

February 2, 2012

ENGR110/210

Perspectives in Assistive Technology



David L. Jaffe, MS



Professor Drew Nelson



John Thiemer

Questions?



Whats for dinner?



Projects

- Cautions
 - How much to bite off?
 - Project goal
 - Moving the process forward
- Think about
 - Mid-term presentation and report (in 2 weeks)
 - Continue to send updates, including photos

Tuesday



Peter W. Axelson, MSME, ATP, RET

**Designing Beyond the Norm to Meet the
Needs of All People**

Today



Allison M. Okamura, PhD and
David L. Jaffe, MS



Rehabilitation Robotics

Assistive Robotics

Dave Jaffe

Agenda

- What is a robot?
- What is an assistive robot?
- What is a medical therapy robot?
- Early assistive robots
- Assistive robots at VA
- Other assistive robots
- Robots in the news
- Summary

- Short break

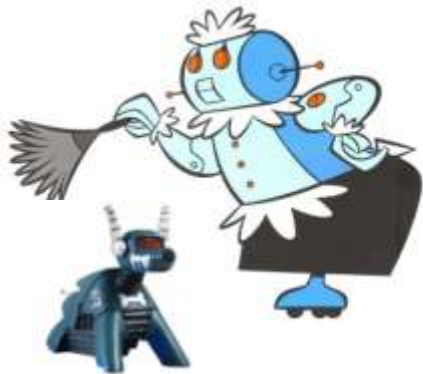
- Movement Therapy Robots – Prof Allison M. Okamura

- Final questions

What is a robot?

What image comes to mind when you think of a robot?

Some images of robots



klaatu barada nikto

What defines a robot?

Which of these are required characteristics of a robot?

1. Ability to move – legs, wheels, fly, burrow, swim, orbit
2. Ability to sense – eyes, ears, other inputs
3. Ability to manipulate – arms, hands, fingers
4. Ability to mimic – appearance, human tasks
5. Ability to communicate – expressions, sounds, voice, digital, analog
6. Ability to think – brain, mechanical mechanism, computer, self-awareness
7. Ability to operate – remotely, program control, autonomously
8. Ability to react and respond to different situations
9. Ability to do something useful

Can a software program be considered a robot?

Is Siri a robot?

What defines a robot?

Definition from Wikipedia:

A **robot** is a mechanical or virtual intelligent agent that can perform tasks automatically or with guidance, typically by remote control. In practice a robot is usually an electro-mechanical machine that is guided by computer and electronic programming. Robots can be autonomous, semi-autonomous, or remotely controlled. Robots range from humanoids such as ASIMO and TOPIO to nano robots, swarm robots, industrial robots, military robots, mobile, and servicing robots. By mimicking a lifelike appearance or automating movements, a robot may convey a sense that it has intent or agency of its own.

What is assistive robotics?

VDL's definition: An **assistive robot** performs a physical task for the well-being of a person with a disability. The task is embedded in the context of normal human activities of daily living (ADLs) and would otherwise have to be performed by an attendant. The person with the disability controls the functioning of the robot. (2005)

Dave's definition: An **assistive** robot is a device that can sense, process sensory information, and perform actions that benefit people with disabilities and seniors.

What is a movement therapy robot?

Dave's definition: A **movement therapy robot** is one that is specifically designed to provide a diagnostic (measurement and assessment) or therapeutic (improvement of function) benefit.

Kinds of assistive robotics

Fixed-base robots

Workstation

- vocational, ADL

Bedside

- food, medicine, health

Mobile robots

Autonomous

- fetch & carry
- mobility support

Wheelchair

- autonomous navigation
- manipulator arm

Users of assistive robotics

	Prevalence	Potential users
Spinal cord injury:	90,000	90,000
Cerebral palsy:	500,000	50,000
Rheumatoid arthritis:	2,100,000	20,000
Other:		
Frail elderly		
ALS, MD, MS, stroke, temporary impairment, amputees, etc.		

[Stanger CA (1996) Cawley MF, Demographics of rehabilitation robotics users. *Technology and Disability* 5, pp. 125-137.]

Early assistive robots



Rancho Golden Arm

Early assistive robots



JHU / APL Robotic Workstation

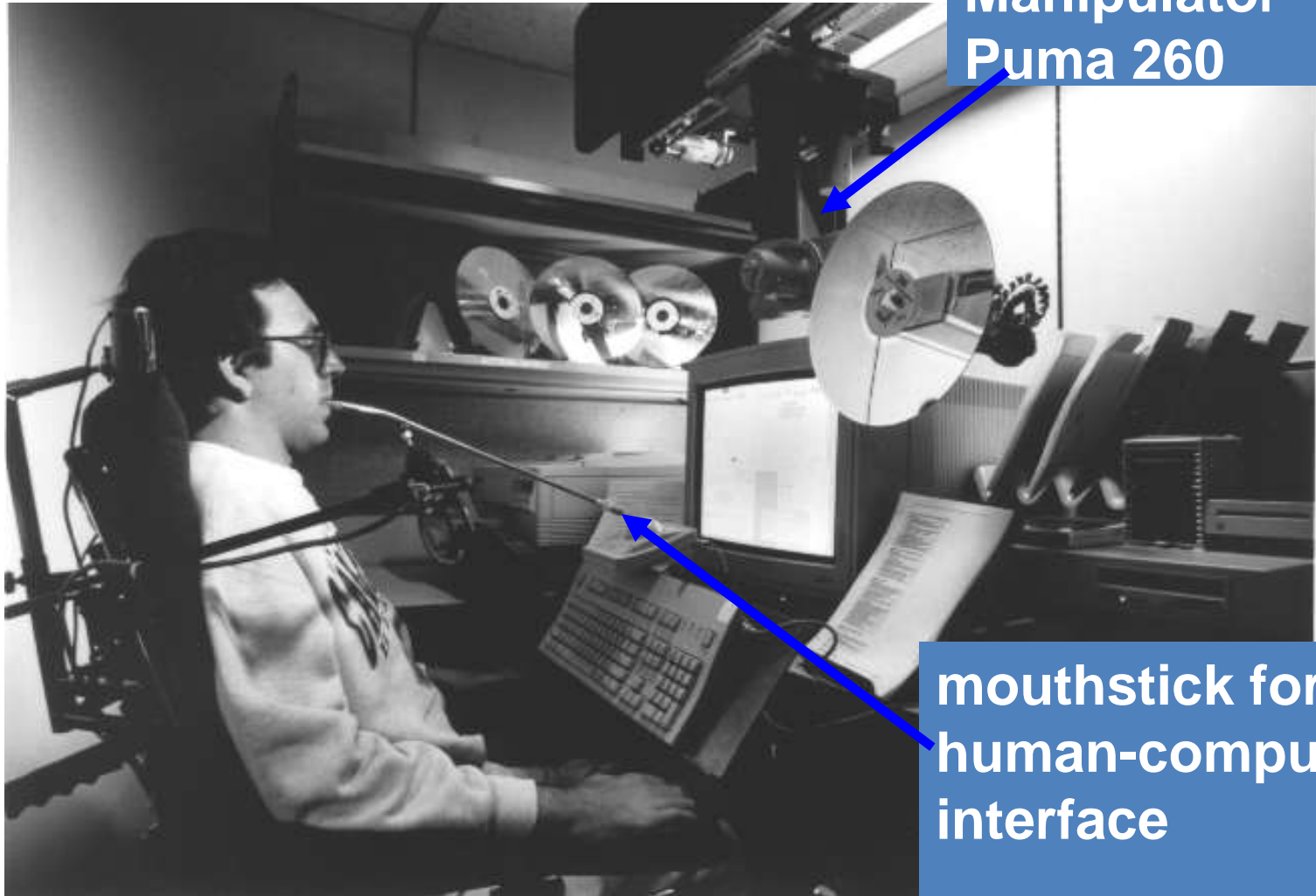
Assistive robotics at VA

VA / Stanford MoVar



DeVAR & ProVAR

Desktop Vocational Assistant Robot



Manipulator
Puma 260

mouthstick for
human-computer
interface

DeVAR & ProVAR

Desktop Vocational Assistant Robot



DeVAR & ProVAR

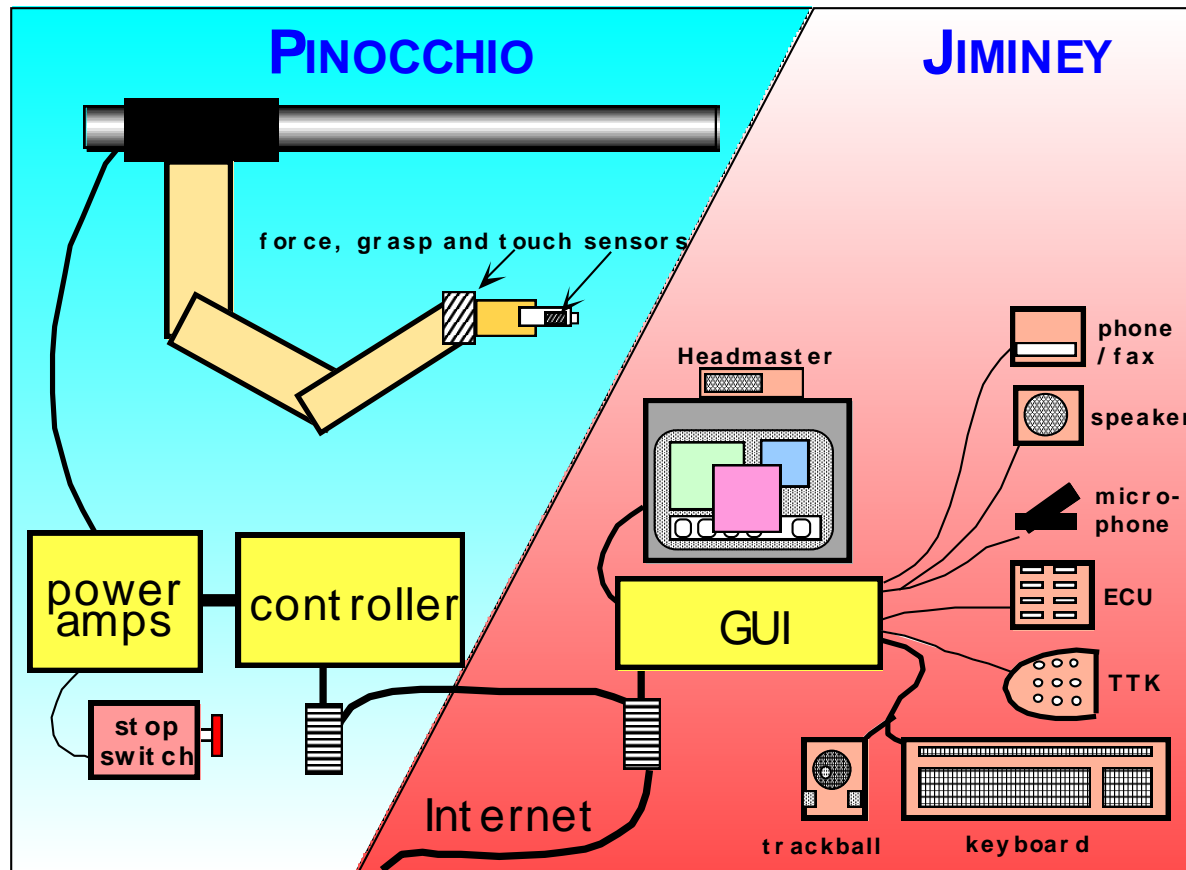
Desktop Vocational Assistant Robot



Dual-Character Interface

Joe Wagner, PhD candidate

- Pinocchio: simple-minded robot arm
- Jiminey: helpful consultant / coach



ProVAR Interface

The screenshot displays the ProVAR interface within a Netscape browser window. The browser's address bar shows the file path: `file:///E:/provar/ui23/provar.html`. The main window contains a 3D simulation of a robotic arm in a virtual environment. Below the simulation is a control panel with buttons for "Call Pinocchio", "Show menu window", "Hide menu window", and "Record Location".

Overlaid on the right is the "Jiminey" application window, which has a menu bar with "Change", "Put", "Get", "Primitives", "Call", and "Help". The "Get" menu is open, showing options: "Video Tape", "Paper", and "Computer Media". The "Video Tape" submenu is also open, listing "from Slot 1", "from Slot 2", "from Slot 3", "from Slot 4", and "from Video Player". A mouse cursor is pointing at "from Video Player".

The "Tasks" list in the Jiminey window includes:

- Get Video Tape from Slot #1
- Put Video Tape into VCR
- Task2
- Task3
- Task4
- Task5

Below the tasks list is an "Edit Step: Go to slot 1" section with a table of joint positions:

Label8	Track0	Waist1	Shoulde...	Elbow3	Foreware4	Wrist5	Hand6	Gripper7
Go to sl...	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0

At the bottom of the Jiminey window, there is a "Pinocchio Action" section with three buttons: "Go" (green), "One Step" (yellow), and "STOP" (red). Below these buttons is a status bar that reads "Unsigned Java Applet Window".

Other assistive robotics

Handy-1

- CP users
- Single-switch input
- Modules for:
 - Feeding
 - Cosmetics
 - Face-hygiene



[Link](#)

MANUS Wheelchair Robot

- 5-dof, belt-drives
- Grounded actuators
- Keypad / display input



Raptor Wheelchair Robot

- 4-dof
- Motors in links
- No encoders
- Joystick control
- Over-torque clutches
- Commercialized 2001
- Applied Resources, Corp.



Weston Wheelchair Arm

- R&D at University of Bath, UK
- Inexpensive arm
- Also designed a workstation version



[Link](#)

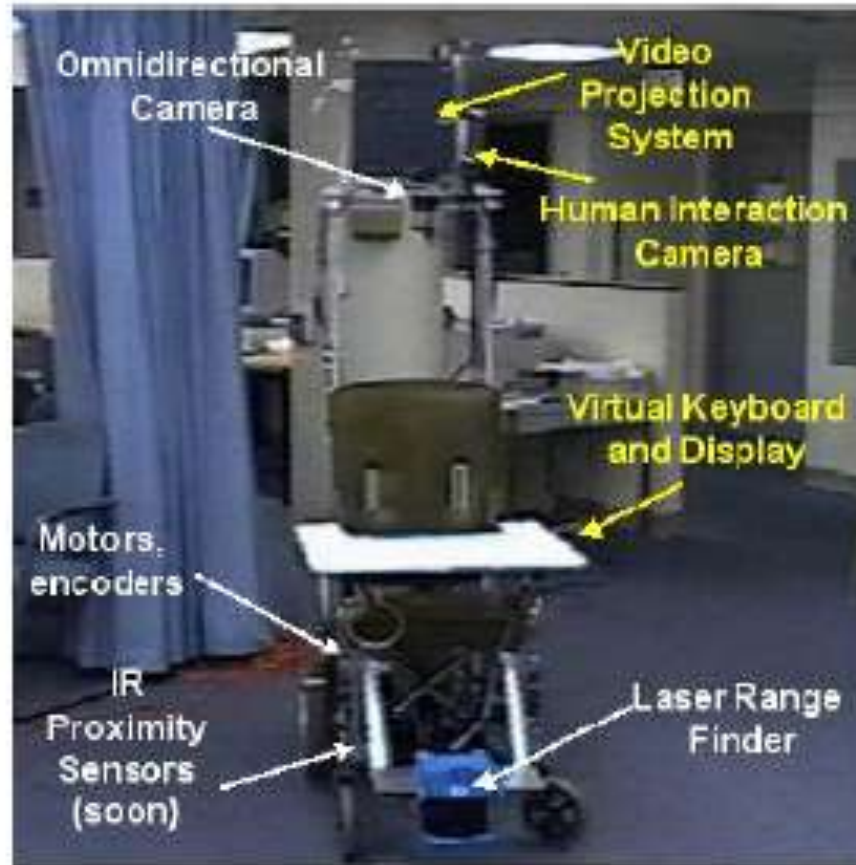
Hephaestus Navigation

- Builds on NavChair, University of Minnesota
- Ultrasonic, IR, and tactile sensors
- Add-on kit for any wheelchair



[Link](#)

SmartChair Navigation



[Link](#)

Wheelesley

- Eye-tracking (EOG) interface
- Single-switch scanning input
- Vision system navigation
- 12 infrared sensors
- 4 ultrasonic range sensors
- 2 shaft encoders
- Instrumented front bumper



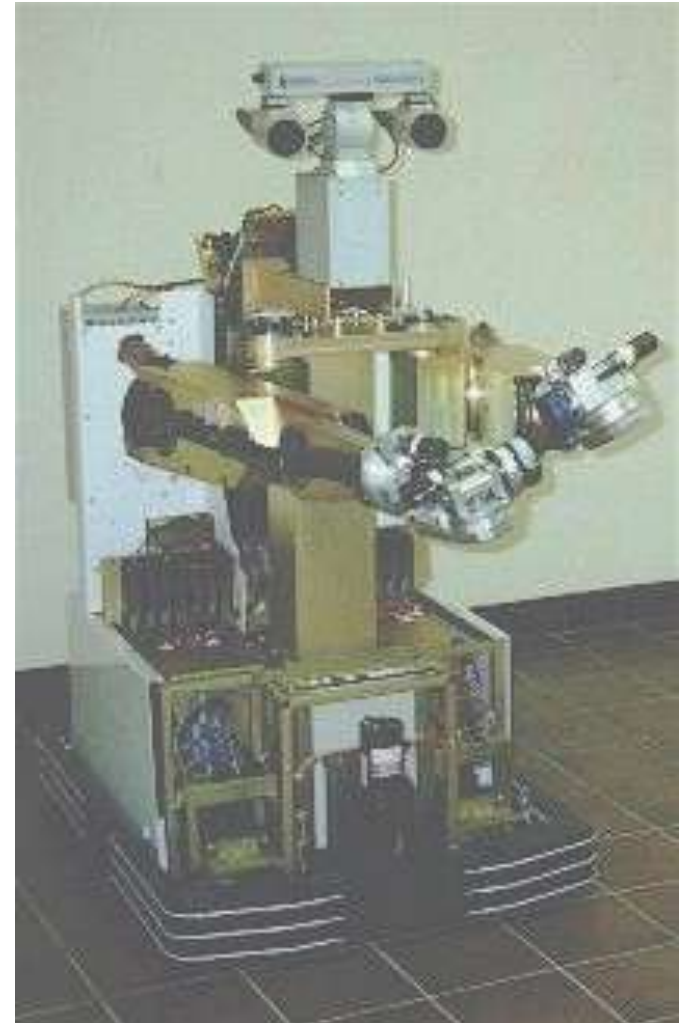
[Link](#)

Helpmate - Isaac

- Based on R&D platform “Labmate”
- Voice controlled
- Walking assist for elderly
- Fetch & carry robot in the home



[Link](#)



[Link](#)

Walking Assist Robot

- Guido (PamAid)
- Wheels, not motorized
- Steering motorized
- Range sensors in front



[Link](#)

Robots in the news



PR2 Can Now Fetch You a Sandwich from Subway

[Link](#)



Willow Garage's PR2 robot can fold clothes, set a table, and bake cookies.

[Link](#)



eLEGS: Wearable, Artificially Intelligent, Bionic Device

[Link](#)



Exoskeleton Technology Helps Paraplegic Student Walk Again

[Link](#)



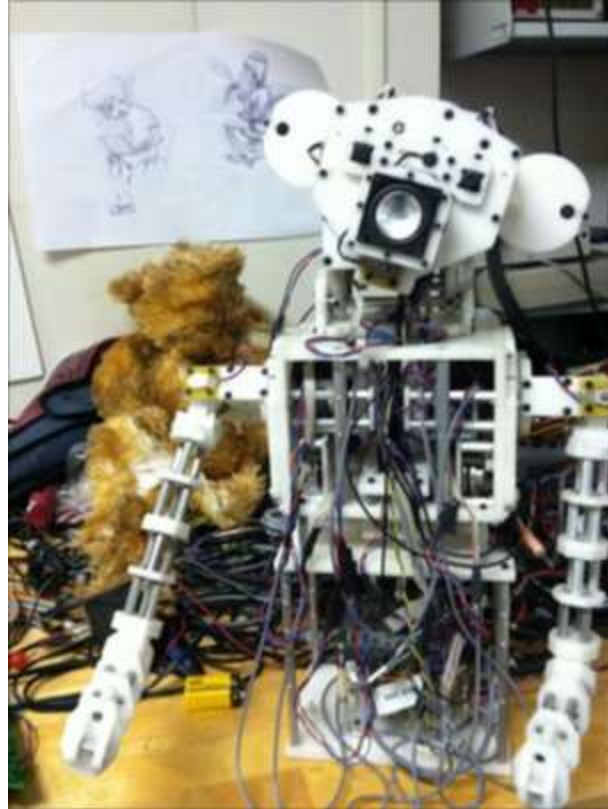
Robosoldier

[Link](#)



Glove that Vibrates Fingertip Could Improve One's Sense of Touch

[Link](#)



Ready for the robot revolution?

[Link](#)



Ready for the robot revolution?

[Link](#)



Panasonic's Hospi-Rimo robot tends to patients

[Link](#)



Hair-washing robot leaves your locks silky-smooth

[Link](#)



Bed Mode



Shown with the back rest up



The wheelchair separated from the bed

Panasonic's Robotic Bed transforms into wheelchair

[Link](#)



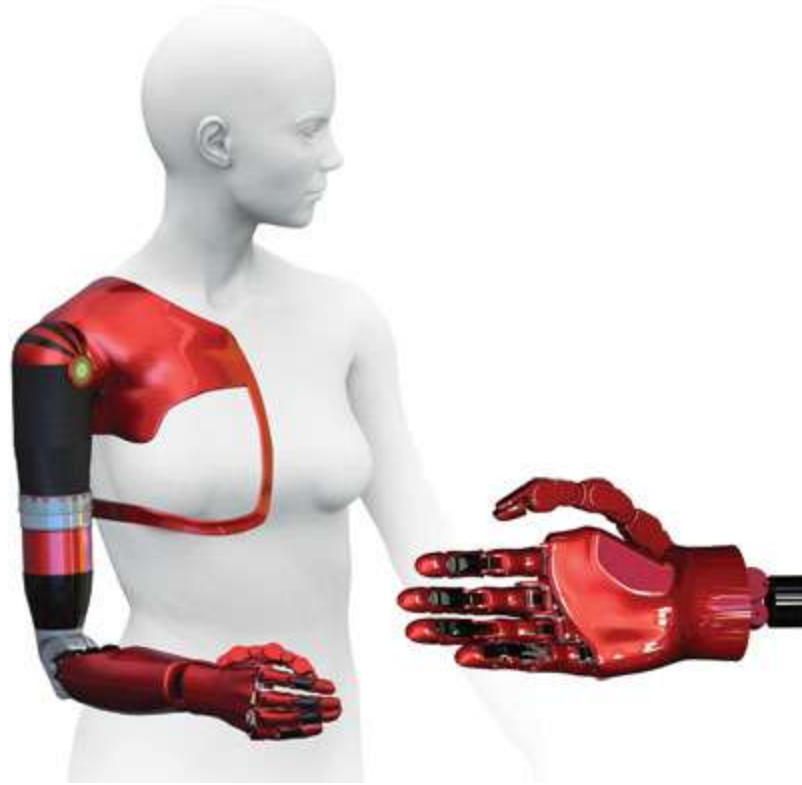
Development of a Powered Transfemoral Prosthesis

[Link](#)



The Revolution Will Be Prosthetized - DARPA

[Link](#)



The Revolution Will Be Prosthetized – JHU/APL

[Link](#)



Giant teddy bear robot can pick you off the floor

[Link](#)



Babyloid: Therapeutic Baby Robot for the Elderly

[Link](#)



Robot Helps Quadriplegic Scratch an Itch for the First Time in a Decade

[Link](#)



Humanoid Robots: STEM Vehicles Today, Classroom Assistants Tomorrow

[Link](#)

Economics of assistive robotics

A \$50,000 assistive robot can be amortized over three years if it replaces attendant care at \$6 per hour and is used for two 4-hour shifts per day. (2005)

[Hammel J and Symons J (1993) Evaluating reasonable accommodation in the workplace: A team approach. *Work*, 3(4): pp. 12-20.]

The running costs of installation, training, customization, maintenance, and repair will be the dominant factor in determining overall cost, **not the cost of the manipulator** itself.

Robotics Research Issues

- Importance of Multi-Disciplinary Approach
 - Engineering design with only able-bodied subjects can lead to unexpected results and a system not appropriate to the intended user population of persons with a disability.
 - Early integration with medical/rehab team shortens development time.

Robotics Research Issues

- Bring all professionals in at the beginning (actually, **before** the beginning) to instill sense of ownership
 - PIs from Medical and Engineering domains
 - Therapists as part of staffing of Center
 - Ergonomics experts on-call
 - People with disabilities as an integral part of project
- Ownership = championing of idea
- Conference presentations
- Publication in both clinical & engineering journals

Future of Robots in Health Care

- Economics of care
 - Insistence on ‘best possible care’
 - Consumer-centric healthcare
 - Rehab being pushed into the home setting earlier
- Demographics of disability
 - Aging society
 - Lack of caregivers
 - Better medical care means longer lives and more improvement in function

Future of Robots in Health Care

- Reduction in cost due to mainstreaming of robot technology
- Integration of advanced sensing, actuation, and embedded computer technology in household appliances

Summary

- Robots come in many forms
- Robots can be used in many ways to help people with disabilities
- Lots of research being done, resulting in prototypes
- Few assistive robots in common use today
- High cost and uncertain benefit are major barriers to their widespread adoption

Short Break

