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## Course Overview

Three sections:

- ▶ Monday 2:30pm-3:45pm Wednesday 1:00pm-2:15pm  
Thursday 2:30pm-3:45pm

Goal:

- ▶ Review some basic (or not so basic) concepts in probability and statistics
- ▶ Good preparation for CME 308

Syllabus:

- ▶ Basic probability, including random variables, conditional distribution, moments, concentration inequality
- ▶ Convergence concepts, including three types of convergence, WLLN, CLT, delta method
- ▶ Statistical inference, including fundamental concepts in inference, point estimation, MLE

# Section 1: Basic probability theory

Dangna Li

ICME

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# Outline

## Random Variables and Distributions

## Expectation, Variance and Covariance

- Definitions

- Key properties

## Conditional Expectation and Conditional Variance

- Definitions

- Key properties

## Concentration Inequality

- Markov inequality

- Chebyshev inequality

- Chernoff bound

## Random variables: discrete and continuous

- ▶ For our purposes, random variables will be one of two types: discrete or continuous.
- ▶ A random variable  $X$  is discrete if its set of possible values  $\mathbb{X}$  is finite or countably infinite.
- ▶ A random variable  $X$  is continuous if its possible values form an uncountable set (e.g., some interval on  $\mathbb{R}$ ) and the probability that  $X$  equals any such value exactly is zero.
- ▶ Examples:
  - ▶ Discrete: binomial, geometric, Poisson, and discrete uniform random variables
  - ▶ Continuous: normal, exponential, beta, gamma, chi-squared, Student's t, and continuous uniform random variables

## The probability density (mass) function

- ▶ *pmf*: The probability mass function (pmf) of a discrete random variable  $X$  is a nonnegative function  $f(x) = P(X = x)$ , where  $x$  denotes each possible value that  $X$  can take. It is always true that  $\sum_{x \in \mathbb{X}} f(x) = 1$ .
- ▶ *pdf*: The probability density function (pdf) of a continuous random variable  $X$  is a nonnegative function  $f(x)$  such that  $\int_a^b f(x) dx = P(a \leq X \leq b)$  for any  $a, b \in \mathbb{R}$ . It is always true that  $\int_{-\infty}^{\infty} f(x) dx = 1$ .

# The cumulative distribution function

The cumulative distribution function (cdf) of a random variable  $X$  is  $F(x) = P(X \leq x)$ .

- ▶ If  $X$  is discrete, then  $F(x) = \sum_{t \in \mathbb{X}: t \leq x} f(t)$ , and so the cdf consists of constant sections separated by jump discontinuities.
- ▶ If  $X$  is continuous, then  $F(x) = P(X \leq x) = \int_{-\infty}^x f(t) dt$ , and so the cdf is a continuous function regardless of the continuity of  $f$ .

## Note

The cdf is a more general description of a random variable than the pmf or pdf, since it has a single definition that applies for both discrete and continuous random variables.

## A common mistake in probability

*A random variable is not the same thing as its distribution.*

One might find the following helpful in distinguishing these two concepts

- ▶ A distribution can be thought of as a blueprint for generating r.v.s. Confusing a distribution with that r.v. is like confusing a blueprint of a house with the house itself. *The word is not the thing, the map is not the territory.*
- ▶ It is possible to have two r.v.s which have the same distribution but never equal to each other.

## Conditional probability

The conditional probability of event  $A$  given event  $B$  is defined as

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

### Quiz

Is it true that  $P(A|B)$  always larger than  $P(A)$ ? or less?



## Conditional distribution

If  $X$  and  $Y$  are both discrete random variables with joint probability mass function  $p_{X,Y}(x,y)$ , then the conditional probability mass function of  $X$  given  $Y$  is given by:

$$P(X = x|Y = y) = p_{X|Y}(x|y) := \frac{p_{X,Y}(x,y)}{p_Y(y)}$$

If  $X$  and  $Y$  are both continuous random variables with joint density function  $f_{X,Y}(x,y)$ , the conditional probability density function of  $X$  given  $Y$  is given by:

$$f_{X|Y}(x|y) = \frac{f_{X,Y}(x,y)}{f_Y(y)}$$

## Another common mistake

*A Conditional p.d.f. is not the result of conditioning on a set of probability zero.*

- ▶ The conditional p.d.f.  $f_{X|Y}(x|y)$  of  $X$  given  $Y = y$  is the p.d.f. we would use for  $X$  if we were to learn that  $Y = y$ . So that  $\int_A f_{X|Y}(x|y) = P(X \in A|Y = y)$  for any set  $A \in \mathbb{R}$ .
- ▶ This sounds as if we were conditioning on the event  $Y = y$ , which has zero probability if  $Y$  has a continuous distribution.
- ▶ However, this is not technically correct.  $P(X \in A|Y = y)$  can not even be properly defined using our definition of conditional probability.
- ▶ Actually, the value of  $f_{X|Y}(x|y)$  is a limit:

$$f_{X|Y}(x|y) = \lim_{\epsilon \rightarrow 0} \frac{\partial}{\partial x} P(X \leq x | y - \epsilon < Y < y + \epsilon)$$

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Definitions

Key properties

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Chernoff bound

## Expectation

The expectation  $\mathbb{E}[X]$  of a continuous random variable  $X$  is defined as:

$$\mathbb{E}[X] = \int_{\mathbb{R}} xf(x)dx$$

Similarly, the expectation of a function  $g(\cdot)$  of  $X$  can be computed as (LOTUS):

$$\mathbb{E}[g(X)] = \int_{\mathbb{R}} g(x)f(x)dx$$

### Quiz

Does  $\mathbb{E}[X]$  always exist?

## Variance

The variance  $\text{Var}[X]$  of a random variable  $X$  is defined as

$$\text{Var}[X] = \mathbb{E}[(X - \mathbb{E}[X])^2]$$

An equivalent (and typically easier) formula is

$$\text{Var}[X] = \mathbb{E}[X^2] - (\mathbb{E}[X])^2$$

Similarly, the variance of a function  $g(X)$  of a random variable  $X$  is

$$\text{Var}[g(X)] = \mathbb{E}[g(X)^2] - (\mathbb{E}[g(X)])^2$$

### Quiz

If you want to implement  $\text{Var}[X]$  on a computer, which formula would you chose?

## Covariance

The covariance  $\text{Cov}[X, Y]$  of a random variable  $X$  and a random variable  $Y$  is defined as

$$\text{Cov}[X, Y] = \mathbb{E}[(X - \mathbb{E}[X])(Y - \mathbb{E}[Y])].$$

An equivalent (and typically easier) formula is

$$\text{Cov}[X, Y] = \mathbb{E}[XY] - \mathbb{E}[X]\mathbb{E}[Y]$$

Similarly, the covariance of  $g(X)$  and  $h(Y)$  is

$$\text{Cov}[g(X), h(Y)] = \mathbb{E}[g(X)h(Y)] - \mathbb{E}[g(X)]\mathbb{E}[h(Y)]$$

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## Important properties of expectation

- ▶ *Linearity:*

$$\mathbb{E}[a + bg(X) + ch(Y)] = a + b\mathbb{E}[g(X)] + c\mathbb{E}[h(Y)]$$

In particular, for a sequence of random variables  $\{X_i\}_{i=1}^n$ ,

$$\mathbb{E}\left[\sum_{i=1}^n X_i\right] = \sum_{i=1}^n \mathbb{E}[X_i]$$

- ▶ *The fundamental bridge:*

Let  $\mathbb{I}(\cdot)$  be the indicator function for some random event  $A$ , then

$$\mathbb{E}[\mathbb{I}(A)] = P(A)$$



## Linearity of expectation: An example

A group of  $n$  people play “Secret Santa” as follows: each puts his or her name on a slip of paper in a hat, picks a name randomly from the hat (without replacement), and then buys a gift for that person. Unfortunately, they overlook the possibility of drawing one’s own name, so some may have to buy gifts for themselves.

Assume  $n \geq 2$ .

Find the expected number of pairs of people,  $A$  and  $B$ , such that  $A$  picks  $B$ ’s name and  $B$  picks  $A$ ’s name (where  $A \neq B$  and order doesn’t matter).

## Important properties of variance and covariance

- ▶  $\text{Var} [a + bg(X)] = b^2\text{Var} [g(X)]$
- ▶  $\text{Cov} [a + bg(X), h(Y)] = b\text{Cov} [g(X), h(Y)]$
- ▶ If  $X$  and  $Y$  are independent, then

$$\text{Cov} [g(X), h(Y)] = 0$$

- ▶ If  $X$  and  $Y$  are independent, then

$$\text{Var} [g(X) + h(Y)] = \text{Var} [g(X)] + \text{Var} [h(Y)]$$

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## Conditional expectation

The conditional expectation of a continuous random variable  $X$  given another random variable  $Y$  is defined as:

$$\mathbb{E}[X|Y = y] = \int_{\mathbb{R}} x f_{X|Y}(x|y) dx$$

where  $f_{X|Y}(\cdot|\cdot) = \frac{f_{X,Y}(\cdot,\cdot)}{f_Y(\cdot)}$  is the conditional probability density function of  $X$  given  $Y$ .

### Remarks

- ▶ Notice that computing  $\mathbb{E}[X|Y = y]$  yields (in general) different results for different values of  $y$ . Thus,  $\mathbb{E}[X|Y = y]$  is a function of  $y$  (and not a random variable).
- ▶ If we plug the random variable  $Y$  into this function, which does yield a random variable. This random variable is what we mean when we write  $\mathbb{E}[X|Y]$ .

## Conditional variance

The conditional variance of a continuous random variable  $X$  given another random variable  $Y$  is defined as:

$$\text{Var}[X|Y = y] = \mathbb{E}[X^2|Y = y] - (\mathbb{E}[X|Y = y])^2$$

### Remarks

- ▶ Again, we might consider either  $\text{Var}[X|Y = y]$ , which is a function of  $y$ , or  $\text{Var}[X|Y]$  which is a random variable.

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## Important properties of conditional expectation

- ▶ *Linearity*:  $\mathbb{E}[X_1 + X_2|Y] = \mathbb{E}[X_1|Y] + \mathbb{E}[X_2|Y]$
- ▶ *Independence*: if  $X$  and  $Y$  are independent:  $\mathbb{E}[X|Y] = \mathbb{E}[X]$
- ▶ *Taking out what's known*:

$$\mathbb{E}[h(Y)X|Y] = h(Y)\mathbb{E}[X|Y]$$

- ▶ *Law of Total Expectation*:

$$\mathbb{E}[X] = \mathbb{E}[\mathbb{E}[X|Y]]$$

- ▶ *Law of Total Variance*:

$$\text{Var}[X] = \mathbb{E}[\text{Var}[X|Y]] + \text{Var}[\mathbb{E}[X|Y]]$$

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## Concentration inequality

- ▶ Concentration inequalities provide probability bounds on how a random variable deviates from some value (e.g., its expectation).
- ▶ Most concentration inequalities are about the concentrating behavior of the sum of a sequence of *iid* random variables. But such behavior is shared by other functions of independent random variables as well.
- ▶ As an example, the laws of large numbers(which we will see in the next section) states that sums of independent random variables are, under very mild conditions, close to their expectation with a large probability.

## Markov inequality

Let  $X$  be any *nonnegative* integrable random variable then for all  $a > 0$ ,

$$\mathbb{P}(X \geq a) \leq \frac{\mathbb{E}[X]}{a}.$$

## Example: application of Markov inequality

Consider a biased coin, which lands heads with probability  $1/10$ . Suppose the coin is flipped 200 times consecutively. Give an upper bound on the probability that it lands heads at least 120 times.

### Solution:

The total number of heads is a binomial random variable  $X$ , with parameters  $p = 1/10$  and  $n = 200$ . Thus, the expected number of heads is

$$\mathbb{E}[X] = np = 20$$

By Markov inequality, the probability of at least 120 heads is

$$P(X \geq 120) \leq \frac{\mathbb{E}[X]}{120} = \frac{20}{120} = 1/6$$

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## Chebyshev inequality

Let  $X$  be any integrable random variable then for all  $a > 0$

$$\mathbb{P}(|X - \mathbb{E}[X]| \geq a) \leq \frac{\text{Var}[X]}{a^2}$$

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# Chernoff bound

## Chernoff bound

Suppose we conduct a sequence of  $n$  *iid* Bernoulli trials, with probability  $p$  of landing head. Let  $X$  be the total number of heads in  $n$  trials. Then  $X \sim \text{Bin}(n, p)$  (recall that  $\mathbb{E}[X] = np$ ). Then

$$P(X \geq (1 + \delta)\mathbb{E}[X]) \leq \left( \frac{e^\delta}{(1 + \delta)^{1+\delta}} \right)^{\mathbb{E}[X]}$$

If we let  $\delta = 5$ , one can show that :

$$P(X \geq 6\mathbb{E}[X]) \leq 2^{-(6\mathbb{E}[X])}$$

## Example: application of Chernoff bound

If we apply the Chernoff bound on the previous example, we get:

$$P(X \geq 120) = P(X \geq 6\mathbb{E}[X]) \geq 2^{-6E(X)} = 2^{-(6 \times 20)} = 2^{-120}$$

which is vastly better than the one obtained from Markov inequality.