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Stanford CS224W: GNNs for Recommender Systems

CS224W: Machine Learning with Graphs Jure Leskovec, Stanford University http://cs224w.stanford.edu

Announcements

- **(11/4) Homework 2** is due Monday (was updated Wed 10/23)
- **Homework 3** is released today. Watch ED for recitation session information. Due on 11/14
- ¡ **No class next Tuesday 11/5 (Election day!)**
- ¡ **(11/7) Colab 3** is due next Thursday (one week from today)
- ¡ **(11/7) Project Milestone** is due next Thursday (one week from today)

Stanford CS224W: Recommender Systems: Task and Evaluation

CS224W: Machine Learning with Graphs Jure Leskovec, Stanford University http://cs224w.stanford.edu

Preliminary of Recommendation

\blacksquare **Information Explosion in the era of Internet**

- 10K+ movies in Netflix
- 12M products in Amazon (350m on Marketplace)
- 70M+ music tracks in Spotify
- § 10B+ videos on YouTube
- 200B+ pins (images) in Pinterest
- Personalized recommendation (i.e., suggesting **a small number of interesting items for each user)** is critical for users to effectively explore the content of their interest.

Recommender System as a Graph

- Recommender system can be naturally modeled as a **bipartite graph**
	- A graph with two node types: **users** and **items**.
	- **Edges** connect users and items
		- Indicates user-item interaction (e.g., click, purchase, review etc.)
		- **Often associated with timestamp** (timing of the interaction).

Recommendation Task

¡ **Given**

■ Past user-item interactions

¡ **Task**

- **Predict new items each user will** interact in the future.
- Can be cast as **link prediction** problem.
	- **Predict new user-item interaction** edges given the past edges.
- For $u \in U$, $v \in V$, we need to get a real-valued **score** $f(u, v)$.

Modern Recommender System

- **Problem:** Cannot evaluate $f(u, v)$ for every user u – item v pair. Example $f(u, v)$ $f(u, v) = z_u \cdot z_v$
- **Solution:** 2-stage process:
	- § Candidate generation (cheap, fast)

Top-K Recommendation

- \blacksquare For each user, we recommend K items.
	- For recommendation to be effective, *K* needs to **be much smaller than the total number of items (up to billions)**
	- \blacksquare K is typically in the order of 10–100.
- ¡ The goal is to include as many **positive items** as possible in the top- K recommended items.
	- Positive items = Items that the user will interact **with in the future.**
- **Evaluation metric**: Recall@K (defined next)

Evaluation Metric: Recall@K (1)

For each user u **,**

- **Let** P_{ij} **be a set of positive items the user will interact** in the future.
- **Let** R_{ν} **be a set of items recommended by the model.**
	- In top-K recommendation, $|R_{\nu}| = K$.
	- Items that the user has already interacted are excluded.

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Evaluation Metric: Recall@K (2)

F Recall@K for user *u* is $|P_u \cap R_u|/|P_u|$.

Higher value indicates more positive items are recommended in top- K for user u .

The final Recall ωK is computed by averaging the recall values across all users.

Recommendations with LLMs

- **GNN** to embed users & products
- **LLM** to textify products and embed them
	- user emb. is avg. of purchased product embs.
- H&M fashion recommendation:

More info: Do Large Language Models make accurate personalized recommen

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Stanford CS224W: Recommender Systems: Embedding-Based Models

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Notation

¡ **Notation**:

- \blacksquare U: A set of all users
- \blacksquare V: A set of all items
- \blacksquare \pmb{E} : A set of observed user-item interactions

 \bullet $\boldsymbol{E} = \{ (u, v) \mid u \in \boldsymbol{U}, v \in \boldsymbol{V}, u \text{ interacted with } v \}$

Score Function

- \blacksquare To get the top-K items, we need a score function for user-item interaction:
	- For $u \in U, v \in V$, we need to get a real-valued scalar $score(u, v)$.
	- *K* items with the largest **scores for a given user** (excluding alreadyinteracted items) are then recommended.

For $K = 2$, recommended items for user u would be $\{v_1, v_3\}$.

Embedding-Based Models

- **E** We consider **embeddingbased models** for scoring useritem interactions.
	- For each user $u \in U$, let $u \in \mathbb{R}^D$ be its D -dimensional embedding.
	- For each item $v \in V$, let $v \in \mathbb{R}^D$ be its D -dimensional embedding.
	- **•** Let $f_{\theta}(\cdot,\cdot)$: $\mathbb{R}^D \times \mathbb{R}^D \to \mathbb{R}$ be a parametrized function.

Then,
$$
score(u, v) \equiv f_{\theta}(u, v)
$$

Training Objective

- Embedding-based models have three kinds of parameters:
	- An encoder to generate user embeddings $\{u\}_{u\in H}$
	- An encoder to generate item embeddings $\{v\}_{v\in V}$
	- Score function $f_{\theta}(\cdot,\cdot)$
- **Training objective:** Optimize the model parameters to achieve high recall@ K on *seen* (i.e., *training*) user-item interactions
	- We hope this objective would lead to high recall@ K on *unseen* (i.e., *test*) interactions.

Surrogate Loss Functions

- **The original training objective (recall** $@K$) is *not* **differentiable**.
	- *Cannot* apply efficient gradient-based optimization.
- **Two surrogate loss functions** are widely-used to enable efficient gradient-based optimization.
	- Binary loss
	- § Bayesian Personalized Ranking (BPR) loss
- ¡ Surrogate losses are **differentiable** and should **align well with the original training objective**.

Binary Loss (1)

- ¡ Define **positive/negative edges**
	- A set of **positive edges E** (i.e., observed/training user-item interactions)
	- A set of **negative edges** $E_{\text{neg}} = \{(u, v) | (u, v) \notin$ $E, u \in U, v \in V$
- **Define sigmoid function** $\sigma(x) \equiv$ 1 $1+exp(-x)$
	- Maps real-valued scores into binary likelihood scores, i.e., in the range of [0,1].

Binary Loss (2)

Example 1 Binary Ioss: Binary classification of **positive/negative** edges using $\sigma(f_{\theta}(u, v))$: $-\frac{1}{15}$ $\frac{1}{|E|}$, \sum $\overline{u,v} \in E$ $\log\left(\sigma(f_\theta(\boldsymbol{u}, \boldsymbol{v}))\right) - \frac{1}{|\boldsymbol{F}|}$ $\frac{1}{|E_{\text{neg}}|}$ $(u, v) \in E_{\text{neg}}$ $\log\left(1 - \sigma(f_\theta(\boldsymbol{u}, \boldsymbol{v})\right)$

> During training, these terms can be approximated using mini-batch of positive/negative edges

- ¡ Binary loss pushes the scores of **positive edges** higher than those of **negative edges**.
	- § This aligns with the training recall metric since positive edges need to be recalled.

Issue with Binary Loss (1)

- **Example:** In the binary loss, the scores of **ALL** positive edges are pushed higher than those of *ALL* negative edges.
- **This would unnecessarily penalize model** predictions even if the training recall metric is perfect.
- ¡ **Why?** (example in the next slide)

Issue with Binary Loss (2)

¡ **Let's consider the simplest case:**

- § Two users, two items
- Metric: Recall@1.
- § A model assigns the score for every user-item pair (as shown in the right).
- ¡ Training **Recall@1 is 1.0** (perfect score), because v_0 (resp. v_1) is correctly recommended to u_0 (resp. u_1).
- **E** However, the binary loss would **still penalize the model prediction** because the negative (u_1, v_0) edge gets the higher score than the positive edge (u_0, v_0) .
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Issue with Binary Loss (3)

- ¡ **Key insight**: The binary loss is **non-personalized** in the sense that the **positive/negative edges are considered** *across ALL users at once.*
- However, the recall metric is inherently **personalized (defined for each user)**.
	- The non-personalized binary loss is overly-stringent for the personalized recall metric.

Desirable Surrogate Loss

- ¡ **Lesson learned**: Surrogate loss function should be defined in a **personalized** manner.
	- **For each user**, we want the scores of positive items to be higher than those of the negative items
	- We do *not* care about the score ordering across users.
- ¡ **Bayesian Personalized Ranking (BPR)** loss achieves this!

Observed interaction

Unobserved interaction

Loss Function: BPR Loss (1)

- ¡ **Bayesian Personalized Ranking (BPR) loss** is a personalized surrogate loss that aligns better with the recall@K metric.
- For each user u^* $\in U$, define the **rooted positive/negative edges** as **User**
	- **Positive edges rooted at** u^*
		- $E(u^*) \equiv \{(u^*, v) | (u^*, v) \in E\}$
	- Regative edges rooted at u^*
		- $E_{\text{neg}}(u^*) \equiv \{(u^*, v) | (u^*, v) \in E_{\text{neg}}\}$

Note: The term "Bayesian" is not essential to the loss definition. The original paper [Rendle et al. 2009] considers the Bayesian prior over parameters (essentially acts as a parameter regularization), which we omit here.

 u^*

Item

Loss Function: BPR Loss (2)

- **Training objective: For each user** u^* , we want the scores of rooted positive edges $\mathbf{E}(u^*)$ to be higher than those of rooted negative edges $E_{\text{neg}}(u^*).$
	- § **Aligns with the personalized nature of the recall metric.**
- BPR Loss for user u^* :

Encouraged to be positive for each user

=positive edge score is higher than negative edge score

$$
Loss(u^*) = \frac{1}{|E(u^*)| \cdot |E_{neg}(u^*)|} \sum_{(u^*, v_{pos}) \in E(u^*)} \sum_{(u^*, v_{neg}) \in E_{neg}(u^*)} -log\left(\sigma\left(f_{\theta}(u^*, v_{pos}) - f_{\theta}(u^*, v_{neg})\right)\right)
$$

Can be approximated using a mini-batch

■ Final BPR Loss:
$$
\frac{1}{|U|} \sum_{u^* \in U} Loss(u^*)
$$

Loss Function: BPR Loss (3)

- ¡ **Mini-batch training for the BPR loss:**
	- **In each mini-batch, we sample a** subset of users $\boldsymbol{U}_{\text{mini}} \subset \boldsymbol{U}$.
		- For each user $u^* \in U_{\text{mini}}$, we sample one positive item v_{pos} and a set of sampled negative items $V_{\text{neg}} = \{v_{\text{neg}}\}.$

■ The mini-batch loss is computed as

$$
\frac{1}{|\boldsymbol{U}_{\text{mini}}|} \sum_{u^* \in \boldsymbol{U}_{\text{mini}}}\frac{1}{|\boldsymbol{V}_{\text{neg}}|} \sum_{\boldsymbol{v}_{\text{neg}} \in \boldsymbol{V}_{\text{neg}}}\text{ -log}\bigg(\sigma\big(f_{\theta}\big(u^*, \boldsymbol{v}_{\text{pos}}\big) - f_{\theta}\big(u^*, \boldsymbol{v}_{\text{neg}}\big)\big)\bigg)
$$

Average over users in the mini-batch

Summary So Far

¡ **We have introduced**

- Recall@ K as a metric for personalized recommendation
- Embedding-based models
	- Three kinds of parameters to learn
		- **user encoder** to generate user embeddings
		- **item encoder** to generate item embeddings
		- **Score function** to predict the user-item interaction likelihood.
- Surrogate loss functions to achieve the high recall metric.
- Embedding-based models have achieved SoTA in recommender systems.
	- § **Why do they work so well?**

Why Embedding Models Work?

¡ **Underlying idea: Collaborative filtering**

- § Recommend items for a user by **collecting preferences of many other similar users.**
- § **Similar users tend to prefer similar items.**
- **E** Key question: How to **capture similarity between users/items?**

Why Embedding Models Work?

- Embedding-based models can capture similarity of users/items!
	- § **Low-dimensional embeddings** *cannot* **simply memorize all user-item interaction data.**
	- Embeddings are forced to **capture similarity between users/items to fit the data.**
	- This allows the models to make effective prediction on *unseen* user-item interactions.

This Lecture: GNNs for Recsys

- \blacksquare In this lecture, we teach two representative **GNN approaches for recommender systems.**
- ¡ **(1) Neural Graph Collab. Filtering (NGCF)** [Wang et al. 2019]
- **(2) LightGCN** [He et al. 2020]
	- Improve the conventional collaborative filtering models (i.e., shallow encoders) by explicitly modeling graph structure using GNNs.
	- Assumes no user/item features.
- **PinSAGE** [Ying et al. 2018]
	- Use GNNs to generate high-quality embeddings by simultaneously capturing rich node attributes (e.g., images) and the graph structure.

Stanford CS224W: Neural Graph Collaborative Filtering

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Conventional Collaborative Filtering

- Conventional collaborative filtering model is based on **shallow encoders**:
	- No user/item features.
	- Use shallow encoders for users and items:
		- For every $u \in U$ and $v \in V$, we prepare shallow learnable embeddings $u, v \in \mathbb{R}^D$.
	- Score function for user u and item ν is $f(\boldsymbol{u},\boldsymbol{\nu})\equiv \boldsymbol{z_u}^T\boldsymbol{z_v}.$ Learnable shallow user/item embeddings

Limitations of Shallow Encoders

- ¡ The model itself does *not explicitly* capture graph structure
	- The graph structure is **only implicitly** captured in the training objective.
- ¡ Only the **first-order graph structure** (i.e., edges) is captured in the training objective.
	- **High-order graph structure** (e.g., K-hop paths between two nodes) is *not* **explicitly captured.**
- We want a model that...
	- explicitly captures graph structure (beyond implicitly through the training objective)
	- captures **high-order graph structure** (beyond the first-order edge connectivity structure)
- ¡ **GNNs are a natural approach to achieve both!**
	- § **Neural Graph Collaborative Filtering** (NGCF) [Wang et al. 2019]
	- **LightGCN** [He et al. 2020]
		- **A simplified and improved version of NGCF**

NGCF: Overview

- ¡ **Neural Graph Collaborative Filtering (NGCF)** *explicitly* incorporates high-order graph structure when generating user/item embeddings.
- **Key idea**: Use a GNN to generate graph-aware user/item embeddings.

NGCF Framework

- **Given**: User-item bipartite graph.
- ¡ **NGCF framework:**
	- § Prepare shallow learnable embedding for each node.
	- Use multi-layer GNNs to propagate embeddings along the bipartite graph.
		- High-order graph structure is captured.
	- Final embeddings are *explicitly* graphaware!
- ¡ **Two kinds of learnable params are jointly learned:**
	- § Shallow user/item embeddings
	- § GNN's parameters

Shallow user/item embeddings (learnable)
Initial Node Embeddings

- ¡ Set the shallow learnable embeddings as the initial node features:
	- For every user $u \in U$, set $\boldsymbol{h}_{u}^{\left(0\right)}$ as the user's shallow embedding.
	- For every item $v \in V$, set $\boldsymbol{h}_{\nu}^{\left(0\right)}$ as the item's shallow embedding.

Learnable shallow user/item embeddings

Neighbor Aggregation

Exteratively update node embeddings using neighboring embeddings. $\boldsymbol{h}_v^{(k+1)} = \text{COMBINE}\left(\boldsymbol{h}_v^{(k)}, \text{AGGR}\left(\left\{\boldsymbol{h}_u^{(k)}\right\}\right)\right)$ $u \in N(v)$ $h_u^{(k+1)} = \text{COMBINE} \left(h_u^{(k)}, \text{AGGR} \left(\left\{ h_v^{(k)} \right\} \right) \right)$ $v \in N(u)$

High-order graph structure is captured through iterative neighbor aggregation.

Different architecture choices are possible for AGGR and COMBINE.

- $AGGR(\cdot)$ can be MEAN (\cdot)
- COMBINE (x, y) can be $ReLU(Linear(Concat(x, y)))$

Final Embeddings and Score Function

- **After K rounds of neighbor** aggregation, we get the **final** user/item embeddings $\bm{h}_{\mathcal{u}}^{(l)}$ (K) and $\bm{h}_{\bm{\nu}}^{U}$ (K) .
- **For all** $u \in U$ **,** $v \in V$ **, we set**

$$
u \leftarrow h_u^{(K)}, v \leftarrow h_v^{(K)}.
$$

Example 1 Score function is the inner product

 $score(u, v) = u^T v$

Final user/item embeddings (graph-aware)

- Conventional collaborative filtering uses shallow user/item embeddings.
	- § The embeddings do *not explicitly* **model graph structure**.
	- **The training objective does not model high-order graph structure.**
- ¡ **NGCF uses a GNN to propagate the shallow embeddings.**
	- **The embeddings are explicitly aware of highorder graph structure.**

Stanford CS224W: LightGCN

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LightGCN: Motivation (1)

- **Recall: NGCF jointly learns two kinds of** parameters:
	- § Shallow user/item embeddings
	- GNN's parameters
- **EXPERIGA**: Shallow learnable embeddings are already quite expressive.
	- They are learned for every (user/item) node.
	- Most of the parameter counts are in shallow embeddings when N (#nodes) $\gg D$ (embedding dimensionality)
		- Shallow embeddings: $O(ND)$.
		- GNN: $O(D^2)$.
	- The GNN parameters may not be so essential for performance.

LightGCN: Motivation (2)

- Can we simplify the GNN used in NGCF (e.g., remove its learnable parameters)?
	- § **Answer**: Yes!
	- § **Bonus**: Simplification improves the recommendation performance!
- ¡ **Overview of the idea:**
	- § Adjacency matrix for a bipartite graph
	- § Matrix formulation of GCN
	- § Simplification of GCN by removing non-linearity
		- Related: SGC for scalable GNN [Wu et al. 2019]

Adjacency and Embedding Matrices

- ¡ **Adjacency matrix** of a (undirected) bipartite graph.
- ¡ **Shallow embedding matrix**.

Matrix Formulation of GCN

¡ **Define: The diffusion matrix**

- **Let D** be the degree matrix of \boldsymbol{A} .
- **Define the normalized adjacency** matrix \widetilde{A} as

 $\widetilde{A} \equiv D^{-1/2}AD^{-1/2}$

Note: Different from the original GCN, selfconnection is omitted here.

- **Let** $E^{(k)}$ **be the embedding matrix** at k -th layer.
- **Each layer of GCN's aggregation** can be written in a matrix form: $E^{(k+1)} = \text{ReLU}(\widetilde{A}E^{(k)}|W^{(k)})$

Each row stores node embedding

Neighbor aggregation Learnable linear transformation

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Simplifying GCN (1)

¡ **Simplify GCN by removing ReLU non-linearity:** $\boldsymbol{E}^{(k+1)} = \widetilde{\boldsymbol{A}} \boldsymbol{E}^{(k)} \boldsymbol{W}^{(k)} \quad \text{Original idea from} \ \ \text{SGC (Wu et al. 201)}$ **• The final node embedding matrix is given as** $E^{(K)} = \widetilde{A} E^{(K-1)} W^{(K-1)}$ = $\widetilde{A}(\widetilde{A}E^{(K-2)}|W^{(K-2)})W^{(K-1)}$ $= \widetilde{A}(\widetilde{A}(\cdots(\widetilde{A}_{\mathbf{E}}^{(0)}W^{(0)})\cdots)W^{(K-2)})W^{(K-1)}$ $= \widetilde{A}^K \, \widetilde{E} \, (W^{(0)} \cdots W^{(K-1)})$ Set E as input embedding $E^{(0)}$ **SGC [Wu et al. 2019]**

Simplifying GCN (2)

• Removing ReLU significantly simplifies GCN! $E^{(K)} = \widetilde{A}^K E$ $W \equiv W^{(0)} \cdots W^{(K-1)}$ **Diffusing node embeddings**

along the graph

• Algorithm: Apply $E \leftarrow \tilde{A} E$ for K times.

- Each matrix multiplication diffuses the current embeddings to their one-hop neighbors.
- **Note:** \widetilde{A}^K is dense and never gets materialized. Instead, the above iterative matrix-vector product is used to compute $\widetilde{A}^K E$

Multi-Scale Diffusion

- ¡ We can consider **multi-scale diffusion** $\alpha_0 E^{(0)} + \alpha_1 E^{(1)} + \alpha_2 E^{(2)} + \cdots + \alpha_k E^{(K)}$
	- The above includes embeddings diffused at multiple hop scales.
	- $\alpha_0 E^{(0)} = \alpha_0 \widetilde{A}^0 E^{(0)}$ acts as a self-connection (that is omitted in the definition \widetilde{A})
- **The coefficients,** $\alpha_0, ..., \alpha_K$ **, are hyper-parameters.** ■ For simplicity, LightGCN uses the uniform coefficient, i.e., $\alpha_k =$ 1 $K+1$ for $k = 0, ..., K$.

LightGCN: Model Overview (1)

¡ **Given**:

- § **Adjacency matrix A**
- § **Initial learnable embedding matrix**

LightGCN: Model Overview (2)

Iteratively diffuse embedding matrix E using \vec{A}

LightGCN: Model Overview (3)

■ Average the embedding matrices at different scales.

LightGCN: Model Overview (4)

¡ **Score function**:

• Use user/item vectors from E_{final} **to score user**item interaction

LightGCN: Intuition

¡ **Question**: **Why does the simple diffusion propagation work well?**

- **EXTER:** The diffusion directly encourages the embeddings of similar users/items to be similar.
	- Similar users share many common neighbors (items) and are expected to have similar future preferences (interact with similar items).

LightGCN and GCN

- The embedding propagation of LightGCN is closely related to GCN
- **Recall:** GCN (neighbor aggregation part)

$$
\boldsymbol{h}_{v}^{(k+1)} = \sum_{u \in N(v)} \frac{1}{\sqrt{d_u} \sqrt{d_v}} \cdot \boldsymbol{h}_{u}^{(k)}
$$

- Self-loop is added in the neighborhood definition.
- LightGCN uses the same equation except that
	- Self-loop is *not* added in the neighborhood definition.
	- Final embedding takes the average of embeddings from all the layers: $\bm{h}_v =$? $\frac{1}{K+1}\sum_{k=0}^K h_\nu^{(k)}$.

LightGCN and MF: Comparison

- Both LightGCN and shallow encoders **learn a unique embedding for each user/item.**
- The difference is that LightGCN uses the *diffused* user/item embeddings for scoring.
- LightGCN performs better than shallow encoders but are also more computationally expensive due to the additional diffusion step.
	- The final embedding of a user/item is obtained by aggregating embeddings of its multi-hop neighboring nodes.

LightGCN: Summary

- ¡ LightGCN simplifies NGCF by **removing the learnable parameters of GNNs.**
- ¡ **Learnable parameters are all in the shallow input node embeddings.**
	- Diffusion propagation only involves matrix-vector multiplication.
	- The simplification leads to better empirical performance than NGCF.

Stanford CS224W: PinSAGE

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Motivation

• P2P recommendation

PinSAGE: Pin Embedding

- \Box Unifies visual, textual, and graph information.
- \Box The largest industry deployment of a Graph Convolutional Networks.
- [Huge Adoption across Pi](https://arxiv.org/pdf/1806.01973.pdf)nterest
- \Box Works for fresh content and is available in a few seconds after pin creation

>

PinSage graph convolutional network:

- **Goal: Generate embeddings for nodes in a large-scale** Pinterest granh containing hillions of ohiects Pinterest graph containing billions of objects
- **Key Idea:** Borrow information from nearby nodes
- of elements of a given type, and the max aggregator is defined to a gregator in the multiset to and the multiset to a gregator is a gregator in the multiset to a gregator is defined to a gregator in the multiset to a greg simple set). ■ E.g., bed rail Pin might look like a garden fence, but gates and beds are rarely adjacent in the graph

vs.

>

- **Pin embeddings are essential to various tasks like** recommendation of Pins, classification, ranking structures/multisets.
	- § Services like "Related Pins", "Search", "Shopping", "Ads"

Harnessing Pins and Boards

PinSAGE: Graph Neural Network

- Graph has tens of billions of nodes and edges
- **Further resolves embeddings across the** Pinterest graph

PinSAGE: Methods for Scaling-Up

- **In addition to the GNN model, the PinSAGE** introduces several methods to scale the GNN to a billion-scale recommender system (e.g., Pinterest).
	- Shared negative samples across users in a mini-batch
	- Hard negative samples
	- Curriculum learning
	- Mini-batch training of GNNs on a large-graph (to be covered in the future lecture)

PinSAGE Model

Task: Recommend related pins to users

Learn node embeddings z_i such that

 $d(z_{\text{check2}}, z_{\text{check2}}) < d(z_{\text{check1}}, z_{\text{sweater}})$

Training Data

• 1+B repin pairs:

- From Related Pins surface
- Capture semantic relatedness
- Goal: Embed such pairs to be "neighbors"

Example positive training pairs (Q,X) :

Shared Negative Samples (1)

- **Recall:** In BPR loss, for each user $u^* \in$ $\boldsymbol{U}_{\text{mini}}$, we sample one positive item v_{pos} and a set of sampled negative items $V_{\text{neg}} = \{v_{\text{neg}}\}.$
- **Using more negative samples per user** improves the recommendation performance, but is also expensive.
	- We need to generate $|U_{\text{mini}}| \cdot |V_{\text{neg}}|$ embeddings for negative nodes.
	- We need to apply $|U_{\text{mini}}| \cdot |V_{\text{neg}}|$ GNN computational graphs (see right), which is expensive.

Shared Negative Samples (2)

- **Key idea**: We can share the same set of negative samples $\boldsymbol{V}_{\text{neg}} = \{\nu_{\text{neg}}\}$ across all users $\boldsymbol{U}_{\text{mini}}$ in the mini-batch.
- **This way, we only need to generate** $|V_{\text{neg}}|$ **embeddings** for negative nodes.
	- **This saves the node embedding generation** computation **by a factor of** $|U_{\text{mini}}|!$
	- Empirically, the performance stays similar to the non-shared negative sampling scheme.

Hard Negatives (1)

- **Example 12 Challenge:** Industrial recsys needs to make **extremely fine-grained predictions**.
	- #Total items: Up to billions.
	- § #Items to recommend for each user: 10 to 100.
- **Issue**: The shared negative items are randomly sampled from all items
	- Most of them are "easy negatives", i.e., a model does not need to be fine-grained to distinguish them from positive items.
- ¡ We need a way to sample "**hard negatives**" to force the model to be fine-grained!

PinSAGE: Curriculum Learning

If Idea: use harder and harder negative samples **• Include more and more hard negative** samples for each epoch

Curriculum Learning

- ¡ **Key insight**: It is effective **to make the negative samples** *gradually harder* **in the process of training**.
- At *n*-th epoch, we add $n-1$ hard negative items.
	- § #(Hard negatives) gradually increases in the process of training.
- The model will gradually learn to make finergrained predictions.

Hard Negatives (2)

- ¡ **For each user node**, the **hard negatives** are item nodes that are close (but not connected) to the user node in the graph.
- **Hard negatives for user** $u \in U$ **are obtained as** follows:
	- Compute random walks from user u .
		- Run random walk with restart from u , obtain visit counts for other items/nodes.
	- Sort items in the descending order of their visit count.
	- § Randomly sample items that are ranked high but not too high, e.g., $2000^{th} - 5000^{th}$.
		- Item nodes that are close but not too close (connected) to the user node.
- The hard negatives for each user are used in addition to the shared negatives.

PinSAGE: Negative Sampling

(q, p) positive pairs are given but various methods to sample negatives to form (q, p)

- Distance Weighted Sampling (Wu et al., 2
	- Sample negatives so that query-negative distance distribution is approx uniform U[0.5, 1.4]

Fine-Grained Object Similarity

Visual only

Compare against Prod

PinSAGE: Summary

- ¡ **PinSAGE uses GNNs** to generate high-quality user/item embeddings that **capture both the rich node attributes and graph structure**.
- The PinSAGE model is effectively trained using sophisticated **negative sampling strategies**.
- ¡ PinSAGE is **successfully deployed at Pinterest**, a billion-scale image content recommendation service.
	- § **Uncovered in this lecture**: How to scale up GNNs to large-scale graphs. Will be covered in a later lecture.