

DIFFUSION MODELS AS GENERATIVE PRIORS FOR INVERSE PROBLEMS

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Overview

Diffusion models [1] are a class of generative models that learn to synthesize data by gradually denoising a noisy input. In this work, we explore their capabilities in **image generation, denoising, inpainting, and deconvolution**.

Specifically, we use diffusion model-based methods for the following tasks:

- Unconditional Image Generation from Noise
- Single Step Image Denoising

We also apply diffusion based methods to inverse problems - specifically Inpainting and Deconvolution via three methods:

- **Score Distillation Editing (SDEdit)** [2]
- **Score Annealed Langevin Dynamics (ScoreALD)** [3]
- **Diffusion Posterior Sampling (DPS)** [4]

For these tasks, we use a pre-trained diffusion model[4] that is trained on the Flickr-Faces-HQ Dataset (FFHQ) dataset, and use the variance preserving formulation of diffusion models[1].

Image Generation

The sequence showing the forward (reverse) diffusion process of generating a sample by slowly adding (removing) noise.

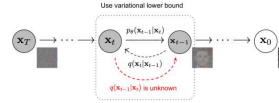


Figure from Ho et al. 2020[1], additionally annotated by Lilian Weng.

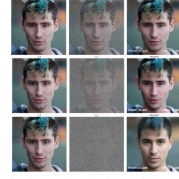


Examples of faces generated by the pretrained model starting from noise.

Single Step Image Denoising

Single Step Denoising Algorithm:

$$s \leftarrow \frac{-\epsilon}{\sqrt{1-\alpha_t}}; \quad \hat{x}_0 \leftarrow \sqrt{\frac{1}{\alpha_t}}(x_t + (1-\alpha_t)s)$$



Ground Truth (left), Noisy Input (middle), Model Result (right) for noise levels $t=100, 250$ and 500 (top to bottom)

Inverse Problems via SDEdit[2]

Inverse Problem:

$$y = Ax^* + w$$

Iteratively apply the SDEdit Algorithm, to calculate $\hat{x}_0(x_t) \forall t = T-1, \dots, 0$.

SDEdit Algorithm:

$$s \leftarrow \frac{-\epsilon}{\sqrt{1-\alpha_t}}; \quad \hat{x}_0 \leftarrow \sqrt{\frac{1}{\alpha_t}}(x_t + (1-\alpha_t)s) \\ x_{t-1} \leftarrow q(\hat{x}_{t-1}|x_t, x_0) + \sigma z \quad \text{where } w \sim \mathcal{N}(0, 1)$$



Inpainting for $t=250$ (top), 500 (middle) and 750 (bottom) Deconvolution for $t=250$ (top), 500 (middle) and 750 (bottom)

Inverse Problems via ScoreALD[3]

Inverse Problem:

$$y = Ax^* + w$$

Sampling the posterior $\mu(x|y)$ using Langevin Dynamics:

$$x_{t+1} \leftarrow x_t + \eta \nabla_{x_t} \log \mu(x_t|y) + \sqrt{2\eta} \zeta_t; \quad \zeta_t \sim \mathcal{N}(0, 1)$$

ScoreALD Algorithm: Initialize $x_0 \sim \mathcal{N}_t(0, 1)$ and $\forall t = 0, \dots, T-1$:

$$x_{t+1} \leftarrow x_t + \eta \left(f(x_t; \beta_t) + \frac{A^H(y - Ax_t)}{\gamma_t^2 + \sigma^2} \right) + \sqrt{2\eta} \zeta_t; \quad \zeta_t \sim \mathcal{N}(0, 1)$$



ScoreALD results for deconvolution (top) and inpainting (bottom); $\sigma = 0.05$

Inverse Problems via DPS[4]

Inverse Problem:

$$y = Ax^* + w$$

Diffusion Posterior Sampling Algorithm:

$$x_{i-1} \leftarrow x'_{i-1} - \eta \nabla_{x_i} \|y - \mathcal{A}(\hat{x}_i)\|^2; \quad \text{where } \zeta_i = \frac{c}{\|y - \mathcal{A}(\hat{x}_i)\|^2}$$

where for $\forall i = N-1, \dots, 0$ we have $x_N \sim \mathcal{N}_t(0, I)$ and:

$$\hat{s} \leftarrow s_\theta(x_i, i); \quad \hat{x}_0 \leftarrow \sqrt{\frac{1}{\alpha_t}}(x_t + (1-\alpha_t)\hat{s}) \\ x'_{i-1} \leftarrow \frac{\sqrt{\alpha_i(1-\alpha_{i-1})}}{(1-\alpha_i)}x_i + \frac{\sqrt{\alpha_{i-1}\beta_i}}{1-\alpha_i}\hat{x}_0 + \hat{\sigma}_i z$$



DPS results for deconvolution (top) and inpainting (bottom)

References

- [1] Pieter Abbeel Jonathan Ho Ajay Jain. "Denoising diffusion probabilistic models." In: *NeurIPS* (2020). URL: <https://doi.org/10.48550/arXiv.2006.11239>.
- [2] Yang Song Jiaming Song Jaun Wu Jun-Yao Zhu Stefano Ermon Chenlin Meng Yutong He. "Guided image synthesis and editing with stochastic differential equations." In: (2022). URL: <https://doi.org/10.48550/arXiv.2108.01073>.
- [3] Giannis Dantas Eric Price Alejandro G. Dimakis-Jonathan I. Tamir Ajil Jalal Maries Arvinte. "Robust Compressed Sensing MRI with Deep Generative Priors." In: (2021). URL: <https://doi.org/10.48550/arXiv.2108.01968>.
- [4] Michael T. McKeown Marc L. Klesky Jong Chul Ye Hyungjin Chung Jeongsol Kim. "Diffusion posterior sampling for general noisy inverse problems." In: *ICLR* (2023). URL: <https://doi.org/10.48550/arXiv.2209.14687>.