + \|x\|_2^2)^\beta$ for some $\beta < 0$

L^r IMQ RΦSD:

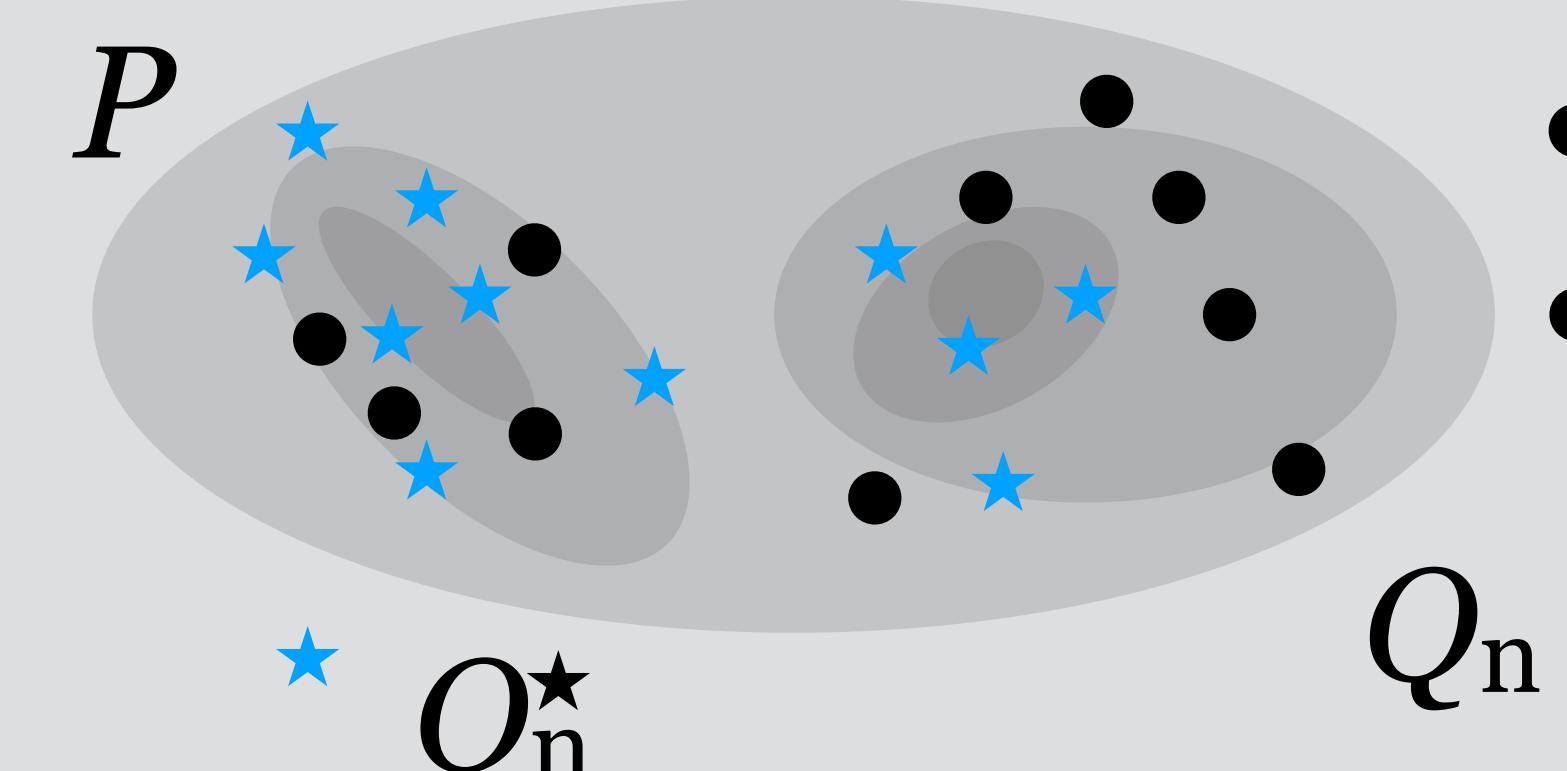
$$F = \Psi_{c',\beta'}^{\text{IMQ}}, \quad r = -D/(2\beta'\xi), \quad \text{and} \quad \nu(z) \propto \Psi_{c',\beta'}^{\text{IMQ}}(z - m_N)^{\xi r},$$

where $c' = \bar{\lambda}c/2$, $\beta' \in [-D/(2\xi), -\beta/(2\xi) - D/(2\xi)]$, and $\xi \in (\underline{\xi}, 1)$

Simplest choice: $\beta' = -D/(2\xi)$ yields $r = 1$.

The Big Picture

I. Motivation



II. Stein discrepancies

$$d_{\mathcal{T}\mathcal{G}}(Q_n, P) = \sup_{g \in \mathcal{G}} |Q_n(\mathcal{T}g) - P(\mathcal{T}g)|$$

Stein operator: $P(\mathcal{T}g) = 0$

III. Desiderata

1. Detect convergence of Q_n to P
2. Detect non-convergence
3. Computationally efficient

IV. Choices for \mathcal{G}

- Uses a kernel function
- Closed-form
- Uses a feature function
- Approximate with importance sampling

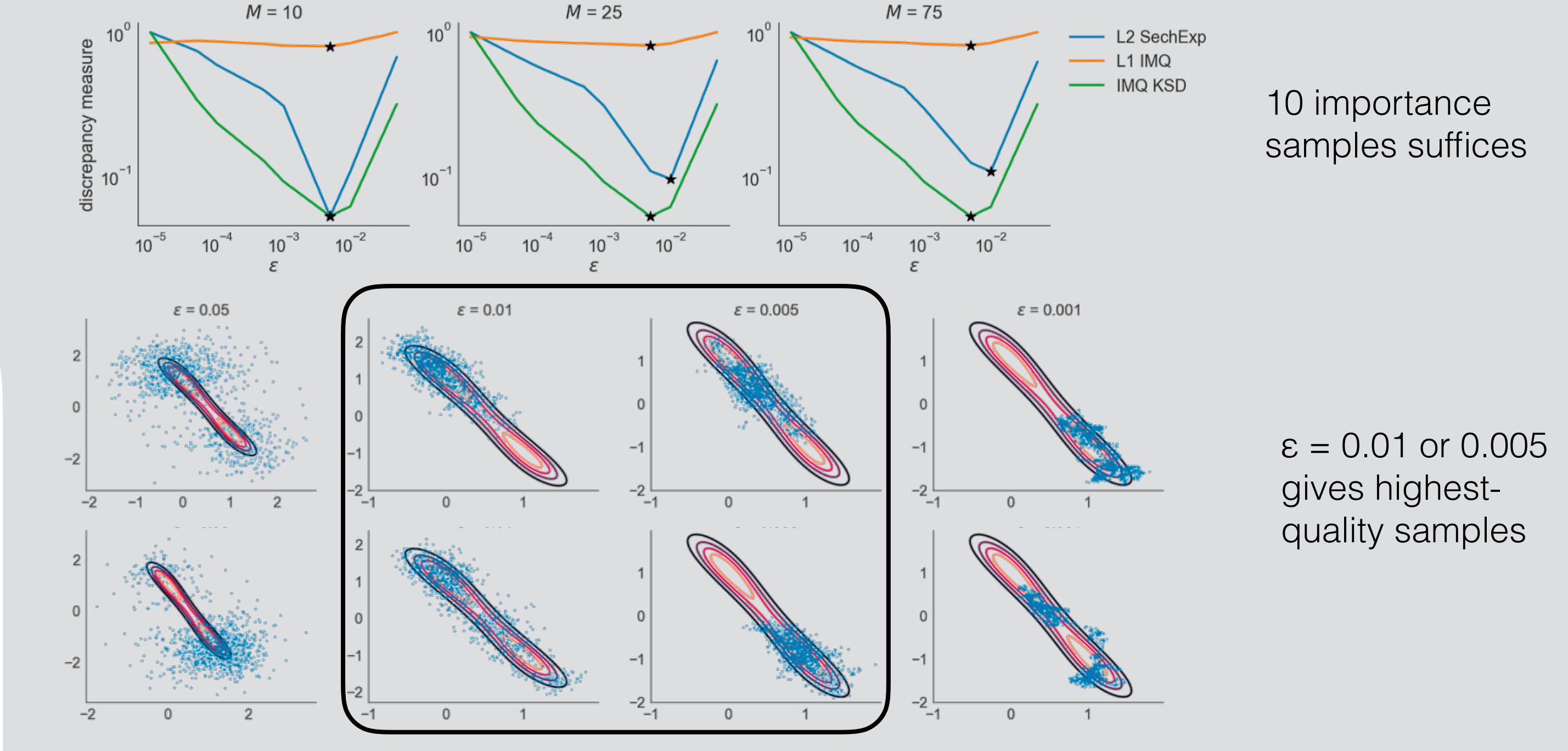
graph Stein discrepancy

- All “smooth” functions
- Have to solve a linear program

V. Linear-time approximations

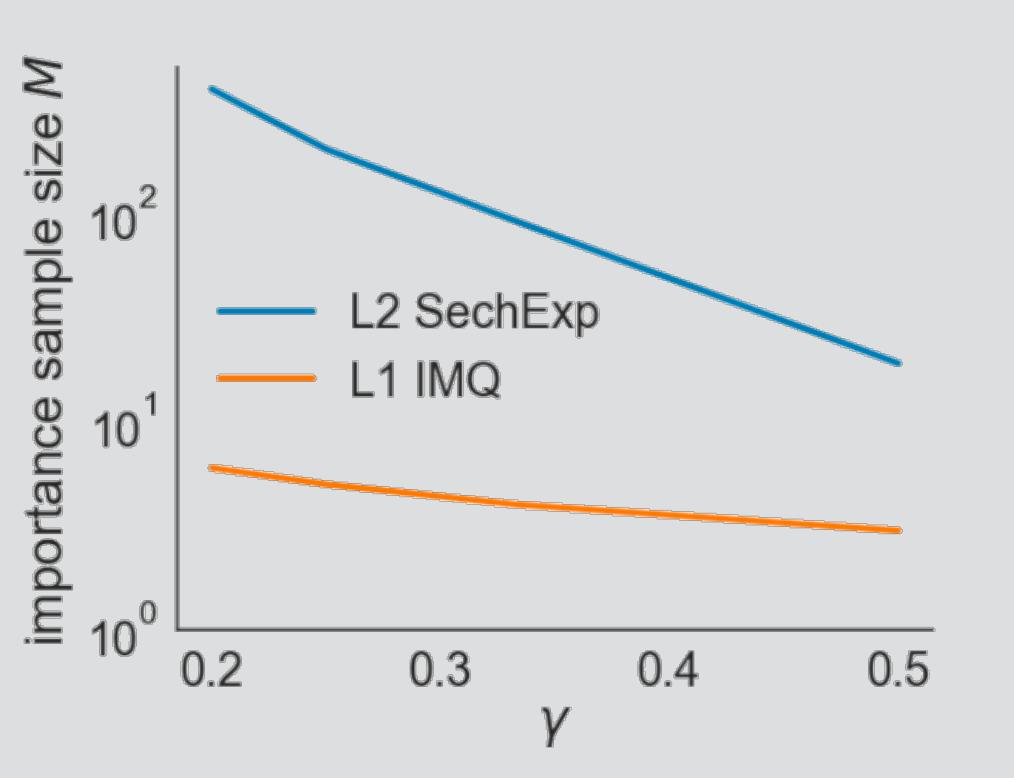
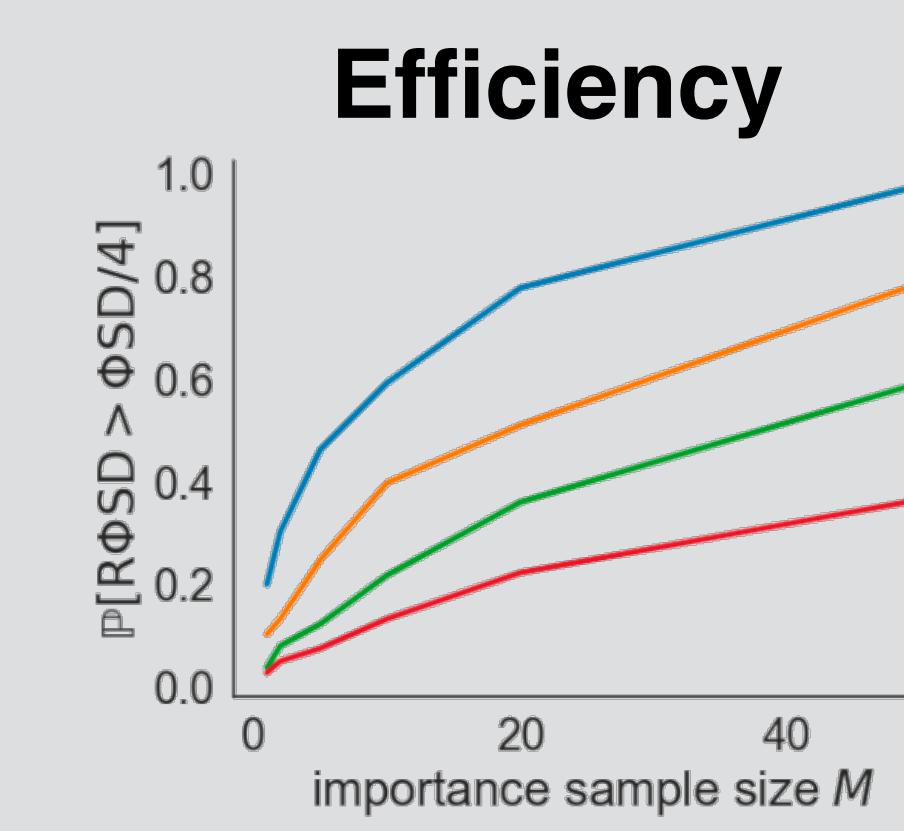
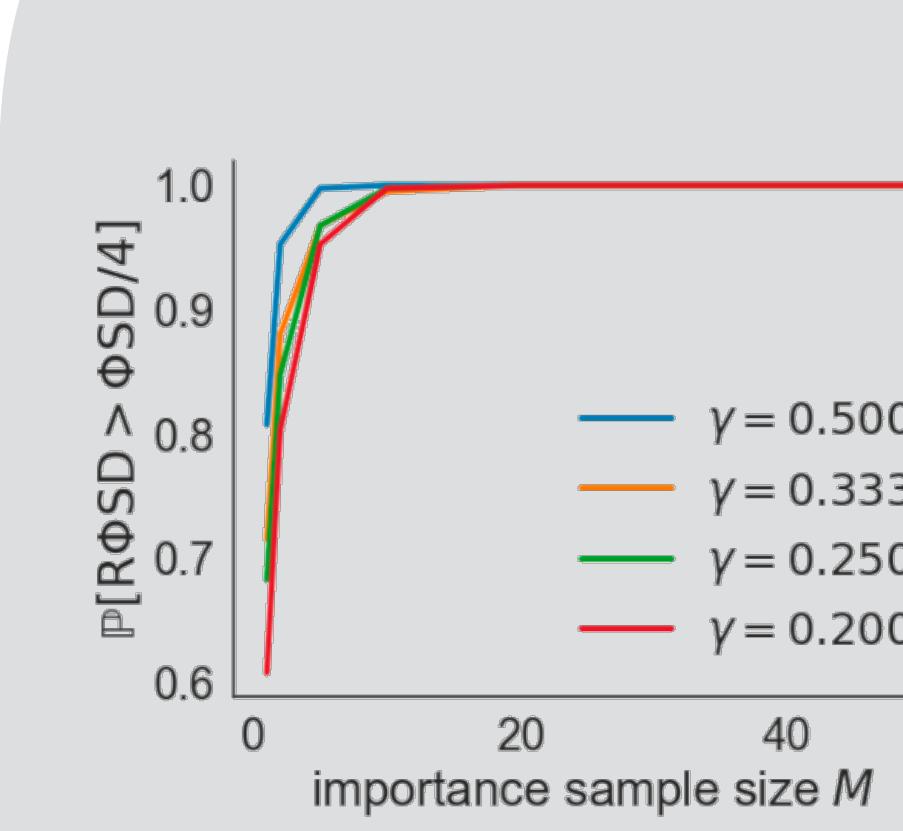
- Not convergence-determining
- Can be convergence-determining
- Provably close to ΦSD when using near-linear number of importance samples [$\Omega(n^\kappa)$ for any $\kappa > 0$]
- Underpowered

VI. Experiment: Selecting SGLD step size

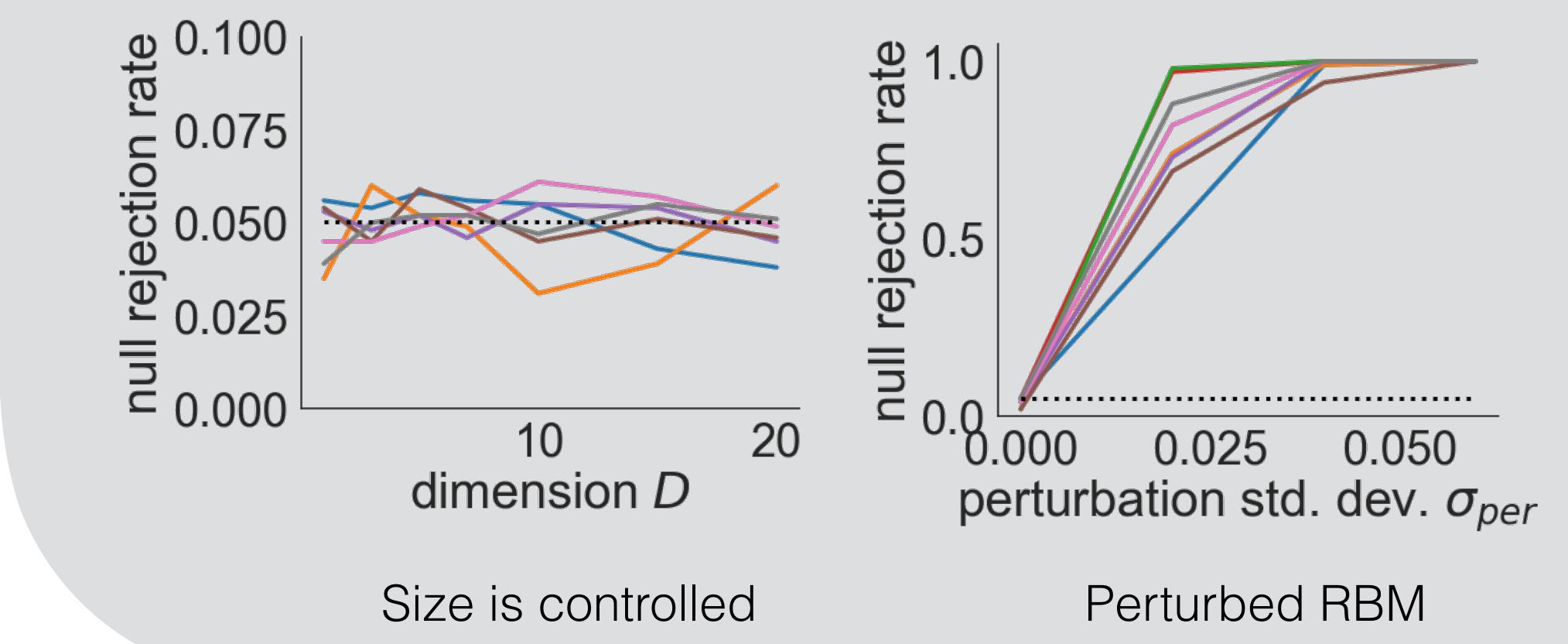


$\epsilon = 0.01$ or 0.005
gives highest-quality samples

More Experiments



Goodness-of-fit testing



Size is controlled

Perturbed RBM