

ME 106/227 – Vehicle Dynamics and Control
Spring Quarter 2002
TTh 9:30-10:50am
Terman 556

Instructor:

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Office Hours: Monday 2:00-3:30pm
Thursday 1:00-2:30pm

Course Assistants:

Matthew Schwall
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Course Text and Software:

Gillespie, Thomas. Fundamentals of Vehicle Dynamics, SAE, 1992.
Available at the bookstore, through SAE (www.sae.org) or at various online booksellers.
MATLAB Student Edition and control toolbox. Available at the bookstore.

Course Website:

<http://www.stanford.edu/class/me106>

Other References:

Bosch Automotive Handbook, 4th Edition.
Great reference for all sorts of automotive systems, components and engineering principles. More qualitative than quantitative.

Milliken and Milliken, Race Car Vehicle Dynamics.
Good coverage of race car principles and a good deal of information about transient handling. This is an excellent book, but takes a bit of time to navigate because there is simply so much material included.

Dixon, Tires, Suspension and Handling.
Less comprehensive with regards to covering all aspects of vehicle dynamics, but a great resource for suspension design and transient handling response.

Adams, Chassis Engineering.
Often found in bookstores next to titles like *How to Paint Flames*, this is an excellent practical resource from someone who obviously understands the underlying physics.

All of these are available through SAE (www.sae.org) and other online booksellers.

The automotive section of How Stuff Works at www.howstuffworks.com

Tom and Ray Magliozzi online at www.cars.com

The Garage section at www.nascar.com.

Prerequisites:

You should have a basic understanding of dynamic systems comparable to ME161 or E104, but no experience with control theory (E105, E205,...) is assumed. This background is assumed to include familiarity with Laplace Transforms, the basic characteristic responses in mass-spring-damper systems (overdamped, underdamped and critically damped) and frequency response (gain and phase of a linear system at any frequency, Bode plots,...). If any of these sound unfamiliar, there will be two extra sessions held to review Laplace transforms and frequency responses. The two extra sessions will be held on Monday evenings prior to the material being used in class:

Laplace Transform review:	Monday, April 22	7:00pm	Terman 556
Frequency Response review:	Monday, May 13	7:00pm	Terman 556

All of the assignments will require the use of MATLAB. Familiarity with this software (or willingness to pick it up and learn) is a prerequisite for the class. To avoid overly tedious programming, some subroutines in the form of MATLAB code will be provided to you.

Course Objectives:

During this quarter, you should:

- (1) Develop an understanding of the fundamental dynamic considerations that influence the design of ground vehicles and vehicle control systems.
- (2) Use the example of the automobile to investigate modeling dynamic systems at various levels of abstraction.
- (3) Explore the tradeoffs between completeness and simplicity when choosing an appropriate level of modeling abstraction.

Course Policies:

- (1) Lectures are an integral part of the class. There is no textbook available that captures the full range of class topics, so some information may only be available in lecture. Attendance and participation during the lectures are expected.
- (2) Reading assignments should be completed (skimming is fine) prior to the class period for which they are assigned.
- (3) Assignments are due on Tuesdays. Assignments turned in the following Wednesday will be docked 10% for one day late. Assignments turned in at the beginning of class on Thursday will be docked 30% for two days late. No assignments will be accepted after the beginning of class on Thursday since we intend to hand back graded assignments in class.
- (4) No last minute extensions will be granted. If you need an extension on an assignment you should request it at least a week in advance.

Assignments and Grading:

There will be four contributors to the final grade given in the course: problem sets, a midterm exam, a final group project and class participation. The breakdown of grading is as follows:

Problem Sets:	50%
Midterm:	25%
Final Project:	20%
Class Participation:	5%

Reading Assignments:

Reading assignments from the textbook are intended to provide an introduction to vehicle dynamics and quasi-static analysis techniques. In addition, there may be technical papers assigned over the course of the quarter. These papers will demonstrate some of the more detailed analytical techniques employed in vehicle research and development and some of the control algorithms implemented in production systems. Papers assigned as reading will be placed on reserve in the Engineering library. Material in the reading assignments is fair game for problem sets or the midterm.

Problem Sets:

The problem sets are designed to integrate and expand upon the analytical techniques presented in lecture. Most problem sets will require the use of software analysis tools in order to obtain a solution. ***You are strongly encouraged to begin (or at least assess) the problem sets soon after they are handed out.*** Many of the concepts in the class are best understood when you can work with a physical or mathematical model. Most of the problem sets require you to develop such models. If you develop the model early, the rest of the problem set should be quite easy; waiting until the last minute, however, can be a recipe for disaster. The assignments are individual assignments but several require the use of laboratory data obtained in groups. For all assignments, you are encouraged to collaborate with others in the class to develop and debug analysis necessary for the problems – the answers to any open-ended problems should be your own work, however. The tentative problem set topics are:

- Assignment 1: A closer look at simple handling models
- Assignment 2: Steady handling and race car set-up
- Assignment 3: Vehicle parameter estimation and suspension design
- Assignment 4: Transient handling and design for performance
- Assignment 5: Nonlinear effects and simulation
- Assignment 6: Ride quality and frequency response
- Assignment 7: Ride quality II

Midterm Exam:

The midterm will cover material from the first six weeks of the class including tire modeling, steady-state handling, transient handling, suspension design and stability control.

Final Project:

In lieu of a final exam, the course requires a final analysis project that builds upon the concepts covered in lecture, the text and previous assignments. This is a group project and involves the analysis and design of a vehicle using the various software tools built up in the class assignments. Further information on the final project will be handed out later in the quarter.

ME 106D/227D:

This year the in-vehicle lab section will be a required part of the course. Labs will be held on Saturday mornings and early afternoons to ensure ample parking lot space for maneuvers and will be performed in teams of three. There will be a mandatory pre-lab session from 2:00-3:00pm on Fridays immediately preceding Saturdays when labs are held. Attendance at the three lab sessions and pre-labs is mandatory to receive credit for the class and the lab.