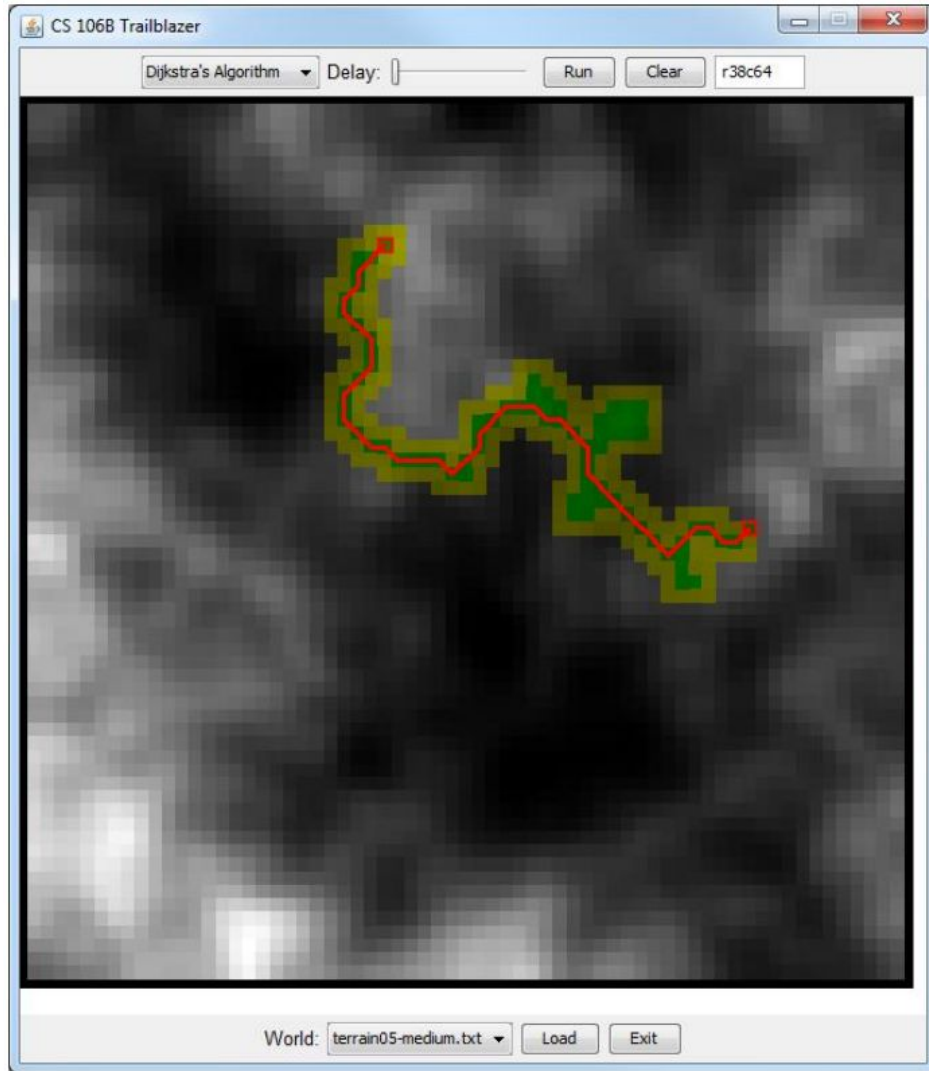


Trailblazer YEAH Hours

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What do you have to do?

- `Vector depthFirstSearch(BasicGraph& graph, Vertex* start, Vertex* end)`
- `Vector breadthFirstSearch(BasicGraph& graph, Vertex* start, Vertex* end)`
- `Vector dijkstrasAlgorithm(BasicGraph& graph, Vertex* start, Vertex* end)`
- `Vector aStar(BasicGraph& graph, Vertex* start, Vertex* end)`
- `Set kruskal(BasicGraph& graph)`

All your code should live in `trailblazer.cpp`, don't modify any other files!

Searching

You'll be given:

- Start Vertex
- End Vertex
- BasicGraph

Your job is to find a path from Start Vertex to End Vertex.

What does the Vertex look like?

<code>string name</code>	vertex's name, such as "r34c25" or "vertex17"
<code>Set<Edge*> edges</code>	edges outbound from this vertex
<code>double cost</code>	cost to reach this vertex (initially 0)
<code>bool visited</code>	whether this vertex has been visited yet (initially false)
<code>Vertex* previous</code>	pointer to a vertex that comes before this one; initially NULL
<code>void setColor(Color c)</code>	sets this vertex to be drawn in the given color in the GUI, one of WHITE, GRAY, YELLOW, or GREEN
<code>Color getColor()</code>	returns color you set previously using setColor; initially UNCOLORED
<code>void resetData()</code>	sets cost, visited, previous, and color back to their initial values
<code>string toString()</code>	returns a printable string representation of the vertex for debugging

What does the Edge look like?

Edge member	Description
Vertex* start	the starting vertex of this edge
Vertex* finish	the ending vertex of this edge (i.e., finish is a neighbor of start)
double cost	cost to traverse this edge

Section Seven!

The first two pages are just HUGE reference sheets! You should go through it before you start this assignment, it will save you a lot of pain!

Depth-first search (DFS) pseudo-code:

```
function dfs(v1, v2):  
    dfs(v1, v2, { }).
```

```
function dfs(v1, v2, path):  
    path += v1.  
    mark v1 as visited.  
    if v1 is v2:  
        a path is found!
```

```
    for each unvisited neighbor n of v1:  
        if dfs(n, v2, path) finds a path:  
            a path is found!
```

```
    path -= v1.    // path is not found.
```


Breadth-first search (BFS) pseudo-code:

```
function bfs(v1, v2):  
    queue := {v1}.  
    mark v1 as visited.  
  
    while queue is not empty:  
        v := queue.dequeue().  
        if v is v2:  
            a path is found!  
  
        for each unvisited neighbor n of v:  
            mark n as visited.  
            queue.enqueue(n).  
  
    // path is not found.
```

Dijkstra's algorithm pseudo-code:

```
function dijkstra(v1, v2):  
  for each vertex v:  
    v's cost := infinity.  
    v's previous := none.  
  v1's cost := 0.  
  pqueue := {v1, at priority 0}.  
  
  while pqueue is not empty:  
    v := pqueue.dequeue().  
    mark v as visited.  
    for each unvisited neighbor n of v:  
      cost := v's cost +  
              weight of edge (v, n).  
      if cost < n's cost:  
        n's cost := cost.  
        n's previous := v.  
        enqueue/update n in pqueue.  
  reconstruct path back from v2 to v1.
```

A* algorithm pseudo-code:

```
function astar(v1, v2):  
  for each vertex v:  
    v's cost := infinity.  
    v's previous := none.  
  v1's cost := 0.  
  pqueue := {v1, at priority  $H(v1, v2)$ }.  
  
  while pqueue is not empty:  
    v := pqueue.dequeue().  
    mark v as visited.  
    for each unvisited neighbor n of v:  
      cost := v's cost +  
              weight of edge (v, n).  
      if cost < n's cost:  
        n's cost := cost.  
        n's previous := v.  
        enqueue n at priority (cost +  $H(n, v2)$ ).  
  reconstruct path back from v2 to v1.
```

The pseudocode for Kruskal's is as follows:

kruskal(graph):

1. Place each vertex into its own "cluster" (group of reachable vertices).
2. Put all edges into a priority queue, using weights as priorities.
3. While there are two or more separate clusters remaining:
 - Dequeue an edge e from the priority queue.
 - If the start and finish vertices of e are not in the same cluster:
 - Merge the clusters containing the start and finish vertices of e .
 - Add e to your spanning tree.
 - Else:
 - Do not add e to your spanning tree.
4. Once the while loop terminates, your spanning tree is complete.