

# Transform coding - topics

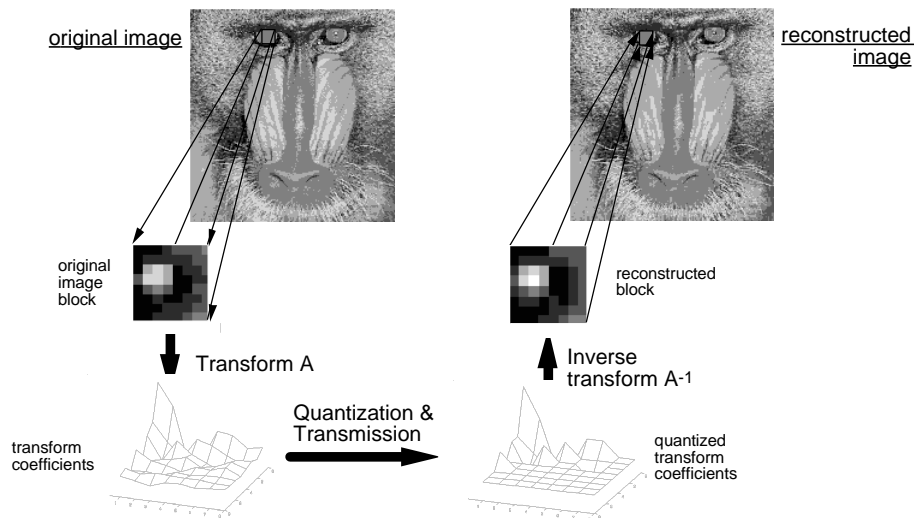
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- Principle of block-wise transform coding
- Properties of orthonormal transforms
- Discrete cosine transform (DCT)
- Bit allocation for transform coefficients
- Threshold coding
- Typical coding artifacts
- Fast implementation of the DCT



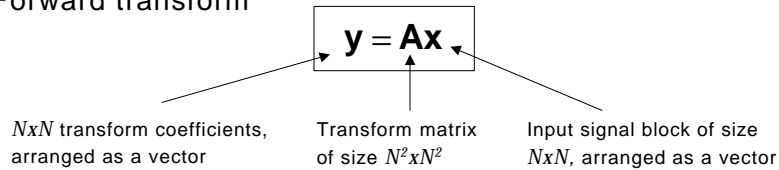
## Principle of block-wise transform coding

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## Properties of orthonormal transforms

- Forward transform



- Inverse transform

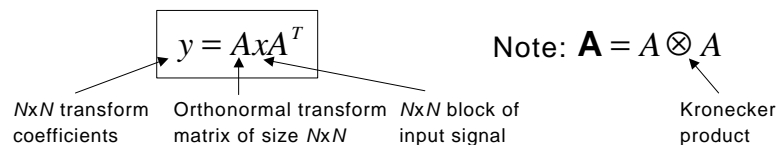
$$\mathbf{x} = \mathbf{A}^{-1}\mathbf{y} = \mathbf{A}^T\mathbf{y}$$

- Linearity:  $\mathbf{X}$  is represented as linear combination of “basis functions”.
- Parseval’s Theorem holds: transform is a rotation of the signal vector around the origin of an  $N^2$ -dimensional vector space.



## Separable orthonormal transforms, I

- An orthonormal transform is separable, if the transform of a signal block of size  $N \times N$  can be expressed by



- The inverse transform is

$$\mathbf{x} = \mathbf{A}^T\mathbf{y}\mathbf{A}$$

- Great practical importance: The transform requires 2 matrix multiplications of size  $N \times N$  instead one multiplication of a vector of size  $1 \times N^2$  with a matrix of size  $N^2 \times N^2$

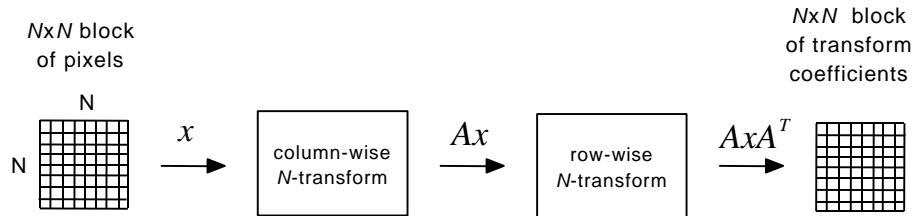
➔ Reduction of the complexity from  $O(N^4)$  to  $O(N^3)$



## Separable orthonormal transforms, II

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- 2-d transform realized by 2 one-dimensional transforms (along rows and columns of the signal block)



## Criteria for the selection of a particular transform

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- Decorrelation, energy concentration (e.g., KLT, DCT, . . .)
- Visually pleasant basis functions (e.g., pseudo-random-noise, m-sequences, lapped transforms)
- Low complexity of computation

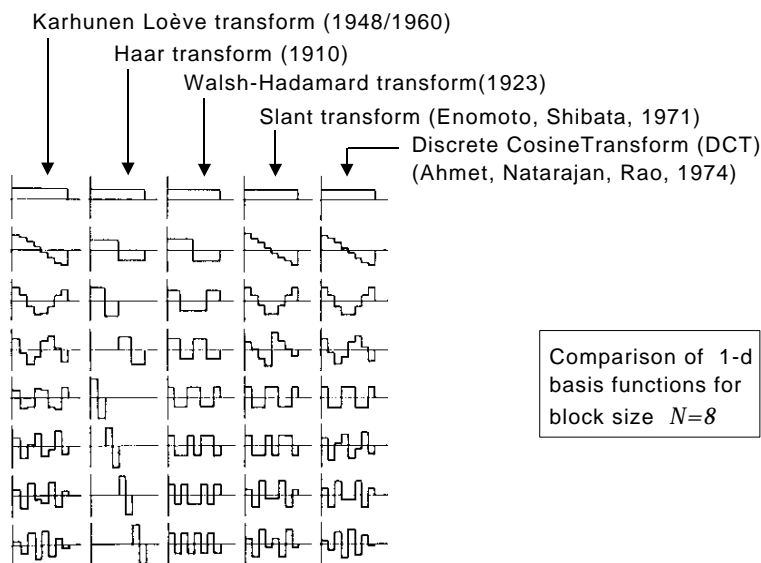


# Karhunen Loève Transform (KLT)

- Karhunen Loève Transform (KLT) yields decorrelated transform coefficients.
- Basis functions are eigenvectors of the covariance matrix of the input signal.
- KLT achieves optimum energy concentration.
- Disadvantages:
  - KLT dependent on signal statistics
  - KLT not separable for image blocks
  - Transform matrix cannot be factored into sparse matrices.

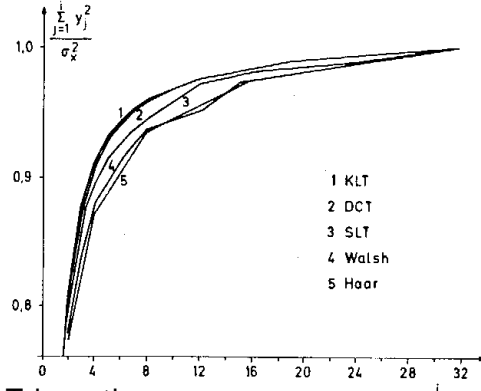


# Comparison of various transforms, I



## Comparison of various transforms, II

- Energy concentration measured for typical natural images, block size 1x32 [Lohscheller]:

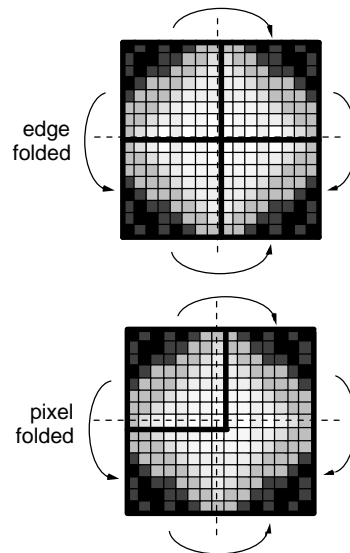


- KLT is optimum
- DCT performs only slightly worse than KLT



## Discrete cosine transform and discrete Fourier transform

- Transform coding of images using the Discrete Fourier Transform (DFT):
  - For stationary image statistics, the energy concentration properties of the DFT converge against those of the KLT for large block sizes.
  - Problem** of blockwise DFT coding: blocking effects due to circular topology of the DFT and Gibbs phenomena.
  - Remedy**: reflect image at block boundaries, DFT of larger symmetric block -> "DCT"



# DCT

- Type II-DCT of blocksize  $M \times M$  is defined by transform matrix  $A$  containing elements

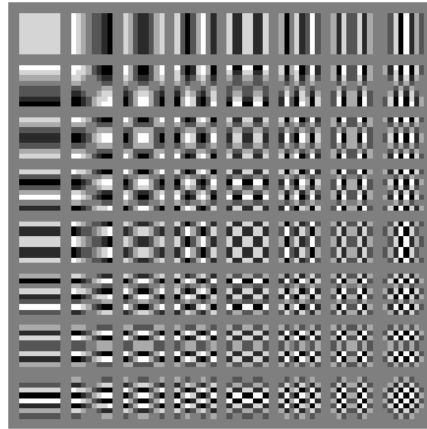
$$a_{ik} = a_i \cos \frac{\mathbf{p}(2k+1)i}{2M}$$

for  $i, k = 0, \dots, M-1$

with  $a_0 = \sqrt{\frac{1}{M}}$

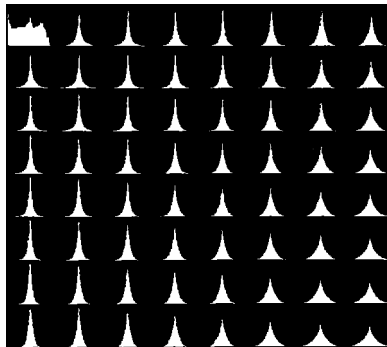
$$a_i = \sqrt{\frac{2}{M}} \quad \forall i \neq 0$$

- 2D basis functions of the DCT:



## Amplitude distribution of the DCT coefficients

- Histograms for 8x8 DCT coefficient amplitudes measured for natural images (from Mauersberger):



- DC coefficient is typically uniformly distributed.
- For the other coefficients, the distribution resembles a Laplacian pdf.



## Bit allocation for transform coefficients I

Problem: divide bit-rate  $R$  among  $M \times M$  transform coefficients  $i$  such that resulting distortion  $D$  is minimized.

Assumptions

$$\begin{array}{cc}
 \boxed{R = \sum_i R_i} & \boxed{D = \sum_i D_i} \\
 \text{Total rate} & \text{Total distortion} \\
 \uparrow & \uparrow \\
 \text{Rate for coefficient } i & \text{Distortion contributed by coefficient } i
 \end{array}$$

lead to "Pareto condition"

$$\frac{\partial D_i}{\partial R_i} = \frac{\partial D_j}{\partial R_j} \quad \text{for all } i, j$$



## Bit allocation for transform coefficients II

- Additional assumptions "Gaussian r.v." and "mse distortion" yield the optimum rate for each transform coefficient  $i$ :

$$\begin{array}{l}
 R_i = \max \left\{ 0, \frac{1}{2} \log_2 \left( \frac{s_i^2}{q} \right) \right\} \text{ bit} \\
 D_i = \min \{ s_i^2, q \}
 \end{array}$$

variance of transform coefficient  $i$   
 Threshold parameter, same for all  $i$

- In practice, with variable length coding, one often uses "distortion allocation" instead of bit allocation



## Bit allocation for transform coefficients III

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- Extension to weighted m.s.e. distortion measure

$$D = \sum_i w_i D_i$$

$$R_i = \max \left\{ 0, \frac{1}{2} \log_2 \left( \frac{w_i s_i^2}{q} \right) \right\} \text{ bit}$$
$$D_i = \min \left\{ s_i^2, \frac{q}{w_i} \right\}$$

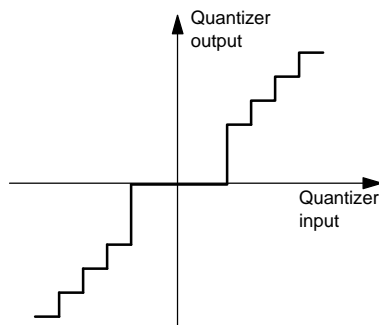
- Often implemented by scaling coefficients by  $(w_i)^{-1/2}$  prior to quantization (“weighting matrix”)



## Threshold coding, I

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- Transform coefficients that fall below a threshold are discarded.
- Implementation by uniform quantizer with threshold characteristic:



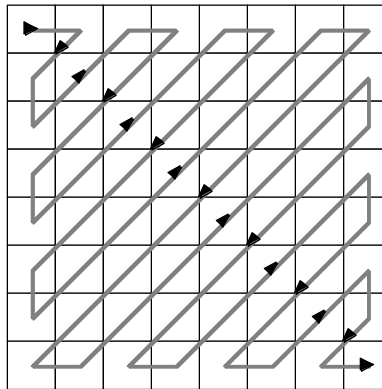
- Positions of non-zero transform coefficients are transmitted in addition to their amplitude values.





# Threshold coding, II

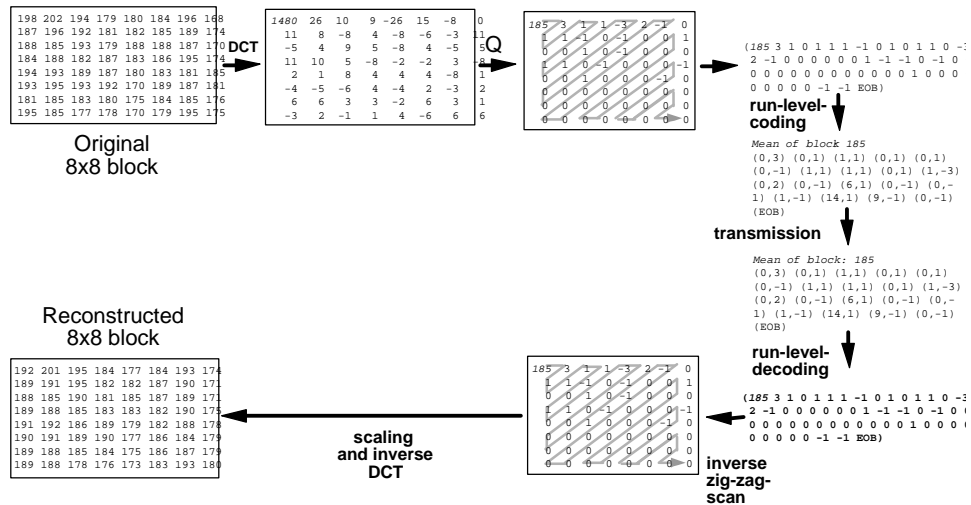
- Efficient encoding of the position of non-zero transform coefficients: zig-zag-scan + run-level-coding



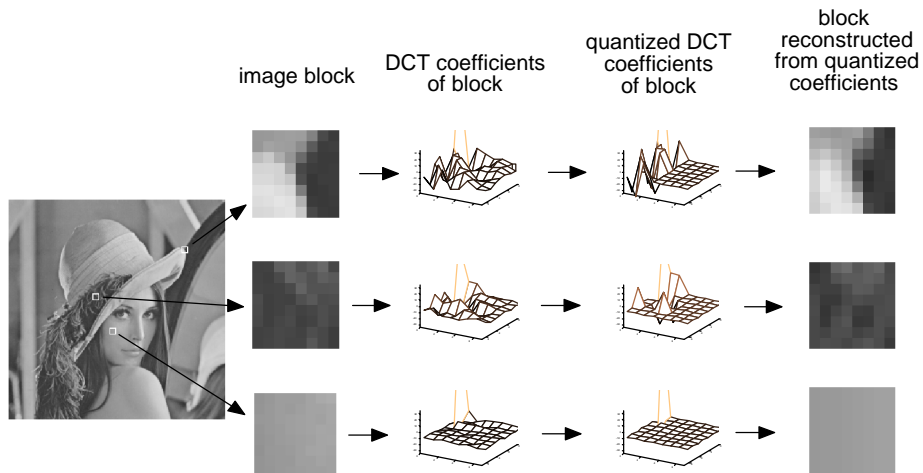
ordering of the transform coefficients by zig-zag-scan



# Threshold coding, III



## Detail in a block vs. DCT coefficients transmitted



## Typical DCT coding artifacts

DCT coding with increasingly coarse quantization, block size 8x8



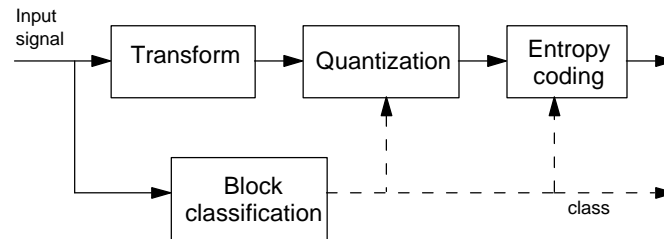
quantizer stepsize  
for AC coefficients: 25

quantizer stepsize  
for AC coefficients: 100

quantizer stepsize  
for AC coefficients: 200



## Adaptive transform coding

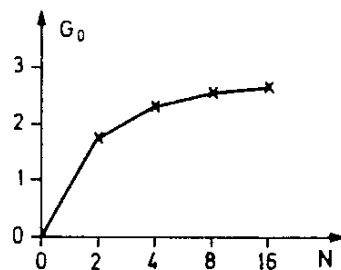


- Quantization and entropy coding optimized separately for each class.
- Typical classes:
  - Blocks without detail
  - Horizontal structures
  - Vertical structures
  - Diagonals
  - Textures without preferred orientation



## Influence of DCT block size

- Efficiency as a function of blocksize  $N \times N$ , measured for 8 bit quantization in the original domain and equivalent quantization in the transform domain



$$G_0 = \frac{\text{memoryless entropy of original signal}}{\text{mean entropy of transform coefficients}}$$

- Block size 8x8 is a good compromise.



## Fast DCT algorithm I

- DCT matrix factored into sparse matrices (Arai, Agui, and Nakajima; 1988):

$$y = Ax$$

$$= SPM_1M_2M_3M_4M_5M_6x$$

$$S = \begin{pmatrix} S_0 & & & & & & & & \\ & S_1 & & & & & & & \\ & & S_2 & & & & & & \\ & & & S_3 & & & & & \\ & & & & S_4 & & & & \\ & & & & & S_5 & & & \\ & & & & & & S_6 & & \\ & & & & & & & S_7 & \\ & & & & & & & & S_8 \end{pmatrix} \quad P = \begin{pmatrix} 1 & & & & & & & & \\ & 1 & & & & & & & \\ & & 1 & & & & & & \\ & & & 1 & & & & & \\ & & & & 1 & & & & \\ & & & & & 1 & & & \\ & & & & & & 1 & & \\ & & & & & & & 1 & \\ & & & & & & & & 1 \end{pmatrix}$$

$$M_1 = \begin{pmatrix} 1 & & & & & & & & \\ & 1 & & & & & & & \\ & & 1 & & & & & & \\ & & & 1 & & & & & \\ & & & & 1 & & & & \\ & & & & & 1 & & & \\ & & & & & & 1 & & \\ & & & & & & & 1 & \\ & & & & & & & & 1 \end{pmatrix} \quad M_2 = \begin{pmatrix} 1 & & & & & & & & \\ & 1 & & & & & & & \\ & & 1 & & & & & & \\ & & & 1 & & & & & \\ & & & & 1 & & & & \\ & & & & & 1 & & & \\ & & & & & & 1 & & \\ & & & & & & & 1 & \\ & & & & & & & & 1 \end{pmatrix}$$

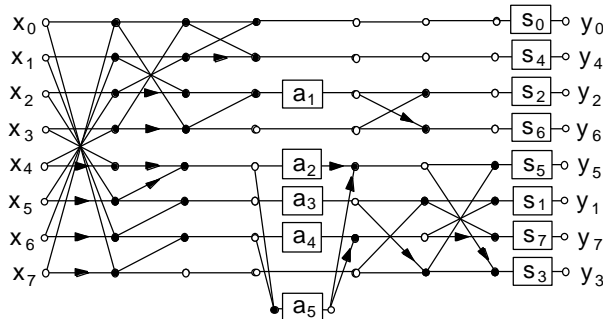
$$M_3 = \begin{pmatrix} 1 & & & & & & & & \\ & 1 & & & & & & & \\ & & 1 & & & & & & \\ & & & 1 & & & & & \\ & & & & 1 & & & & \\ & & & & & 1 & & & \\ & & & & & & 1 & & \\ & & & & & & & 1 & \\ & & & & & & & & 1 \end{pmatrix} \quad M_4 = \begin{pmatrix} 1 & & & & & & & & \\ & 1 & & & & & & & \\ & & 1 & & & & & & \\ & & & 1 & & & & & \\ & & & & 1 & & & & \\ & & & & & 1 & & & \\ & & & & & & 1 & & \\ & & & & & & & 1 & \\ & & & & & & & & 1 \end{pmatrix}$$

$$M_5 = \begin{pmatrix} 1 & & & & & & & & \\ & 1 & & & & & & & \\ & & 1 & & & & & & \\ & & & 1 & & & & & \\ & & & & 1 & & & & \\ & & & & & 1 & & & \\ & & & & & & 1 & & \\ & & & & & & & 1 & \\ & & & & & & & & 1 \end{pmatrix} \quad M_6 = \begin{pmatrix} 1 & & & & & & & & \\ & 1 & & & & & & & \\ & & 1 & & & & & & \\ & & & 1 & & & & & \\ & & & & 1 & & & & \\ & & & & & 1 & & & \\ & & & & & & 1 & & \\ & & & & & & & 1 & \\ & & & & & & & & 1 \end{pmatrix}$$



## Fast DCT algorithm II

- Signal flow graph for fast (scaled) 8-DCT according to Arai, Agui, Nakajima:



scaling

only 5 + 8 multiplications

(direct matrix multiplication: 64 multiplications)

Multiplication:  
 $u \circ \boxed{m} \circ m \cdot u$

Addition:  
 $u \circ \swarrow \searrow \rightarrow u+v$   
 $v \circ \swarrow \searrow \rightarrow u-v$

$$a_1 = C_4$$

$$a_2 = C_2 - C_6$$

$$a_3 = C_4$$

$$a_4 = C_6 + C_2$$

$$a_5 = C_6$$

$$s_0 = \frac{1}{2\sqrt{2}}$$

$$s_k = \frac{1}{4C_k} \quad k=1, \dots, 7$$

$$C_k = \cos\left(\frac{p}{16}k\right)$$



## Transform coding: summary

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- Orthonormal transform: rotation of coordinate system in signal space
- Purpose of transform: decorrelation, energy concentration
- KLT is optimum, but signal dependent and, hence, without a fast algorithm
- DCT shows reduced blocking artifacts compared to DFT
- Bit allocation proportional to logarithm of variance
- Threshold coding + zig-zag-scan + 8x8 block size is widely used today (e.g. JPEG, MPEG, ITU-T H.263)
- Fast algorithm for scaled 8-DCT: 5 multiplications, 29 additions

