

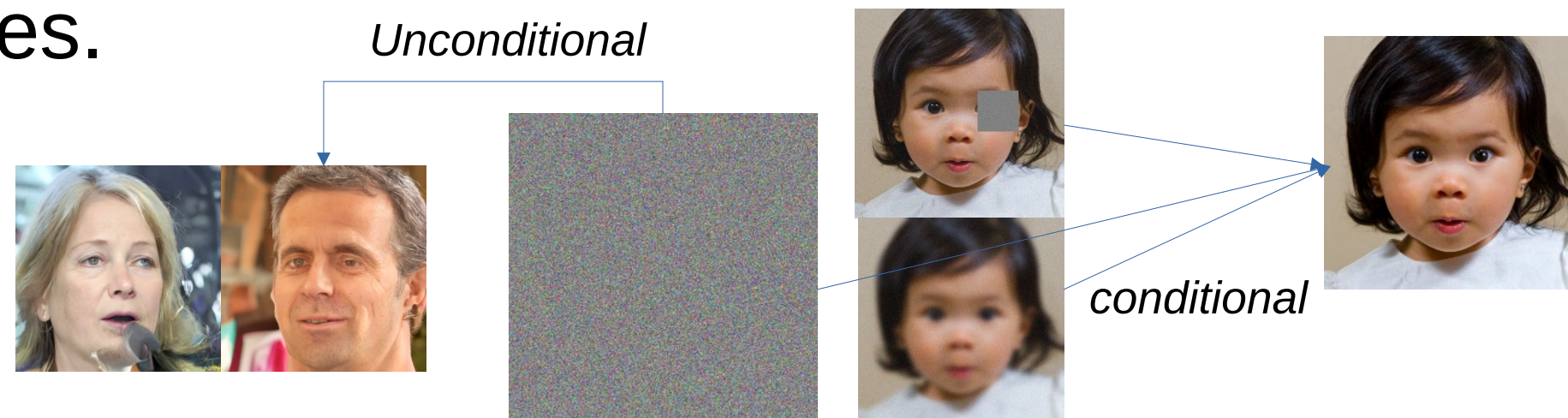


# Diffusion Models for Solving Inverse Imaging Problems

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## Motivation

To solve ill-posed inverse problems such as inpainting, denoising, image reconstruction with generative priors. Diffusion models show great promise in unconditional generation. They model gradient of the log probability density of a data distribution, which guides the inverse process by acting as powerful score based prior that constrains the solution to the manifold of natural images.



## Methods

3 methods build on top of a) pre-trained u-net based diffusion model pre-trained on FFHQ256 dataset b) VP formulation of forward and reverse diffusion process [7]

### SDEdit [4]

$$x_t = \sqrt{\bar{\alpha}_t}y + \sqrt{1 - \bar{\alpha}_t}z, z \sim N(0, I)$$

for  $t = T, \dots, 1$ :

$$z \sim N(0, I) \text{ if } t > 1 \text{ else } z = 0$$

$$\hat{x}_0 = \frac{1}{\sqrt{\bar{\alpha}_t}}(x_t + (1 - \bar{\alpha}_t)s_\theta(x_t, t))$$

$$x_{t-1} = \frac{\alpha_t(1 - \bar{\alpha}_{t-1})}{1 - \bar{\alpha}_t}x_t + \frac{\sqrt{\bar{\alpha}_{t-1}}(1 - \alpha_t)}{1 - \bar{\alpha}_t}\hat{x}_0 + \sigma z$$

end for  
return  $x_0$

Main idea:  $x_t$  partially noised image input + DDPM [3]

### ScoreALD [5]

Problem:  $\nabla_x \log p(\mathbf{b}|\mathbf{x}_0) \neq \nabla_x \log p_t(\mathbf{b}|\mathbf{x}_t)$   
Approach:  $\nabla_x \log p(\mathbf{b}|\mathbf{x}_0) \approx \nabla_x \log p_t(\mathbf{b}|\mathbf{x}_t)$

$$x_t \sim N(0, I)$$

for  $t = T, \dots, 1$ :

$$z \sim N(0, I) \text{ if } t > 1 \text{ else } z = 0$$

$$\hat{x}_0 = \frac{1}{\sqrt{\bar{\alpha}_t}}(x_t + (1 - \bar{\alpha}_t)s_\theta(x_t, t))$$

$$x_{t-1} = \frac{\alpha_t(1 - \bar{\alpha}_{t-1})}{1 - \bar{\alpha}_t}x_t + \frac{\sqrt{\bar{\alpha}_{t-1}}(1 - \alpha_t)}{1 - \bar{\alpha}_t}\hat{x}_0 + \sigma z$$

$$x_{t-1} = x_{t-1} - \frac{1}{2(\sigma^2 + \gamma^2)}\nabla_{x_t} \|\mathcal{A}(x_t) - y\|^2$$

end for  
return  $x_0$

Main idea:  $x_t$  random noise + DDPM [3] + sampling with guidance using current noisy estimate i.e.  $x_t$

### DPS [6]

Problem:  $\nabla_x \log p(\mathbf{b}|\mathbf{x}_0) \neq \nabla_x \log p_t(\mathbf{b}|\mathbf{x}_t)$   
Approach:  $\nabla_x \log p(\mathbf{b}|\mathbf{x}_0) \approx \nabla_x \log p_t(\mathbf{b}|\mathbf{x}_0) = \mathbb{E}[\mathbf{x}_0|\mathbf{x}_t]$

$$x_t \sim N(0, I)$$

for  $t = T, \dots, 1$ :

$$z \sim N(0, I) \text{ if } t > 1 \text{ else } z = 0$$

$$\hat{x}_0 = \frac{1}{\sqrt{\bar{\alpha}_t}}(x_t + (1 - \bar{\alpha}_t)s_\theta(x_t, t))$$

$$x_{t-1} = \frac{\alpha_t(1 - \bar{\alpha}_{t-1})}{1 - \bar{\alpha}_t}x_t + \frac{\sqrt{\bar{\alpha}_{t-1}}(1 - \alpha_t)}{1 - \bar{\alpha}_t}\hat{x}_0 + \sigma z$$

$$x_{t-1} = x_{t-1} - \zeta_t \nabla_{x_t} \|\mathcal{A}(\hat{x}_0) - y\|^2$$

Practical hyper parameter  $\zeta_t = \frac{\zeta}{\|\nabla_{x_t} \|\mathcal{A}(\hat{x}_0) - y\|^2\|}$

end for  
return  $x_0$

Main idea:  $x_t$  random noise + DDPM [3] + conditioning on current denoised estimate  $\hat{x}_0$

## Related Work

- BM3D [1] Conventional approach gold standard: Collapse on complex textures, over smoothing, artifacts on high noise level
- [2],[7] introduce concept of forward and reverse diffusion process & [3] demonstrates it for high quality image generation: main problem: sub-optimal log likelihood

## References

- [1] Sarjanoja, Boutellier, Hannuksela, "BM3D image denoising using heterogeneous computing platforms," DASIP, 2015  
[2] Sohl-Dickstein, Weiss, Maheswaranathan, Ganguli, Deep Unsupervised Learning using Nonequilibrium Thermodynamics, ICML, 2015  
[3] Ho, Jain, Abbeel, Denoising Diffusion Probabilistic Models, NeurIPS, 2020  
[4] Meng et al., "SDEdit: Guided Image Synthesis and Editing with Stochastic Differential Equations" ICLR 2022.  
[5] Jalal et al., "Robust Compressed Sensing MRI with Deep Generative Priors," NeurIPS, 2021.  
[6] Chung et al., "Diffusion Posterior Sampling for General Noisy Inverse Problems," ICLR 2023.  
[7] Y. Song, S. Ermon, "Generative modeling by estimating gradients of the data distribution", NeurIPS 2019

Metric 1: PSNR (higher is better)

	SDEdit	
T	blur+noise	Reconst.
300		
500		
700		
		24.65/0.12
		20.62/0.196
		16.62/0.289

T	300	500	700
Mask + noise			
Reconst.			
	25.00/.11	20.9/.18	16.4/.29

## Experimental Results

ScoreALD		
Input	Ground Truth	Generated using ScoreALD
Anneal [10,15] Deconv. 22.54/0.15		
T=1000 for all experiments		

ScoreALD		
Input	Ground Truth	Generated using ScoreALD
Anneal [15,20] Inpainting 21.95/0.14		
*best results shown here, more in the full paper for full effect of hyperparameter		

Metric 2: LPIPS (lower is better)

DPS	
T=1000 for all exp	
Scale	0.3
	34.89/0.02
	28.59/0.06
Scale	1.0
	35.12/0.02
	27.76/0.11
	Inpaint Deconv

\*here we can see which hyperparameter is the best for which task