

Today's Topic: Clustering 1

- Document clustering
	- **Motivations**
	- Document representations
	- **Success criteria**
- **Clustering algorithms**
	- K-means
	- Model-based clustering (EM clustering)

What is clustering?

- Clustering is the process of grouping a set of physical or abstract objects into classes of similar objects
	- It is the commonest form of unsupervised learning
		- Unsupervised learning = learning from raw data, as opposed to supervised data where the correct classification of examples is given
	- $It is a common and important task that finds many$ applications in IR and other places

Why cluster documents?

- **Whole corpus analysis/navigation Better user interface**
- For improving recall in search applications **Better search results**
- For better navigation of search results
- Effective "user recall" will be higher For speeding up vector space retrieval
- Faster search

Navigating document collections

- Standard IR is like a book index
- Document clusters are like a table of contents
- **People find having a table of contents useful**

Corpus analysis/navigation

- Given a corpus, partition it into groups of related docs
	- Recursively, can induce a tree of topics
	- Allows user to browse through corpus to find information
	- Crucial need: meaningful labels for topic nodes.
- **Nahoo!: manual hierarchy**
	- Often not available for new document collection

For improving search recall *Cluster hypothesis* - Documents with similar text are related **Therefore, to improve search recall:** Cluster docs in corpus a priori

- When a query matches a doc *D*, also return other docs in the cluster containing *D*
- Hope if we do this: The query "car" will also return docs containing *automobile*
	- **Because clustering grouped together docs** containing *car* with those containing *automobile.*

Why might this happen?

For speeding up vector space retrieval

- In vector space retrieval, we must find nearest doc vectors to query vector
- This entails finding the similarity of the query to every doc – slow (for some applications)
- By clustering docs in corpus a priori
	- find nearest docs in cluster(s) close to query
	- \blacksquare inexact but avoids exhaustive similarity computation Exercise: Make up a simple

example with points on a line in 2 clusters where this inexactness shows up.

Speeding up vector space retrieval

- Recall lecture 7 on leaders and followers
	- **Effectively a fast simple clustering algorithm where** documents are assigned to closest item in a set of randomly chosen leaders
- We could instead find natural clusters in the data
	- Cluster documents into *k* clusters
	- Retrieve closest cluster c_i to query
	- Rank documents in c_i and return to user

What Is A Good Clustering?

- **Internal criterion: A good clustering will produce** high quality clusters in which:
	- the intra-class (that is, intra-cluster) similarity is high
	- \blacksquare the inter-class similarity is low
	- The measured quality of a clustering depends on both the document representation and the similarity measure used
- **External criterion: The quality of a clustering is** also measured by its ability to discover some or all of the hidden patterns or latent classes
	- Assessable with gold standard data

- **Assesses clustering with respect to ground truth**
- Assume that there are C gold standard classes, while our clustering algorithms produce *k* clusters, π_1 , π_2 , ..., π_k with n_i members.
- Simple measure: purity, the ratio between the dominant class in the cluster π and the size of cluster πⁱ

$$
Purity(\pi_i) = \frac{1}{n_i} \max_j (n_{ij}) \quad j \in C
$$

 Others are entropy of classes in clusters (or mutual information between classes and clusters)

Issues for clustering **Representation for clustering** Document representation Vector space? Normalization? Need a notion of similarity/distance How many clusters? Fixed a priori? Completely data driven? Avoid "trivial" clusters - too large or small In an application, if a cluster's too large, then for navigation purposes you've wasted an extra user click without whittling down the set of documents much. What makes docs "related"? **Ideal: semantic similarity. Practical: statistical similarity** We will use cosine similarity. Docs as vectors. For many algorithms, easier to think in terms of a distance (rather than similarity) between docs. We will describe algorithms in terms of cosine similarity. Cosine similarity of normalized D_j, D_k : Aka normalized inner product. $\lim(D_j, D_k) = \sum_{i=1}^m w_{ij} \times w_{ik}$

Recall doc as vector

- Each doc *j* is a vector of *tf×idf* values, one component for each term.
- Can normalize to unit length.
- So we have a vector space
	- terms are axes aka *features*
	- *n* docs live in this space
	- e even with stemming, may have 20,000+ dimensions
	- do we really want to use all terms?
		- Different from using vector space for search. Why?

Clustering Algorithms

- **Partitioning "flat" algorithms**
	- Usually start with a random (partial) partitioning
	- Refine it iteratively
		- *k* means/medoids clustering
		- Model based clustering
- **Hierarchical algorithms**
	- Bottom-up, agglomerative
	- **Top-down, divisive**

Partitioning Algorithms

- Partitioning method: Construct a partition of *n* documents into a set of *k* clusters
- Given: a set of documents and the number *k*
- Find: a partition of *k* clusters that optimizes the chosen partitioning criterion
	- Globally optimal: exhaustively enumerate all partitions
	- **Effective heuristic methods: k-means and k**medoids algorithms

K-Means

- Assumes documents are real-valued vectors.
- Clusters based on *centroids* (aka the *center of gravity* or mean) of points in a cluster, *c*:

$$
\vec{\mu}(c) = \frac{1}{|c|} \sum_{\vec{x} \in c} \vec{x}
$$

- Reassignment of instances to clusters is based on distance to the current cluster centroids.
	- (Or one can equivalently phrase it in terms of similarities)

K-Means Algorithm

Let *d* be the distance measure between instances. Select *k* random instances $\{s_1, s_2, \ldots s_k\}$ as seeds. Until clustering converges or other stopping criterion: For each instance x_i :

Assign x_i to the cluster c_j such that $d(x_i, s_j)$ is minimal. (*Update the seeds to the centroid of each cluster*) For each cluster *cj* $s_j = \mu(c_j)$

Convergence

- Why should the K-means algorithm ever reach a *fixed point*?
	- A state in which clusters don't change.
- K-means is a special case of a general procedure known as the *Expectation Maximization (EM) algorithm*.
	- EM is known to converge.
	- Number of iterations could be large.

Convergence of K-Means

- Define goodness measure of cluster k as sum of squared distances from cluster centroid:
	- $G_k = \sum_i (v_i c_k)^2$ (sum all v_i in cluster k)
- $G = \sum_k G_k$
- Reassignment monotonically decreases G since each vector is assigned to the closest centroid.
- Recomputation monotonically decreases each G_k since: $(m_k \text{ is number of members in cluster})$
	- $Σ (v_{in} a)² reaches minimum for:$
	- $\Sigma -2(v_{in} a) = 0$

Convergence of K-Means $\Sigma -2(v_{in} - a) = 0$ \bullet Σ v_{in} = Σ a

- m_k a = Σ v_{in}
- **a** = (1/ m_k) Σ $v_{in} = c_{kn}$
- K-means typically converges quite quickly

Time Complexity

- Assume computing distance between two instances is $\dot{O}(m)$ where *m* is the dimensionality of the vectors.
- Reassigning clusters: *O(kn)* distance computations, or *O(knm).*
- **Computing centroids: Each instance vector gets** added once to some centroid: *O(nm).*
- Assume these two steps are each done once for *i* iterations: *O(iknm).*
- **Linear in all relevant factors, assuming a fixed** number of iterations, more efficient than hierarchical agglomerative methods

Seed Choice Results can vary based on **Example showing** random seed selection. **sensitivity to seeds** \overline{C} **Some seeds can result in poor** σ σ convergence rate, or \circ \circ \circ convergence to sub-optimal D clusterings. **In the above, if you start with B and E as centroids** Select good seeds using a **you converge to {A,B,C}** heuristic (e.g., doc least similar **and {D,E,F}** to any existing mean) **If you start with D and F** Try out multiple starting points **you converge to {A,B,D,E} {C,F}** \blacksquare Initialize with the results of another method. Exercise: find good approach for finding good starting points

How Many Clusters?

- Number of clusters *k* is given
	- **Partition** *n* docs into predetermined number of clusters
- Finding the "right" number of clusters is part of the problem
	- Given docs, partition into an "appropriate" number of subsets.
	- E.g., for query results ideal value of *k* not known up front - though UI may impose limits.
- **Can usually take an algorithm for one flavor and** convert to the other.

k not specified in advance

- Say, the results of a query.
- **Solve an optimization problem: penalize having** lots of clusters
	- **a** application dependent, e.g., compressed summary of search results list.
- Tradeoff between having more clusters (better focus within each cluster) and having too many clusters

k not specified in advance

- Given a clustering, define the **Benefit** for a doc to be the cosine similarity to its centroid
- Define the Total Benefit to be the sum of the individual doc Benefits.

 \equiv Why is there always a clustering of Total Benefit *n*?

Penalize lots of clusters

- For each cluster, we have a Cost C.
- **Thus for a clustering with** *k* **clusters, the Total** Cost is *kC*.
- \blacksquare Define the Value of a clustering to be \blacksquare Total Benefit - Total Cost.
- Find the clustering of highest value, over all choices of *k*.
	- Total benefit increases with increasing K. But can stop when it doesn't increase by "much". The Cost term enforces this.

K-means issues, variations, etc.

- Recomputing the centroid after every assignment (rather than after all points are re-assigned) can improve speed of convergence of K-means
- Assumes clusters are spherical in vector space Sensitive to coordinate changes, weighting etc.
- Disjoint and exhaustive
	- Doesn't have a notion of "outliers"

Soft Clustering

- **Clustering typically assumes that each instance** is given a "hard" assignment to exactly one cluster.
- Does not allow uncertainty in class membership or for an instance to belong to more than one cluster.
- **Soft clustering** gives probabilities that an instance belongs to each of a set of clusters.
- **Each instance is assigned a probability** distribution across a set of discovered categories (probabilities of all categories must sum to 1).

Model based clustering

- Algorithm optimizes a probabilistic model criterion
- Clustering is usually done by the Expectation Maximization (EM) algorithm
	- Gives a soft variant of the K-means algorithm
	- Assume *k* clusters: $\{c_1, c_2, \ldots c_k\}$
	- Assume a probabilistic model of categories that allows computing P(*c*ⁱ | *E*) for each category, *c*ⁱ , for a given example, *E*.
	- For text, typically assume a naïve Bayes category model.
	- Parameters $θ = {P(c_j), P(w_j | c_j): i \in {1, ... k}, j$ ∈{1,…,|*V*|}}

Expectation Maximization (EM) Algorithm

- **Iterative method for learning probabilistic categorization** model from unsupervised data.
- **Initially assume random assignment of examples to** categories.
- **Learn an initial probabilistic model by estimating model** parameters θ from this randomly labeled data.
- **Iterate following two steps until convergence:**
	- **Expectation (E-step): Compute P(** $c_i | E$ **) for each example given** the current model, and probabilistically re-label the examples based on these posterior probability estimates.
	- Maximization (M-step): Re-estimate the model parameters, θ, from the probabilistically re-labeled data.

EM Experiment [Soumen Chakrabarti] Semi-supervised: some labeled and unlabeled data Take a completely labeled corpus D, and randomly select a subset as D_{K} . **Also use the set** $D^U \subseteq D$ of unlabeled documents in the EM procedure. Correct classification of a document => concealed class label = class with largest probability Accuracy with unlabeled documents > accuracy without unlabeled documents Keeping labeled set of same size **EM beats naïve Bayes with same size of labeled** document set

- Largest boost for small size of labeled set
- Comparable or poorer performance of EM for large labeled sets

Belief in labeled documents Depending on one's faith in the initial labeling \blacksquare Set before 1st iteration:

- Pr(c_d | d) = 1 ε and Pr(c' | d) = ε /(n 1) for all c' \neq c_d
- With each iteration
	- Let the class probabilities of the labeled documents `smear' in reestimation process
- To limit 'drift' from initial labeled documents, one can add a damping factor in the E step to the

contribution from unlabeled documents

Summary

- **Two types of clustering**
	- Flat, partional clustering
	- **Hierarchical, agglomerative clustering**
- How many clusters?
- Key issues
	- Representation of data points
	- Similarity/distance measure
- K-means: the basic partitional algorithm
- **Model-based clustering and EM estimation**